

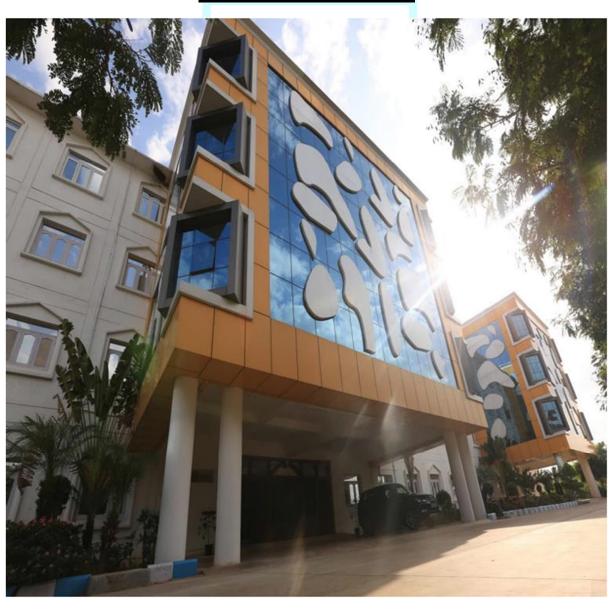




(An Autonomous Institution)
Self-Belief | Self Discipline | Self Respect

Kunnam, Sunguvarchatram, Sriperumbudur-631604

# DEPARTMENT OF MECHANICAL ENGINEERING <u>AUTONOMOUS SYLLABUS</u> <u>REGULATION 2024</u>









(An Autonomous Institution)
Self-Belief | Self Discipline | Self Respect

Kunnam, Sunguvarchatram, Sriperumbudur-631604

## DEPARTMENT OF MECHANICAL ENGINEERING AUTONOMOUS CURRICULUM & SYLLABUS R2024 CHOICE BASED CREDIT SYSTEM









(An Autonomous Institution)
Self-Belief | Self Discipline | Self Respect

Kunnam, Sunguvarchatram, Sriperumbudur-631604

#### **VISION AND MISSION OF THE INSTITUTION**

#### **VISION**

Jeppiaar Institute of Technology aspires to provide technical education in futuristic technologies with the perspective of innovative, industrial, and social applications for the betterment of humanity.

#### **MISSION**

- To produce competent and disciplined high-quality professionals with the practical skills necessary to excel as innovative professionals and entrepreneurs for the benefit of society.
- ❖ To improve the quality of education through excellence in teaching and learning, research, leadership, and by promoting the principles of scientific analysis, and creative thinking.
- ❖ To provide excellent infrastructure, serene, and stimulating environment that is most conducive to learning.
- ❖ To strive for productive partnership between the Industry and the Institute for research and development in the emerging fields and creating opportunities for employability.
- ❖ To serve the global community by instilling ethics, values, and life skills among the students needed to enrich their lives.







(An Autonomous Institution)
Self-Belief | Self Discipline | Self Respect

Kunnam, Sunguvarchatram, Sriperumbudur-631604

#### **VISION AND MISSION OF THE DEPARTMENT**

#### **VISION**

To enhance advanced technical education in the field of Mechanical engineering with the view of transformation in societal and industrialized requirements offering a platform for excellence towards mankind.

#### **MISSION**

- ❖ M1: To develop quality education with the global need.
- ❖ M2: To provide state of art facilities to faculty members and students to apply their innovative thoughts towards communal development.
- ❖ M3: To facilitate team work culture and promote student community to adapt industrial setup.
- ❖ M4: To develop the research fervour among the students and encourage them to shape inventive ideas.
- ❖ M5: To serve the global community by ethical values and core skills.

#### PROGRAMME EDUCATIONAL OBJECTIVES

- **PEO1:** Have a successful career in Mechanical Engineering and allied industries.
- ❖ PEO2: Have expertise in the areas of Design, Thermal, Materials, Manufacturing and Management.
- ❖ PEO3: Contribute towards technological development through academic research and industrial practices.
- ❖ **PEO4:** Practice their profession with good communication, leadership, ethics and social responsibility.
- **PEO5:** Graduates will adapt to evolving technologies through life-long learning.

#### **OUTCOMES**

#### **Engineering Graduates will be able to:**

- 1. **Engineering knowledge:** (K3) Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.
- 2. **Problem analysis:** (K4) Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
- 3. **Design/development of solutions:** (K4) Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.
- 4. Conduct investigations of complex problems: (K5) Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.
- 5. **Modern tool usage:** (K3, K5, K6) Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modelling to complex engineering activities with an understanding of the limitations.
- 6. **The engineer and society:** (A3) Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.
- 7. **Environment and sustainability:** (A2) Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.

- 8. **Ethics:** (A3) Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.
- 9. **Individual and team work:** (A3) Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.
- 10. **Communication:** (A3) Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.
- 11. **Project management and finance:** (A3) Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.
- 12. **Life-long learning:** (A2) Recognize the need for and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.

#### PROGRAM SPECIFIC OUTCOMES

- ❖ PSO 1: Apply the fundamentals of mathematics, Science and Engineering acquaintance to solve real time problems with scientific principles under mechanical engineering profession.
- ❖ PSO 2: Develop the ability to synthesize data for application in modeling and analysis software's to enhance the capabilities in simulation and demonstrate leadership qualities in activities related to sustainable development of society.
- ❖ **PSO 3:** Understand the impact of Professional Engineering solutions in societal and environmental context, commit to professional ethics and communicate effectively.







(An Autonomous Institution)
Self-Belief | Self Discipline | Self Respect

Kunnam, Sunguvarchatram, Sriperumbudur-631604

### DEPARTMENT OF MECHANICAL ENGINEERING AUTONOMOUS CURRICULUM R2024 (CBCS)

SEM	ESTER – I									
S.No	Course	Course Title	Category	Pe	rio	ds	Crodite	CIE	SEE	TOTAL
5.110	Code	Course Tide	Category	L	T	P	Credits	CIE	SILL	TOTAL
1	AIP001	Induction Program	TECHNOLO	Y	-	-	-	ı	-	-
THE	ORY									
2	AMA101	Matrices and Calculus	BS	3	1	0	4	40	60	100
3	AEC103	Basic Electrical and Electronics Engineering	ES	3	0	0	3	40	60	100
4	AME101	Engineering Graphics	PC	3	0	0	3	40	60	100
5	ACS102	Python Programming	ES	3	0	0	3	40	60	100
6	AMC101	Employment Enhancement Skills	MC	2	0	0	0	-	-	100
7	AMC102	Professional Ethics and Human Values	MC	2	0	0	0	-	-	100
PRA	CTICALS									
8	AEC302	Basic Electrical and Electronics Engineering Laboratory	ES	0	0	4	2	60	40	100
9	ACS301	Python Programming Laboratory	ES	0	0	4	2	60	40	100
10	AHS301	Communication Skills and Technical Writing	HS	0	0	2	1	60	40	100
11	AEEC301	Mini Project/Professional practices	EEC	0	0	2	1	60	40	100
			Total	16	1	10	19			

SEM	ESTER – II									
S.No	Course	Course Title	Catagory	Pe	rio	ds	Cuadita	CIE	CEE	TOTAL
2.110	Code	Course Title	Category	L	T	P	Credits	CIE	SEE	IOIAL
THE	ORY									•
1	AMA104	Transforms and Partial Differential Equations	BS	3	1	0	4	40	60	100
2	APH102	Engineering Materials and Metallurgy	BS	3	0	0	3	40	60	100
3	AAI101	Introduction to Data Science	ES	3	0	0	3	40	60	100
4	AME102	Engineering Mechanics	PC	3	0	0	3	40	60	100
5	ACS104	Fundamentals of Cloud Computing	ES	3	0	0	3	40	60	100
6	AHS101	Language Enhancement	HS	1	0	0	1	40	60	100
7	AMC103	Indian Constitution	MC	2	0	0	0	-	-	100
PRA	CTICALS									
8	AME301	Basic Civil & Mechanical Laboratory	ES	0	0	4	2	60	40	100
9	ACS302	Cloud Computing Laboratory	ES	0	0	4	2	60	40	100
10	AMC301	Yoga and Happy Living	MC	0	0	4	- 0	-	-	100
11	AEEC302	Mini Project/ Professional practices	EEC	0	0	2	1	60	40	100
		Top of	Total	18	1	8	22		_	
	ECTED II	Self D:	line S							

SEM	ESTER – II	I								
S.No	Course	Course Title	Catagony	Pe	rio	ds	Cuadita	CIE	CEE	TOTAL
S.1NO	Code	Course Title	Category	L	T	P	Credits	CIE	SEE	TOTAL
THE	ORY									
1	AME103	Engineering Thermodynamics	PC	3	0	0	3	60	40	100
2	AME104	Fluid Mechanics and Machinery	PC	3	0	0	3	60	40	100
3	AME105	Strength of Materials	PC	3	0	0	3	40	60	100
4	AME106	Manufacturing Processes	PC	3	0	0	3	40	60	100
5	AMC104	Environmental Engineering & Sustainability	MC	2	0	0	0	-	-	100
PRA	CTICALS									

6	AME302	Fluid Mechanics and Machinery Laboratory	PC	0	0	4	2	60	40	100
7	AHS302	Soft Skills I	HS	0	0	2	0	1	-	100
8	AEEC303	Mini Project/ Professional practices	EEC	0	0	2	1	60	40	100
			Total	14	0	7	15			

SEM	ESTER – IV	V								
S.No	Course	Course Title	Catagory	Pe	rio	ds	Credita	CIE	CEE	TOTAL
S.1NO	Code	Course Tide	Category	L	T	P	Credits	CIE	SEE	TOTAL
THE	ORY									
1	AME107	Theory of Machines	PC	3	0	0	3	40	60	100
2	AME108	Metrology and Measurements	PC	3	0	0	3	40	60	100
3	AME109	Conventional & Unconventional Machining processes	PC	3	0	0	3	40	60	100
4	AMA106	Statistics and Numerical methods	BS	3	1	0	4	40	60	100
5	AME110	Thermal Engineering	PC	3	0	0	3	40	60	100
PRA	CTICALS									
6	AME303	Machine tools laboratory	PC	0	0	4	2	60	40	100
7	AME304	Strength of Materials Laboratory	PC	0	0	4	2	60	40	100
8	AHS303	Soft Skills II	HS	0	0	2	0	-	-	100
9	AEEC304	Mini Project/ Internship /Professional practices	EEC	0	0	2	1	60	40	100
		2010	Total	15	1	10	<b>&gt;</b> 21			
		F210	. 2011	K	7		-			

SEM	ESTER – V									
S.No	Course	Course Title	Category	Periods		ds	Crodite	CIE	CFF	TOTAL
5.110	Code	Course Title	Category	L	T	P	Credits	CIE	SIMI	TOTAL
THE	ORY									
1	AME111	Machine Design	PC	3	0	0	3	40	60	100
2	AME112	Automobile Engineering	PC	3	0	0	3	40	60	100
3		Professional Elective 1 - Manufacturing	PE	3	0	0	3	40	60	100
PRA	CTICALS									

4	AME305	Computer Aided Design Laboratory	PC	0	0	4	2	60	40	100
5	AME306	Metrology & Dynamics Laboratory	PC	0	0	4	2	60	40	100
6	AEEC305	Mini Project/ Professional practices	EEC	0	0	2	1	60	40	100
			Total	9	0	8	14			

SEM	ESTER – V	I								
S.No	Course Code	Course Title	Category	Pe L	rio T		Credits	CIE	SEE	TOTAL
THE	ORY									
1	AME113	Heat and Mass Transfer	PC	3	1	0	4	40	60	100
2	AME114	Finite Element analysis	PC	3	0	0	3	40	60	100
3		Open Elective 1	OE	3	0	0	3	40	60	100
PRA	CTICALS									
4	AME307	Computer Aided Manufacturing Laboratory	PC	0	0	4	2	60	40	100
5	AME308	Thermal Engineering Laboratory	PC	0	0	4	2	60	40	100
6	AEEC306	Mini Project / Internship /Professional Practices	EEC	0	0	2	1	60	40	100
		16 Miles	Total	9	1	8	15			

SEM	ESTER – V	(I								
S.No	Course	Course Title	Category	Pe			Credits	CIE	SEE	TOTAL
	Code	Course Title	Cutegory	L	T	P	Creares			
THE	ORY									
1	AME115	Robotics & Automation	PC	3	0	0	3	40	60	100
2		Professional Elective 2 – Design	PE	3	0	0	3	40	60	100
3		Professional Elective 3 – Thermal & Energy	PE	3	0	0	3	40	60	100
4		Open elective 2	OE	3	0	0	3	40	60	100
PRA	CTICALS									
5	AME309	Automation Laboratory	PC	0	0	4	2	60	40	100
6	AME310	Simulation and Analysis laboratory	PC	0	0	4	2	60	40	100

7	AEEC307	Internship /Professional Practices	EEC	0	0	2	1	60	40	100
			Total	12	0	8	17			

SEM	ESTER – V	Ш								
S.No	Course	Course Title	Category	Po	eri	ods	Credite	CIE	CEE	TOTAL
5.110	Code	Course Title	Category	L	T	P	Credits	CIE	SEE	TOTAL
THE	ORY									
1		Professional Elective 4 – Materials	PE	3	0	0	3	40	60	100
2		Open Elective 3	OE	3	0	0	3	40	60	100
PRA	CTICALS									
3	AEEC308	Internship/Professional Practices	EEC	0	0	2	1	60	40	100
4	AME311	Project	EEC	0	0	12	10	60	40	100
			Total	6	0	14	17			

		PROFESSIONAL ELECTI	VE 1 (MA	NU	J <b>F</b> A	\C'	TURING	<del>;</del> )		
S.No	Course	Course Title	Category		rio	ds	Credits	CIE	SEE	TOTAL
212 (0	Code	C 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	cutogozy	L	T	P	010010			10111
THE	ORY									
1	AME501	Lean Manufacturing	PE	3	0	0	3	40	60	100
2	AME502	Process Planning & Cost Estimation	PE	3	0	0	3	40	60	100
3	AME503	Computer Integrated Manufacturing Systems	PE	3	0	0	3	40	60	100
4	AME504	Sustainable Manufacturing	PE	3	0	0	3	40	60	100
5	AME505	Precision Manufacturing	2 PE	3	0	0	3	40	60	100

	PROFESSIONAL ELECTIVE 2 (DESIGN)									
S.No	Course	Course Title	Cotogory	Periods		ds	Credits	CIE	SEE	TOTAL
5.110	Code	Course True	Category	L	L T P		Credits	CIE	SEE	TOTAL
THE	ORY									
1	AME506	Ergonomics & Human Factors Engineering	PE	3	0	0	3	40	60	100
2	AME507	Computer Aided Design & Manufacturing	PE	3	0	0	3	40	60	100

3	AME508	Product Design and Development	PE	3	0	0	3	40	60	100
4	AME509	Design of Jigs and Fixtures	PE	3	0	0	3	40	60	100
5	AME510	Design for manufacturing and assembly	PE	3	0	0	3	40	60	100

		PROFESSIONAL ELECT	TVE 3 (TI	ΗE	RM	[A]	L & ENI	ERGY	<b>Y</b> )	
S.No	Course	Course Title	Catagony	Perio		ds	Credita	CIE	CEE	TOTAL
S.110	Code	Course Title	Category	L	T	P	Credits	CIE	SEE	IOIAL
THE	ORY									
1	AME511	Power Plant Engineering	PE	3	0	0	3	40	60	100
2	AME512	Gas Dynamics and Jet Propulsion	PE	3	0	0	3	40	60	100
3	AME513	Refrigeration & Air Conditioning	PE	3	0	0	3	40	60	100
4	AME514	Modern IC Engines	PE	3	0	0	3	40	60	100
5	AME515	Renewable Energy Systems	PE	3	0	0	3	40	60	100

									l .	
	PROFESSIONAL ELECTIVE 4 (MATERIALS)									
S.No	Course	Course Title	Catagory	Pe	Periods		Cuadita	CIE	CIDID	TOTAL
5.NO	Code	Course Title	Category	L	T P		Creans	CIE	SEE	IOIAL
THE	ORY									
1	AME516	Non-Destructive Testing & Evaluation	PE	3	0	0	3	40	60	100
2	AME517	Testing of Materials	PE	3	0	0	3	40	60	100
3	AME518	Nano Materials and applications	PE	3	0	0	3	40	60	100
4	AME519	Composites materials and mechanics	2 PE	3	0	0	3	40	60	100
5	AME520	Mechanical behaviour of materials	PE	3	0	0	3	40	60	100

	OPEN ELECTIVE									
S.No	Course	Course Title	Catagony		Periods		Cradita	CIE	CEE	TOTAL
8.110	Code	Course Title	Category	L	T	P	Credits	CIE	SEE	IOIAL
THE	ORY									
1	AME701	Drone Technologies	OE	3	0	0	3	40	60	100
2	AME702	Additive Manufacturing	OE	3	0	0	3	40	60	100

3	AME703	Electric and Hybrid Vehicle Technology	OE	3	0	0	3	40	60	100
4	AEC701	Sensors and Actuators	OE	3	0	0	3	40	60	100
5	AEC702	Applied Design Thinking	OE	3	0	0	3	40	60	100
6	AEC703	Project Report Writing	OE	3	0	0	3	40	60	100
7	ACS701	System Engineering	OE	3	0	0	3	40	60	100
8	ACS702	Green Computing	OE	3	0	0	3	40	60	100
9	ACS703	Fintech Regulation	OE	3	0	0	3	40	60	100
10	AIT701	Network Essentials	OE	3	0	0	3	40	60	100
11	AIT702	Soft Computing Methodologies	OE	3	0	0	3	40	60	100
12	AIT703	Knowledge Engineering	OE	3	0	0	3	40	60	100
13	ACB701	Business Research Methods	- OE	3	0	0	3	40	60	100
14	ACB702	Automation Testing Tools	OE	3	0	0	3	40	60	100
15	ACB703	Social Network Analysis	OE	3	0	0	3	40	60	100
16	AAI701	Drinking Water Supply and Treatment	OE	3	0	0	3	40	60	100
17	AAI702	Geographical Information System	OE	3	0	0	3	40	60	100
18	AAI703	IT in Agricultural System	OE	3	0	0	3	40	60	100
19	AMB701	Corporate Governance	OE	3	0	0	3	40	60	100
20	AMB702	Digital Marketing	OE	3	0	0	3	40	60	100
21	AMB703	Rural Marketing	OE	3	0	0	3	40	60	100
_										









(An Autonomous Institution)
Self-Belief | Self Discipline | Self Respect

Kunnam, Sunguvarchatram, Sriperumbudur-631604

## DEPARTMENT OF MECHANICAL ENGINEERING AUTONOMOUS SYLLABUS R2024 CHOICE BASED CREDIT SYSTEM



	AMA101 MATRIC	ES AN	D CALCULUS				
Duogramma &	BE & MECH	Sem.	Catagony	L	Т	P	С
Programme & Branch	DE & MECH	Sein.	Category	L	1	1	
Dianen		1	BS	3	1	0	4
The objective of the course is to  introduce the matrix techniques and to explain the nature of the matrix.  provide the necessary basic concepts of a few numerical methods and give procedures for solving numerically different kinds of problems occurring in Engineering and Technology.  familiarize the students with differential calculus.  understand techniques of calculus which are applied in the Engineering problems.  acquaint the student with mathematical tools needed in evaluating multiple integrals and their applications  Unit 1  MATRICES  Preamble  MATRICES  Page 1943							
Unit 1	- me omme me m	alizatio	of matrices vsing	outh		a1 +ma	9+3
_	and eigenvectors - Diagon eorem (without proof) - Q on		_		_		
Unit 2 SOLUTION OF LINEAR SYSTEM OF EQUATIONS 9+3 AND EIGENVALUE PROBLEMS							
=	m of equations - Gauss elirnethod - Matrix Inversion but method.		_				
Unit 3	DIFFERENTIAL CALC	CULUS					9+3
	ntinuity-Derivatives-Differ- -Logarithmic Differentiation				-		<i>'</i>
Unit 4	INTEGRAL CALCULU	JS					9+3
Trigonometric integrals Integration of irrational	integrals - Substitution ru, Trigonometric substitution functions - Improper integ	le - Teo ns, Integ grals.	1			_	tial fraction,
Unit 5	MULTIPLE INTEGRA	LS					9+3
by plane curves – Triple	nge of order of integration – e integrals – Volume of soli- ts and centres of mass, mor	ds –Cha	inge of variables in				ple integrals
							Total: 60
43rd							
	Erwin Kreyszig ," Advanced Engineering Mathematics ", John Wiley and Sons, 10th Edition, New Delhi, 2016						
	val. B.S., and Grewal. J.S ana Publishers, 9th Edition,			Engi	neer	ing a	and Science,

REFERENCES	
1	Ramana. B.V., "Higher Engineering Mathematics", McGraw Hill Education Pvt. Ltd,
	New Delhi, 2018.
2	N.P. Bali and Manish Goyal, A text book of Engineering Mathematics, Laxmi
	Publications, Reprint, 2008

COURSE OUT	COMES:	Bloom's Taxonomy
At the end of th	e course, learners will be able to	Level
CO1	Demonstrate the matrix techniques in solving the related	K4
	problems in engineering and technology.	
CO2	Apply matrix methods to solve system of linear equations	K3
CO3	Apply differential calculus tools in solving various	K3
	application problems	
CO4	Apply different methods of integration in solving	K3
	practical problems.	
CO5	Evaluate multiple integrals to conduct investigations of	K5
	complex problems	

	PO1	PO2	PO3	PO4	PO5	PO6	PO1	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	-	*-	-	~	A	-	- /	1		1	1	_
CO2	3	2	1	-	Şe	1	-^			-//	<i>\$</i> −/		1	1	-
CO3	3	2	3	-	-	9 -	G C		罗	- 8	§ -		1	1	-
CO4	3	2	3	-	-	TO C	-	&n	-	6-50	1		-	1	-
CO5	3	2	3	-	-	-	Selfe	-		30 <u>-</u>	-		1	-	-
								<i>I</i> scip	III						<u>.</u>

AEC103	AEC103 BASIC ELECTRICAL AND ELECTRONICS ENGINEERING							
	SHIP EHOLIDODUR							
Programme &	BE & MECH	Sem.	Category	L	T	P	C	
Branch	1010							
		1	ES	3	0	0	3	
Preamble	Preamble  This course provides the foundation for understanding various aspects of electrical and electronics engineering. From the basics of circuit theory to the intricacies of semiconductor devices, this subject delves into the heart of electrical and electronic systems.							
Unit 1	ELECTRICAL CIRCUI	ITS					9	

DC Circuits: Circuit Components: Conductor, Resistor, Inductor, Capacitor – Ohm's Law - Kirchhoff's Laws –Independent and Dependent Sources – Simple problems- Nodal Analysis, Mesh analysis with Independent sources only (Steady state) Introduction to AC Circuits and Parameters: Waveforms, Average value, RMS Value, Instantaneous power, real power, reactive power and apparent power, power factor – Steady state analysis of RLC circuits (Simple problems only).

Unit 2	ELECTRICAL MACHINES	9					
Construction an	d Working principle- DC Separately and Self excited Gene	erators, EMF equation, Types					
and Application	ns. Working Principle of DC motors, Torque Equation	on, Types and Applications.					
Construction, W	orking principle and Applications of Transformer, Three p	hase Alternator, Synchronous					
motor and Thre	e Phase Induction Motor						
Unit 3	ANALOG ELECTRONICS	9					
Resistor, Induct	or and Capacitor in Electronic Circuits- Semiconductor Ma	terials: Silicon &Germanium					
– PN Junction I	Piodes, Zener Diode – Characteristics Applications – Bipola	r Junction Transistor-Biasing,					
JFET, SCR, MC	OSFET, IGBT – Types, I-V Characteristics and Application	s, Rectifier and Inverters					
Unit 4	DIGITAL ELECTRONICS	9					
Review of num	ber systems, binary codes, error detection and correction	codes, Combinational logic -					
representation of	of logic functions-SOP and POS forms, K-map representati	tions - minimization using K					
maps (Simple P	roblems only).						
Unit 5	MEASUREMENTS AND INSTRUMENTATION	ON 9					
Functional elen	nents of an instrument, Standards and calibration, Operation	ing Principle, types -Moving					
Coil and Mov	ing Iron meters, Measurement of three phase power,	Energy Meter, Instrument					
Transformers-C	T and PT, DSO- Block diagram- Data acquisition.						
		Total: 45					
TEXTBOOKS							
1	Kothari DP and I.J Nagrath, "Basic Electrical and Electrical Elect	tronics Engineering", Second					
	Edition, McGraw Hill Education, 2020						
2	S.K.Bhattacharya "Basic Electrical and Electronics Engi	ineering", Pearson Education					
	Second Edition, 2011						
3	Sedha R.S., "A textbook book of Applied Electronics", S	S. Chand & Co., 2008					
4	James A .Svoboda, Richard C. Dorf, "Dorf's Introductio	n to Electric Circuits", Wiley,					
	2018.						
5	.K. Sawhney, Puneet Sawhney 'A Course in Electrical &	Electronic Measurements &					
	Instrumentation', DhanpatRai and Co, 2015.						
REFERENCE	5						
1	Kothari DP and I.J Nagrath, "Basic Electrical Engineering	ng", Fourth Edition, McGraw					
	Hill Education, 2019						
2	Thomas L. Floyd, 'Digital Fundamentals', 11th Edition,	Pearson Education, 2011					
3	Albert Malvino, David Bates, 'Electronic Principles, I	McGraw Hill Education; 1th					
	edition, 2011						
4	Mahmood Nahvi and Joseph A. Edminister, "Electric	Circuits", Schaum' Outline					
	Series, McGraw Hill.						
COURSEOUT		Bloom's Taxonomy					
	ne course, learners will be able to	Level					
CO1	Compute the electric circuit parameters for simple	K2					
	problems.	772					
CO2	Explain the working principle and applications of	K2					
	electrical machines.						

CO3	Analyze the characteristics of analog electronic devices.	K2
CO4	Explain the basic concepts of digital electronics.	K2
CO5	Explain the operating principles of measuring instruments	K2

	PO1	PO2	PO3	PO4	PO5	PO6	PO1	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	-	-	-	-	1	-	-	-	2	-	-	1
CO2	2	2	1	-	-	-	-	1	-	-	-	2	-	-	1
CO3	2	2	1	-	-		<u>-</u>	1		-	-	2	-	-	1
CO4	2	2	1	-	-	-	гn	1	n-n		-	2	-	-	1
CO5	2	2	1	-	-	-	Lť	1	<b>i</b> - i i	K	-	2	-	-	1

	AME101 ENGINEERING GRAPHICS													
Programme & Branch	BE& MECH	Sem.	Category	L	T	P	C							
		1	PC	3	0	0	3							
Preamble	and design of Engir	<ul> <li>To develop in students, graphic skills for communication of concepts, ids and design of Engineering products.</li> <li>To expose them to existing national standards related to technical</li> </ul>												
Unit 1	PLANE CURVES ANI	FREE H	AND SKETCH	ING			9							

Basic Geometrical constructions, Curves used in engineering practices: Conics – Construction of ellipse, parabola and hyperbola by eccentricity method – Construction of cycloid – construction of involutes of square and circle – Drawing of tangents and normal to the above curves. Visualization concepts and Free Hand sketching: Visualization principles –Representation of Three-Dimensional objects – Layout of views- Free hand sketching of multiple views from pictorial views of objects.

Unit 2	PROJECTION OF POINTS, LINES AND PLANE	9
	SURFACES	

Orthographic projection- principles-Principal Planes-First angle projection-projection of points. Projection of straight lines (only First angle projections) inclined to both the principal planes - Determination of true lengths and true inclinations by rotating line method and traces Projection of planes (polygonal and circular surfaces) inclined to both the principal planes by rotating object method.

Unit 3	9									
Projection of simple solids like prisms, pyramids, cylinder, cone and truncated solids when the axis is										
inclined to one of the pr	incipal planes by rotating object method and auxiliary plane	method.								

Unit 4	SECTION OF SOLIDS & DEVELOPMENT OF	9
	SURFACES	

Sectioning of above solids in simple vertical position when the cutting plane is inclined to the one of the principal planes and perpendicular to the other – obtaining true shape of section. Development of lateral surfaces of simple and sectioned solids – Prisms, pyramids cylinders and cones. Development of lateral surfaces of solids with cut-outs and holes

#### Unit 5 ISOMETRIC AND PERSPECTIVE PROJECTIONS 9

Principles of isometric projection – isometric scale –Isometric projections of simple solids and truncated solids - Prisms, pyramids, cylinders, cones- combination of two solid objects in simple vertical positions and miscellaneous problems. Perspective projection of simple solids-Prisms, pyramids, and cylinders by visual ray method.

	Total: 45
TEXTBOOKS	
1	Bhatt N.D. and Panchal V.M., "Engineering Drawing", Charotar Publishing House,
	50 <sup>th</sup> Edition, 2010
REFERENCES	I IFPHIHHK I
1	Gopalakrishna K.R., "Engineering Drawing" (Vol. I&II combined), Subhas Stores,
	Bangalore, 2001.
2	Luzzader, Warren.J. and Duff, John M., "Fundamentals of Engineering Drawing with
	an introduction to Interactive Computer Graphics for Design and Production, Eastern
	Economy Edition, Prentice Hall of India Pvt. Ltd, New Delhi, 2005.
3	Shah M.B., and Rana B.C., "Engineering Drawing", Pearson, 2nd Edition, 2009.
4	Venugopal K. and Prabhu Raja V., "Engineering Graphics", New Age International
	(P) Limited, 2008
5	Natrajan K.V., "A text book of Engineering Graphics", Dhanalakshmi Publishers,
	Chennai, 2009.
6	Basant Agarwal and Agarwal C.M., "Engineering Drawing", Tata McGraw Hill
	Publishing Company Limited, New Delhi, 2008.

COURSEOUTO	COMES: Disciplin	Bloom's Taxonomy
At the end of the	e course, learners will be able to	Level
CO1	Perform free hand sketching of basic geometrical constructions and multiple views of objects.	K3
CO2	Do orthographic projection of lines and plane surfaces.	K3
CO3	Draw projections and solids and development of surfaces.	K3
CO4	Prepare isometric and perspective sections of simple solids.	К3
CO5	Demonstrate computer aided drafting.	К3

patterns, Search and replace

	PO1	PO2	PO3	PO4	PO5	PO6	PO1	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	2		2					3		2	2	2	
CO2	3	1	2		2					3		2	2	2	
CO3	3	1	2		2					3		2	2	2	
CO4	3	1	2		2					3		2	2	2	
CO5	3	1	2		2					3		2	2	2	

				ACS	102 P	YTH	ON PI	ROG	FRAM	MING					
O	amme &	ķ	1	BE &	MEC	CH	Se	m.	C	ategory	L	T	P		$\mathbf{C}$
Br	anch					_ ]		Ц							
						L I	and the second	1	ninev	ES	3	0	0		3
									_	imic pro		U			
			To learn to solve problems using Python conditionals and loops.												
Dro	amble		To define Python functions and use function calls to solve problems.												
FIC	alliole		To use Python data structures - lists, tuples, dictionaries to represent complex data.												
				-				011							
To do input/output with files in Python.															
Unit 1 BASICS OF PYTHON PROGRAMMING 9															
Overview	of prog	gramm	ing lar	nguage	e- Pyt	hon h	istory-	Inte	ractive	mode -	- script	mode	-Tok	ens:	Literal-
Keyword-	Delimit	er-Ide	ntifier-	Data	types:	Integ	ger-Flo	ating	g-Com	plex-Bo	olean-St	ring-	Inde	ntatio	on-Input
operation-	Comme	ents		N	d l	(1) (C)		人對		.5°					
<b>U</b> 1	nit 2		CON	TRO	LSTI	RUCT	URE,	OP	ERAT	ORS AN	ND			9	
			FUNC	CTIO	NS	Sole			150						
Statement													•		
break, con		•			-						-	•			
Types, pa		_		-						7	-				
values, fur		with a							77.5			scope	, Rec		on
$\mathbf{U}_1$	nit 3						RING	SAN	ND RE	GULAI	R			9	
			EXPI	-											
List: Crea			_				•	_				-			•
Create, In	_			-			-		•				_		-
values, operations on dictionaries. Sets: Create and operations on set. Strings: Formatting, Comparison,															
Slicing, Splitting, Stripping, Negative indices, String functions. Regular expression: Matching the															

Unit 4 FILE HANDLING AND EXCEPTIONS 9

Files: Open, Read, Write, Append, Tell, Seek and Close. Errors and Exceptions: Syntax Errors, Exceptions, Handling Exceptions, Raising Exceptions, Exception Chaining, Userdefined Exceptions, Defining Clean-Up actions

Unit 5 NUMPY, PANDAS, MATPLOTLIB 9

Introduction - Basics of NumPy - N-dimensional Array in NumPy - Methods and Properties - Basics of SciPy - Broadcasting in NumPy Array Operations - Array Indexing in NumPy, Pandas - Introduction - Series - Data Frame - Matplotlib - Basics - Figures and Axes - Method subplot() - Axis container

Deries Data I I a	me - Matpiotho - Dasies - Figures and Axes - Method subplo	t() - Axis container									
		Total: 45									
<b>TEXTBOOKS</b>											
1	Ashok NamdevKamthane, Amit Ashok Kamthane "Pro	gramming and Problem									
	Solving with Python", 2 <sup>nd</sup> edition, Mc Graw Hill										
2	Dr,R,NageswaraRao, "Core Python Programming",3rd edit	ion, Deamtech Publisher									
REFERENCES											
1	Paul Dietel, Harvey Deitel, "Python for Programmers", Pea	arson									
2	Reema Thareja," Problem Solving and programming with Python, Oxford University										
	Press										
COURSEOUTC	COMES:	Bloom's Taxonomy									
At the end of the	e course, learners will be able to	Level									
CO1	Develop algorithmic solutions to simple computational	K3									
	problems.										
CO2	Develop and execute simple Python programs.	K3									
CO3	Write simple Python programs using conditionals and	K2									
	loops for solving problems.										

Decompose a Python program into functions.

Represent compound data using Python lists, tuples,

#### **CO-PO Mapping**

dictionaries etc.

CO4

CO5

POs/ COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	2	2	_	rhi		ī	1_	1	2	2	2	1
CO2	2	3	2	3	2	11:11	41	1410	2	2	3	2	3	2	1
CO3	2	3	2	1	1	31	ATD		2	2	3	2	2	3	1
CO4	2	3	2	2	3	- 4	£971 n	. <u>Z</u> U	2	2	3	2	2	3	1
CO5	2	3	1	2	2	-	-	-	-	-	7	1	3	2	2

K3

K3

A	AMC101 EMPLOYMENT ENCHANCEMENT SKILLS									
Programme & Branch	BE & MECH	Sem.	Category	L	Т	P	C			
		1	MC	2	0	0	0			
Preamble	This course is designed w a resume, face interview meetings, and make a pre	s, have p	professional work	etiqu	ette,	orga	nize events/			

		to be a better professional by imparting skills that	at a working professional is
		expected to possess.	
Unit 1		RESUME WRITING	6
Resume: Object	tive; For	mats; Meticulous & Attention to Detail; Organiz	zing Information; Highligh
skills; Mistakes	s to avoi	d; Qualification & Skill; SWOT Analysis; Assig	gnment – Draft Resume &
Corrections			
Unit 2		INTERVIEW SKILLS	6
• -	-	paration - Company, Role, Brush up Concepts, Te	
	_	ce of Grooming; Interview Questions – HR	
		ation Skills; How to start/end an interview; Group	p Discussion; Assignment -
-		about yourself", Mock Interviews.	
Unit 3		PROFESSIONAL ETIQUETTES	6
	-	Global & Local; Culture Sensitivity; Gender S	•
-		nail, Social Media; Avoid Gossip; How to be pers	• •
		ngs; Agenda; Schedule & Participants; Materials re	equired; Minutes of Meeting
Unit 4		PRESENTATION SKILLS	6
		Develop an effective slide; Know your Slides; Know	
	ime Mar	nagement; Listening to the silent audience; Qu	estion & Answer session
Feedback.			T
TT •4 =			
Unit 5		ation: Types of Communication Internal & Ev	ternal Formal & Informal
Language & Co Direction of Co	ommunic	ation; Types of Communication – Internal & Exation Flow – Downward, Upward, Lateral, Diagon	ternal, Formal & Informal
Language & Co Direction of Co	ommunic	ation; Types of Communication - Internal & Ex	ternal, Formal & Informal nal; Team Work; Emotiona
Language & Co Direction of Co Intelligence	ommunic ommunica	ation; Types of Communication - Internal & Ex	ternal, Formal & Informal nal; Team Work; Emotiona
Language & Co Direction of Co Intelligence	ommunic ommunica	ration; Types of Communication – Internal & Exation Flow – Downward, Upward, Lateral, Diagon	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 30
Language & Co Direction of Co Intelligence  TEXTBOOKS	ommunica ommunica "Soft S	ation; Types of Communication – Internal & Exation Flow – Downward, Upward, Lateral, Diagonation Flow – Bkills & Employability Skills" by Sabina Pillai&A	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 30
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2	ommunica ommunica "Soft S	Skills & Employability Skills" by Sabina Pillai&Aş	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 30  gna Fernandez
Language & Co Direction of Co Intelligence  TEXTBOOKS	"Soft S	ation; Types of Communication – Internal & Exation Flow – Downward, Upward, Lateral, Diagonation Flow – Downward, Upward, Lateral, Diagonation Flow – Bkills & Employability Skills" by Sabina Pillai&AgSkills" by Meenakshi Raman & Shalini Upadhyay bus Recruitment" by Ramanadhan Ramesh Bal	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 30  gna Fernandez
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3	"Soft S "Soft S "Camp	Skills & Employability Skills" by Sabina Pillai&Aş	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 30  gna Fernandez
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES	"Soft S "Camp Bhutao	Skills & Employability Skills" by Sabina Pillai&Ag Skills" by Meenakshi Raman &ShaliniUpadhyay bus Recruitment" by Ramanadhan Ramesh Bal da&Vijaya Lakshmi Krishnan	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 30  gna Fernandez  bu, Israel Battu, Akash F
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES 1	"Soft S "Soft S "Camp Bhutac	ation; Types of Communication – Internal & Exation Flow – Downward, Upward, Lateral, Diagonality & Employability Skills" by Sabina Pillai&Agaskills" by Meenakshi Raman & Shalini Upadhyay bus Recruitment" by Ramanadhan Ramesh Balda&Vijaya Lakshmi Krishnan	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 30  gna Fernandez  bu, Israel Battu, Akash F
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES	"Soft S "Camp Bhutao S "Perso	Skills & Employability Skills" by Sabina Pillai&Ag Skills" by Meenakshi Raman & ShaliniUpadhyay bus Recruitment" by Ramanadhan Ramesh Bal da&Vijaya Lakshmi Krishnan  onality Development & Soft Skills (Old Edition)" b	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 30  gna Fernandez  bu, Israel Battu, Akash F
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES 1 2	"Soft S "Soft S "Camp Bhutaces "Perso	Skills & Employability Skills" by Sabina Pillai&Ag Skills" by Meenakshi Raman & ShaliniUpadhyay bus Recruitment" by Ramanadhan Ramesh Bal da&Vijaya Lakshmi Krishnan bonality Development & Soft Skills (Old Edition)" b	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 30  gna Fernandez  bu, Israel Battu, Akash F  by Barun K Mitra  Employment" by Frederick F
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES 1	"Soft S "Soft S "Camp Bhutace S "Perso "Soft S Wentz "Ten S	Skills & Employability Skills" by Sabina Pillai&Ag Skills" by Meenakshi Raman & ShaliniUpadhyay bus Recruitment" by Ramanadhan Ramesh Bal da&Vijaya Lakshmi Krishnan  onality Development & Soft Skills (Old Edition)" b	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 30  gna Fernandez  bu, Israel Battu, Akash F  by Barun K Mitra  Employment" by Frederick F
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES 1 2	"Soft S "Camp Bhutao S "Perso "Soft S Wentz "Ten S Smith	Skills & Employability Skills" by Sabina Pillai&Ag Skills" by Meenakshi Raman & ShaliniUpadhyay bus Recruitment" by Ramanadhan Ramesh Bal da&Vijaya Lakshmi Krishnan  onality Development & Soft Skills (Old Edition)" b Skills Training: A Workbook to develop Skills for E Soft Skills You Need to Advance Your Career (An	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 30  gna Fernandez  bu, Israel Battu, Akash F  by Barun K Mitra  Employment" by Frederick F  dre Keys Book 9)" by Lisa
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES 1 2	"Soft S "Soft S "Camp Bhutao S "Perso "Soft S Wentz "Ten S Smith "Get S	Skills & Employability Skills" by Sabina Pillai&Ag Skills" by Meenakshi Raman & ShaliniUpadhyay bus Recruitment" by Ramanadhan Ramesh Bal da&Vijaya Lakshmi Krishnan  Skills Training: A Workbook to develop Skills for E Soft Skills You Need to Advance Your Career (An Your First Job: A Companion For Getting You	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 36  gna Fernandez  bu, Israel Battu, Akash F  by Barun K Mitra  mployment" by Frederick F  dre Keys Book 9)" by Lisa  ar First Job – A Guide to
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES 1 2	"Soft S "Soft S "Camp Bhutac S "Perso "Soft S Wentz "Ten S Smith "Get S Emplo	Skills & Employability Skills" by Sabina Pillai&Ag Skills" by Meenakshi Raman & Shalini Upadhyay bus Recruitment" by Ramanadhan Ramesh Bal da&Vijaya Lakshmi Krishnan  Onality Development & Soft Skills (Old Edition)" by Skills Training: A Workbook to develop Skills for E Soft Skills You Need to Advance Your Career (Androyability Skills & Career Planning" by AJ	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 36  gna Fernandez  bu, Israel Battu, Akash F  by Barun K Mitra  mployment" by Frederick F  dre Keys Book 9)" by Lisa  ar First Job – A Guide to
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES 1 2 3	"Soft S "Soft S "Camp Bhutace S "Perso "Soft S Wentz "Ten S Smith "Get S Emplo	Skills & Employability Skills" by Sabina Pillai&Ag Skills" by Meenakshi Raman & Shalini Upadhyay bus Recruitment" by Ramanadhan Ramesh Bal da&Vijaya Lakshmi Krishnan  Conality Development & Soft Skills (Old Edition)" b Skills Training: A Workbook to develop Skills for E Soft Skills You Need to Advance Your Career (An Your First Job: A Companion For Getting You byability Skills & Career Planning" by AJ	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 36  gna Fernandez  bu, Israel Battu, Akash Informal Mitra  mployment" by Frederick Informal Mitra  dre Keys Book 9)" by Lister First Job – A Guide to Balasubramanian & Dr
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES 1 2 3  COURSEOUT	"Soft S "Soft S "Camp Bhutao S "Perso "Soft S Wentz "Ten S Smith "Get S Emplo Sadakl	ation; Types of Communication – Internal & Exation Flow – Downward, Upward, Lateral, Diagonation Flow – Downward, Upward, Lateral, Diagonation Flow – Downward, Upward, Lateral, Diagonation Flow – Billia & Agenta & Employability Skills "by Sabina Pillai & Agenta & Skills "by Meenakshi Raman & Shalini Upadhyay bus Recruitment" by Ramanadhan Ramesh Balda & Vijaya Lakshmi Krishnan  Donality Development & Soft Skills (Old Edition)" by Skills Training: A Workbook to develop Skills for Experimental Experimental Experimental Soft Skills You Need to Advance Your Career (And Your First Job: A Companion For Getting Your Syability Skills & Career Planning" by AJ Madulla.	ternal, Formal & Informal nal; Team Work; Emotional Total: 30  gna Fernandez  bu, Israel Battu, Akash Hoy Barun K Mitra  mployment" by Frederick Hodre Keys Book 9)" by Lister First Job – A Guide to Balasubramanian & Dr  Bloom's Taxonomy
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES 1 2  3  COURSEOUT At the end of the	"Soft S "Soft S "Camp Bhutaces "Soft S Wentz "Ten S Smith "Get S Emplo Sadakl	Skills & Employability Skills" by Sabina Pillai&Ag Skills" by Meenakshi Raman & ShaliniUpadhyay bus Recruitment" by Ramanadhan Ramesh Bal da&Vijaya Lakshmi Krishnan  Conality Development & Soft Skills (Old Edition)" by Skills Training: A Workbook to develop Skills for E  Soft Skills You Need to Advance Your Career (An Your First Job: A Companion For Getting You byability Skills & Career Planning" by AJ kadulla.  : e, learners will be able to	ternal, Formal & Informal nal; Team Work; Emotiona  Total: 36  gna Fernandez  bu, Israel Battu, Akash Formal amployment by Frederick Formal and Frederick Formal and Frederick for First Job – A Guide to Balasubramanian & Dr  Bloom's Taxonomy Level
Language & Co Direction of Co Intelligence  TEXTBOOKS  1 2 3  REFERENCES 1 2 3  COURSEOUT	"Soft S "Soft S "Camp Bhutaces "Soft S Wentz "Ten S Smith "Get S Emplo Sadakl	ation; Types of Communication – Internal & Exation Flow – Downward, Upward, Lateral, Diagonation Flow – Downward, Upward, Lateral, Diagonation Flow – Downward, Upward, Lateral, Diagonation Flow – Billia & Agenta & Employability Skills "by Sabina Pillai & Agenta & Skills "by Meenakshi Raman & Shalini Upadhyay bus Recruitment" by Ramanadhan Ramesh Balda & Vijaya Lakshmi Krishnan  Donality Development & Soft Skills (Old Edition)" by Skills Training: A Workbook to develop Skills for Experimental Experimental Experimental Soft Skills You Need to Advance Your Career (And Your First Job: A Companion For Getting Your Syability Skills & Career Planning" by AJ Madulla.	ternal, Formal & Informal nal; Team Work; Emotional Total: 30  gna Fernandez  bu, Israel Battu, Akash Hoy Barun K Mitra  mployment" by Frederick Hodre Keys Book 9)" by Lister First Job – A Guide to Balasubramanian & Dr  Bloom's Taxonomy

CO3	Employ skills that will enhance employability and ensure	K3
	workplace and career success.	
CO4	Understand and apply appropriate behavior and attitude at workplace.	K5
CO5	Apply skills that will enhance their etiquettes to the standards expected in professional space.	K5

POs/ COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	-	1	-	1	-	-	-	-	-	-	2	-	-	-
CO2	-	1	-	-	-	-	-	-	1	2	2	-	-	-	-
CO3	-	-	-	-	-	2		2	2	-	2	-	-	-	-
CO4	-	-	-	1	-	- [	1	1 - [	A	2	-	-	-	-	-
CO5	-	-	-	-	-	J- L	- 1	1	2	\ -	2	2	-	-	-

AMO	C102 PROFESS	IONAL E	THICS	AND HU	MAN VAI	LUI	ES		
Programme & Branch	BE & ME	ЕСН	Sem.	Cate	gory	L	T	P	С
			1	M	(C	2	0	0	0
Preamble		erstand soc	ial respo	onsibility	of an engin	eer.			Values. professional
Unit 1	HUMAN VAL	UES	월 )	1600					2
Morals, Values and Eth  - Character	ics – Integrity –	Work Ethi	c – Hon	esty – Co	urage –Em <sub>l</sub>	patl	hy –	Self	-Confidence
Unit 2	ENGINEERIN	NG ETHIC	CS						4
Senses of 'Engineering autonomy - Kohlberg's Roles - theories about ri Time - Co-operation -	theory - Gilligan ght action - Self-	's theory -	consens	sus and co	ontroversy -	- M	odel	ls of	Professional
Unit 3	ENGINEERIN	NG AS SO	CIAL F	EXPERIN	IENTATI(	ON			3
Engineering as experimoutlook on law - the cha			onsible	experime	enters - cod	les (	of et	hics	- a balanced
Unit 4	SAFETY, RES	SPONSIBI	LITIES	S AND R	GHTS				3
Safety and risk - assessment of safety and risk - risk benefit analysis and reducing risk - the three mile island and chernobyl case studies									
Unit 5	GLOBAL ISS	UES							3
Multinational corporations - Environmental ethics - computer ethics - weapons development - engineers as managers-consulting engineers-engineers as expert witnesses and advisors -moral leadership									
									Total: 15

TEXTBOOK	8	
1	Mike Martin and Roland Schinzinger, "Ethics in Engine	eering", McGraw-Hill, New
	York 1996	
2	Govindarajan M, Natarajan S, Senthil Kumar V. S, "En	ngineering Ethics", Prentice
	Hall of India, New Delhi, 2004	
REFERENCE	ES	
1	Charles D. Fleddermann, "Engineering Ethics", Pearson	n Education / Prentice Hall,
	New Jersey, 2004 (Indian Reprint now available).	
2	Charles E Harris, Michael S. Protchard and Michael J Ra	abins, "Engineering Ethics -
	Concepts and Cases", Wadsworth Thompson Leatning,	United States, 2000 (Indian
	Reprint now available).	
3	John R Boatright, "Ethics and the Conduct of Business	s", Pearson Education, New
	Delhi, 2003.	
4	Edmund G Seebauer and Robert L Barry, "Fundamentals	s of Ethics for Scientists and
	Engineers", Oxford University Press, Oxford, 2001.	
	, ,	
	INSTITUTE OF TECHNOLOGY	
COURSEOU	TCOMES:	Bloom's Taxonomy
	monitoit di italmotodi	Bloom's Taxonomy Level
	TCOMES:	•
At the end of	TCOMES: the course, learners will be able to	Level
At the end of CO1	TCOMES: the course, learners will be able to Understanding Core Human Values	Level K2
CO2	TCOMES: the course, learners will be able to Understanding Core Human Values Applying Ethical Theories in Engineering	K2 K3

POs/	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
COs	101	102	105			100	10,	100	10)	1010		1012	1501	1502	1500
CO1		1	-	-		2	1	. 20	11-	2	-	2	-	1	-
CO2	1	-	1	-	2	ı	-	-	2	-	7	-	-	-	-
CO3	-	-	-	-	-	ı	2	-	ı	-	ı	-	-	2	-
CO4	-	2	-	-	1	ı	-	2	1	-	1	-	-	-	-
CO5	-	-	-	-	2	ı	-	-	2	-	2	-	1	-	1

AEC302 BASIC E	LECTRICAL AND ELI	ECTRON	ICS ENGINEERI	NG	LAF	BOR	ATORY
Programme & Branch	BE & MECH	Sem.	Category	L	T	P	С
		1	ES	0	0	4	2

### Preamble ➤ Soldering and testing simple electronic circuits; ➤ Assembling and testing simple electronic components on PCB. ➤ Study of basic electrical and digital equipment.

#### LIST OF EXPERIMENTS

- 1. Soldering simple electronic circuits and checking continuity.
- 2. Assembling and testing electronic components on a small PCB.
- 3. Study of electronic components and equipment's.
  - (a) Resistor Color coding using digital multi-meter.
  - (b) Assembling electronic components on breadboard.
- 4. Verification of Logic Gates
- 5. Verification of Half Adder and Full Adder
- 6. Measurement of electrical quantities-voltage current, power & power factor in RLC circuit
- 7. Verification of KVL, KCL
- 8. Verification of Thevenin, Norton, Superposition Theorem
- 9. Fluorescent lamp wiring
- 10. Stair case wiring
- 11. Study of iron box wiring and working
- 12. Assembly and dismantle of computer/laptop

Total: 60

COURSEOUTO At the end of the	COMES: e course, learners will be able to	Bloom's Taxonomy Level
CO1	Solder and test simple electronic circuits; Assemble and test simple electronic components on PCB.	К3
CO2	Demonstrate the wiring of various electrical joints in common household electrical wire work.	К3
CO3	Test the working of basic logic gates.	К3
CO4	Understand the working of basic electrical devices	К3
CO5	Apply basic electrical concepts to implement basic electrical circuits.	К3

POs/ COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	-	-	1	1	1	-	-	-	-	2	2	1	1
CO2	3	2	-	-	1	1	1	-	-	-	-	2	2	1	1
CO3	3	2	-	-	1	1	1	-	-	-	-	2	2	1	1
CO4	3	2	-	-	1	1	1	-	-	-	-	2	2	1	1
CO5	3	2	-	-	1	1	1	-	-	-	-	2	2	1	1

Programme &	BE& MECH	Sem.	Category	L	T	P	C
Branch		1	ES	0	0	4	2
Preamble	<ul> <li>To understand the</li> <li>To learn the basic</li> <li>To practice various world problems.</li> <li>To use Python dat</li> </ul>	programming computing	ng constructs in strategies for Py	Pythorython-	base		ions to 1

#### LIST OF EXPERIMENTS

- 1. Identification and solving of simple real life or scientific or technical problems, and developing flow charts for the same. (Electricity Billing, Retail shop billing, Sin series, weight of a motorbike, Weight of a steel bar, compute Electrical Current in Three Phase AC Circuit, etc.)
- 2. Python programming using simple statements and expressions (exchange the values of two variables, circulate the values of n variables, distance between two points).
- 3 Scientific problems using Conditionals and Iterative loops. (Number series, Number Patterns, pyramid pattern)
- 4.Implementing real-time/technical applications using Lists, Tuples. (Items present in a library/Components of a car/ Materials required for construction of a building –operations of list & tuples)
- 5.Implementing real-time/technical applications using Sets, Dictionaries. (Language, components of an automobile, Elements of a civil structure, etc.- operations of Sets & Dictionaries)
- 6. Implementing programs using Functions. (Factorial, largest number in a list, area of shape)
- 7.Implementing programs using Strings. (reverse, palindrome, character count, replacing characters)
- 8.Implementing programs using written modules and Python Standard Libraries (pandas, numpy. Matplotlib, scipy)
- 9.Implementing real-time/technical applications using File handling. (copy from one file to another, word count, longest word)
- 10.Implementing real-time/technical applications using Exception handling. (divide by zero error, voter's age validity, student mark range validation)
- 11.Exploring Pygame tool. 12. Developing a game activity using Pygame like bouncing ball, car race etc.

		Total: 60				
COURSEOUT	COMES:	Bloom's Taxonomy				
At the end of the	At the end of the course, learners will be able to					
CO1	Develop algorithmic solutions to simple computational	К3				
	problems					
CO2	Develop and execute simple Python programs.	К3				
CO3	Implement programs in Python using conditionals and	К3				
	loops for solving problems.					

CO4	Deploy functions to decompose a Python program.	К3
CO5	Process compound data using Python data structures.	K3

POs/ COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	-	-	1	1	1	-	-	-	-	2	2	1	
CO2	3	2	-	-	1	1	1	-	-	-	-	2	2	1	
CO3	3	2	-	-	1	1	1	-	-	-	-	2	2	1	
CO4	3	2	-	-	1	1	1	· · ·		<u>-</u>	-	2	2	1	
CO5	3	2	-	-	1	1	1	i	-	-	-	2	2	1	

	1 COMMUNICATION SI						
Programme &	BE & MECH	Sem.	Category	L	T	P	С
Branch							
		1	HS	0	0	2	1
Preamble	<ul> <li>Impart a thorough untechnical communic</li> <li>Develop the skills not audience needs.</li> <li>Enhance proficiency genres related to technical communic</li> <li>Foster an awareness technical communic</li> </ul>	ation.  ceessary to the using the ability ation prace of ethical	tailor technical clanguage technique nmunication. to utilize technotices.	comm ies an logica	unica d und	ation dersta	to divers anding improve
Unit 1	PRINCIPLES OF TEC	CHNICAL	L COMMUNICA	TIO	N		12

Listening -Brief video snippets of conversational moments from movies and short documentaries

Speaking- Presenting oneself, introducing others, inviting people, and explaining places.

Reading - Short passages that need understanding include inference and critical analysis.

Writing-Finishing missing phrases and constructing suggestions based on supplied information.

Grammar- Who-Questions and Yes/No Questions - Parts of Speech. Vocabulary development: prefixes, suffixes, articles, countable and uncountable nouns.

Unit 2	AUDIENCE-CENTERED COMMUNICATION	12
--------	---------------------------------	----

Listening: Deep Listening - Talk Shows and Debates.

Reading: In depth Reading: Scanning Passages

Speaking: Describe current issues, happenings, etc.

Writing: Instructions, Recommendations, Note Taking, and Paragraph Writing

Grammar: Continuous tenses, prepositions and articles

Vocabulary: Phrasal	verbs and one-word substitutes	
Unit 3	LANGUAGE TECHNIQUES AND GENRES IN	12
	TECHNICAL COMMUNICATION	

Listening: Listening to lectures, podcasts, audio books.

Reading: Interpretation of Tables, Charts and Graphs

Speaking: SWOT Analysis on oneself and Narrating incidents Writing: Formal Letter Writing, Covering Letter and Memos.

Grammar: Perfect Tenses and Discourse Markers

Vocabulary: Nouns, usage of keywords

Unit 4	TECHNOLOGICAL TOOLS USED IN	12
	COMMUNICATION	

Listening: Instructional videos, webinars on personal branding and networking and TED talks

Reading: Manuals, Research papers or articles, Graphic narratives, AI tools used in reading

Speaking: Participating in and conducting mock virtual meetings, focusing on presentation skills and etiquette. Mock networking events and Elevator Pitch

Writing: E-Mails, drafting formal messages in social media handles, and Usage of AI prompts.

Grammar: Adjectives, Verbs and Adverbs.

Unit 5	ETHICAL AND GLOBAL PERSPECTIVES IN	12
	TECHNICAL COMMUNICATION	

Listening: Podcasts, documentaries and webinars on digital ethics and cybersecurity.

Reading: Articles on fundamental ethical principles and case studies.

Speaking: Cultural sensitivity and representation ross-cultural communication strategies Mock meetings to practice global collaboration.

Writing: Case study analysis reports on legal and ethical responsibilities. Proposals for implementing sustainable communication practices.

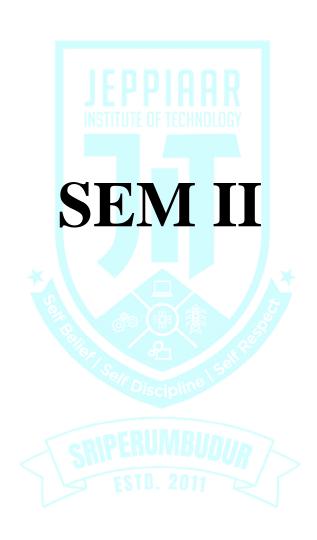
Grammar: Reported Speech, Idioms and phrases and Loan words

	Total: 60
TEXTBOOKS	Discipline
1	Effective Technical Communication by M. Ashraf Rizvi (Author) 2nd Edition
	Paperback 2017
2	Sylvan Barnet and Hugo Bedau, 'Critical Thinking Reading and Writing', Bedford/st.
	Martin's: Fifth Edition (June 28, 2004)
3	Meenakshi Upadhyay, Arun Sharma – Verbal Ability and Reading Comprehension.
4	Teaching Speaking: A Holistic Approach, Book by Anne Burns and Christine Chuen
	Meng Goh, Cambridge.
REFERENCES	
1	Technical Communication: A Reader-Centered Approach" by Paul V. Anderson
2	"Technical Writing: Process and Product" by Sharon J. Gerson and Steven M. Gerson
3	"English for Engineers and Technologists: A Skill Approach" by Jeyanthi G. and
	Ramasamy P
4	"A Handbook for Technical Writers and Editors" by M. Ragunathan and M.
	Sundararajan
	,

COURSEOUTO	COMES:	Bloom's Taxonomy
At the end of the	Level	
CO1	To create clear and successful technical publications, use core technical communication concepts.	K2
CO2	Modify technical communication to the requirements and expectations of various audiences.	K2
CO3	Use proper language and genres to effectively communicate technical knowledge.	K2
CO4	Use technology technologies to improve the generation, management, and dissemination of technical material.	K2
CO5	Navigate ethical quandaries and explore global views in technological communication methods.	K2

CO	)-РО	Марр	ing												
POs/ COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	1	2	1	1									
CO2	1	2	1	1	1	1									
CO3	1	1	2	2	1	2									
CO4	1	1	1	1	1	1									
CO5	2	1	1	1	1	1									





Programme	&	BE & MECH	Sem.	Category	L	T	P	C		
Branch										
		N 77 1 . 1.1 . 1	2	BS	3	1	0	4		
		Understand the appl			engın	eerin	ig ap	art from its		
		uses in solving boundary value problems								
		➤ Understand the basic concepts of the Fourier transform techniques and its								
Preamble		application in Engin	_	1, 1, 0, 1, 1,	٠.	c	.· 1	1:001		
		Use the effective ma				-				
		equations that mode	_	=	and t	o dev	erop	Z		
		transform technique	s for discr	ete time systems.						
Unit 1		PARTIAL DIFFEREN	TIAL EQ	UATIONS				9+3		
Formation of par	tial diff	ferential equations – Sing	gular integr	als - Solutions of	stand	ard ty	pes	of first order		
partial differentia	al equa	ntions - Lagrange's linea	ar equation	n – Linear homog	geneo	us pa	artial	differentia		
equations of seco	nd and	higher order with consta	ant coeffici	ients.						
Unit 2		FOURIER SERIES						9+3		
Dirichlet's condi	tions –	General Fourier series -	- Odd and	even functions –	Half	rang	e sin	e series and		
cosine series – Pa	arseval	's identity Hermonic or	a olyvaia							
	arbe var	s identity – Harmonic at	iarysis.							
Unit 3	arse var	APPLICATIONS OF		DIFFERENTIA	L			9+3		
Unit 3		APPLICATIONS OF EQUATIONS	PARTIAL							
Unit 3 Classification of	PDE –	APPLICATIONS OF EQUATIONS  Method of separation of	PARTIAL variables -	Solutions of one-	dime			ave equation		
Unit 3  Classification of using Fourier ser	PDE –	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation	PARTIAL variables -	Solutions of one- conduction – Ste	dime			ave equation		
Unit 3  Classification of using Fourier sendimensional equa	PDE –	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation of the heat conduction (Cartes)	variables - on of heat ian coordi	Solutions of one- conduction – Ste	dime			ave equation		
Unit 3  Classification of using Fourier sendimensional equal Unit 4	PDE – ries – ( ation of	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation from the conduction (Cartes)  FOURIER TRANSFORM	variables - on of heat ian coordi	Solutions of one- conduction – Stenates only).	dimer eady	state	solu	ave equation tion of two-		
Unit 3  Classification of using Fourier sendimensional equation by the Unit 4  Statement of Fourier 1	PDE – ries – ration of	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation from the equation (Cartest FOURIER TRANSFO tegral theorem – Fourier	variables - on of heat ian coordi  DRMS transform	Solutions of one- conduction – Ste nates only).	dimeready s	state d cos	solu	ave equation tion of two-		
Unit 3  Classification of using Fourier serdimensional equation by Unit 4  Statement of Fourier Franchischer Transport 1985	PDE – ries – ration of	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation for the front the conduction (Cartest FOURIER TRANSFORM tegral theorem — Fourier of simple functions — Control of the conduction of th	variables - on of heat ian coordi  DRMS transform	Solutions of one- conduction – Ste nates only).	dimeready s	state d cos	solu	ave equation tion of two-		
Unit 3  Classification of using Fourier serdimensional equal Unit 4  Statement of Fourier Fourier Serdimensional equal Unit 5	PDE – ries – contion of the price in a sforms	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation for the equation (Cartest FOURIER TRANSFORMS)  The equation of the	variables - on of heat ian coordi ordi ordi ordi ordi ordi ordi ordi	Solutions of one- conduction – Ste nates only). pair – Fourier si theorem – Parsey	dimeready s	d cos	solurisine t	9+3 ransforms -		
Unit 3  Classification of using Fourier serdimensional equal Unit 4  Statement of Fourier Transet Unit 5  Z- transforms - E	PDE – ries – o ation of arier in asforms	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation of the tendent conduction (Cartest FOURIER TRANSFORMS to simple functions – Corollary properties – Convolutions – Convolution	variables - on of heat ian coordin DRMS transform onvolution	Solutions of one- conduction – Ste nates only).  pair – Fourier si theorem – Parsey	dimeready s	d cos denti	sine t	9+3 g partial and		
Unit 3  Classification of using Fourier serdimensional equation Unit 4  Statement of Fourier Transity Unit 5  Z- transforms - Econvolution theo	PDE – ries – o ation of arier in asforms	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation for the equation (Cartest FOURIER TRANSFORMS)  The equation of the	variables - on of heat ian coordin DRMS transform onvolution	Solutions of one- conduction – Ste nates only).  pair – Fourier si theorem – Parsey	dimeready s	d cos denti	sine t	9+3 g partial and		
Unit 3  Classification of using Fourier serdimensional equation Unit 4  Statement of Fourier Transity Unit 5  Z- transforms - Econvolution theo	PDE – ries – o ation of arier in asforms	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation of the tendent conduction (Cartest FOURIER TRANSFORMS to simple functions – Corollary properties – Convolutions – Convolution	variables - on of heat ian coordin one on volution ution theore	Solutions of one- conduction – Ste nates only).  pair – Fourier si theorem – Parsey	dimeready s	d cos denti	sine t	9+3 ransforms - 9+3 g partial and ns using Z -		
Unit 3  Classification of using Fourier set dimensional equate Unit 4  Statement of Fourier Set of Fourier 4  Statement of Fourier 5  Z- transforms - Econvolution theo transform.	PDE – ries – o ation of arier in asforms	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation of the tendent conduction (Cartest FOURIER TRANSFORMS to simple functions – Corollary properties – Convolutions – Convolution	variables - on of heat ian coordin one on volution ution theore	Solutions of one- conduction – Ste nates only).  pair – Fourier si theorem – Parsey	dimeready s	d cos denti	sine t	9+3 g partial and		
Unit 3  Classification of using Fourier serdimensional equal Unit 4  Statement of Fourier Serdimensional equal Unit 5  Textbooks	PDE – ries – ries of rier in rier in rier in rier in	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation of the tendent conduction (Cartest FOURIER TRANSFO tegral theorem – Fourier of simple functions – Convolution of difference formation of difference	variables - on of heat ian coordi  ORMS transform onvolution ution theore	Solutions of one-conduction – Stenates only).  pair – Fourier si theorem – Parseverem - Inverse Z - Solution of diff	ne anval's i	d cos denti Form	sine ty using	9+3 ransforms - 9+3 g partial and ns using Z  Total: 60		
Unit 3  Classification of using Fourier set dimensional equation Unit 4  Statement of Fourier Transtant Unit 5  Z- transforms - Econvolution theo transform.	PDE – ries – Gation of urier in asforms Elemen rem – I	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation for the feat conduction (Cartest FOURIER TRANSFORMS)  tegral theorem – Fourier of simple functions – Convolution of difference formation of difference of Kreyszig, Advanced In Kreyszig, Ad	variables - on of heat ian coordi  ORMS transform onvolution ution theore	Solutions of one-conduction – Stenates only).  pair – Fourier si theorem – Parseverem - Inverse Z - Solution of diff	ne anval's i	d cos denti Form	sine ty using	9+3 ransforms - 9+3 g partial and ns using Z		
Unit 3  Classification of using Fourier set dimensional equal Unit 4  Statement of Fourier - Transet Unit 5  Z- transforms - Econvolution theo transform.	PDE – ries – ries in rier in sforms Elemen rem - Terwin 2011	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation of the tendence of	variables - on of heat ian coordin onvolution ution theore equations Engineerin	Solutions of one-conduction – Stenates only).  pair – Fourier si theorem – Parseverem - Inverse Z - Solution of different general section of different forces.	ne an val's i	d cosdenti Corm e equ	sine ty using	9+3 ransforms - 9+3 g partial and ns using Z - Total: 60		
Unit 3  Classification of using Fourier serdimensional equal Unit 4  Statement of Fourier – Tran Unit 5  Z- transforms – Econvolution theocransform.	PDE – ries – Gation of arier in asforms Elemen rem – D Erwii 2011. Grew	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation for the equation (Cartest FOURIER TRANSFORMS)  tegral theorem — Fourier of simple functions — Compared to the equation of the equation of the equation of difference of the equation of the equati	variables - on of heat ian coordin onvolution ution theore equations Engineerin	Solutions of one-conduction – Stenates only).  pair – Fourier si theorem – Parseverem - Inverse Z - Solution of different general section of different forces.	ne an val's i	d cosdenti Corm e equ	sine ty using	9+3 ransforms - 9+3 g partial and ns using Z  Total: 60		
Unit 3  Classification of using Fourier serdimensional equate Unit 4  Statement of Fourier 5  Z- transforms - Econvolution theotransform.  TEXTBOOKS  1  2	PDE – ries – ries – rier in sforms Elemen rem - 2011 Grew Delhi	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation of the tendency of the tendency of the tendency of simple functions – Control of simple functions – Control of tendency of simple functions – Control of tendency of tende	variables - on of heat ian coordin on volution ution theor equations Engineerin ering Math	Solutions of one-conduction – Stenates only).  pair – Fourier sing theorem – Parsey rem - Inverse Z - Solution of different different formatics, and the solution of different formatics for a solution of different formatics.	ne an transference	d cosdenti Form e equ	sine ty using	9+3 g partial and ns using Z  Total: 60  Wiley India		
Unit 3  Classification of using Fourier set dimensional equal Unit 4  Statement of Fourier - Transtant Unit 5  Z- transforms - Econvolution theo transform.	PDE – ries – Gation of urier in usforms Elemen rem – J Erwin 2011. Grew Delhi Naray	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation of the equation (Cartest FOURIER TRANSFORMS)  tegral theorem – Fourier of simple functions – Compared to the equation of the equat	variables - on of heat ian coordi or transform onvolution ution theor equations Engineerin ering Math	Solutions of one-conduction — Stenates only).  I pair — Fourier sing theorem — Parseverem — Inverse Z — Solution of different different particles, and the second particles, a	ne an val's i	d cosdenti Corm e equ	solution sine to ty  using the control on, Veneziania	9+3 g partial and ns using Z  Total: 60  Wiley India Publishers		
Unit 3  Classification of using Fourier set dimensional equal Unit 4  Statement of Fourier – Tran Unit 5  Z- transforms – Econvolution theo transform.  TEXTBOOKS  1  2	PDE – ries – ries – rier in asforms Elemen rem – Control Contr	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation of the tendency of the tendency of simple functions — Control of simple function	variables - on of heat ian coordi or transform onvolution ution theor equations Engineerin ering Math	Solutions of one-conduction — Stenates only).  I pair — Fourier sing theorem — Parseverem — Inverse Z — Solution of different different particles, and the second particles, a	ne an val's i	d cosdenti Corm e equ	solution sine to ty  using the control on, Veneziania	9+3 g partial and ns using Z  Total: 60  Wiley India Publishers		
Classification of using Fourier set dimensional equal Unit 4 Statement of Fourier Set Transforms - Econvolution theotransform.  TEXTBOOKS  1 2 3	PDE – ries – Gation of urier in usforms Elemen rem – J Erwin 2011. Grew Delhi Naray	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation of the tendency of the tendency of simple functions — Control of simple function	variables - on of heat ian coordi or transform onvolution ution theor equations Engineerin ering Math	Solutions of one-conduction — Stenates only).  I pair — Fourier sing theorem — Parseverem — Inverse Z — Solution of different different particles, and the second particles, a	ne an val's i	d cosdenti Corm e equ	solution sine to ty  using the control on, Veneziania	9+3 g partial and ns using Z  Total: 60  Wiley India Publishers		
Unit 3  Classification of using Fourier set dimensional equal Unit 4  Statement of Fourier 5  Z- transforms - Econvolution theo transform.  TEXTBOOKS  1  2	PDE – ries – ries – ries in rier in rier in rier in rem – ries –	APPLICATIONS OF EQUATIONS  Method of separation of One dimensional equation of the tendency of the tendency of simple functions — Control of simple function	variables - on of heat ian coordin  PRMS transform onvolution  ution theore equations  Engineerin ering Math hagam Pil Students,	Solutions of one-conduction — Stenates only).  pair — Fourier sing theorem — Parsever — Inverse Z — Solution of different generation, and the second part of the seco	ne anval's i	d cosdenti Corm e equ Edition, Kh	solution sine to ty  using the control of the contr	9+3 g partial and ns using Z  Total: 60  Wiley India Publishers G Advanced blishers Pyter		

2	Ramana, B.V., Higher Engineering Mathematics, Tata McGraw Hill Education Private							
	Ltd., 9th Edition, New Delhi 2010							
3	Michael Greenberg, Advanced Engineering Mathematics, 2nd Edition, Pearson							
	Education, 2011							

COURSEOUT	COMES:	Bloom's Taxonomy
At the end of th	e course, learners will be able to	Level
CO1	Acquire problem solving skills to handle first order and	K3
	higher order Partial differential equations.	
CO2	Demonstrate Fourier series to study the behaviour of	K3
	periodic functions and their applications in engineering	
	problems such as system communications, digital signal	
	processing and field theory.	
CO3	Develop skills in classification, formulation, solution, and	К3
	interpretation of PDE models.	
CO4	Develop the skill of conversion between time domain to	К3
	frequency domain using the concept of Fourier	
	Transforms.	
CO5	Use the effective mathematical tools for the solutions of	K4
	partial differential equations by using Z-transform	
	techniques for discrete time systems.	

	PO1	PO2	PO3	PO4	PO5	PO6	PO1	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	1	1	-	0/	-/	Ŏ.	2	- 00°	-	3	-	-	-
CO2	3	3	1	1	-		So.		2	jell <u>-</u>	-	3	-	-	-
CO3	3	3	1	1	-	-	L	iscip	2	_	-	3	-	-	-
CO4	3	3	1	1	-	-	_	_	2	-	-	3	-	-	-
CO5	3	3	1	1	-		DER	III	2		-	3	-	-	-

API	H102 ENGINEERING M	IATERIAL	S AND METAI	LLUR	GY		
Programme & Branch	BE& MECH	Sem.	Category	L	Т	P	С
		2	BS	3	0	0	3
Preamble	<ul> <li>To learn the construphase diagram for</li> <li>microstructure form</li> <li>To learn selecting a microstructure form</li> </ul>	nation.	Ü				

➤ To illustrate the different types of ferrous and non-ferrous alloys and their uses in engineering field.
 ➤ To illustrate the different polymer, ceramics and composites and their uses in engineering field.
 ➤ To learn the various testing procedures and failure mechanism in engineering field
 Unit 1
 CONSTITUTION OF ALLOYS AND PHASE 9
 DIAGRAMS

Constitution of alloys – Solid solutions, substitutional and interstitial – phase diagrams, Isomorphous, eutectic, eutectoid, peritectic, and peritectoid reactions, Iron – Iron carbide equilibrium diagram. Classification of steel and cast-Iron microstructure, properties and application

#### Unit 2 MECHANICAL TESTING

Q

Testing of materials under tension, compression and shear loads, Hardness tests, fatigue and creep test. Impact testing, Fatigue testing, Fracture, Types, Fracture mechanics. Characteristics of creep curve & steady state creep. Fracture toughness & fatigue, Stress and temperature effects

#### Unit 3 HEAT TREATMENT

9

Definition – Full annealing, stress relief, recrystallisation and spheroidising –normalizing, hardening and tempering of steel. Isothermal transformation diagrams – cooling curves superimposed on I.T. diagram – continuous cooling Transformation (CCT) diagram – Austempering, Martempering – Hardenability, Jominy end quench test -case hardening, carburizing, Nitriding, cyaniding, carbonitriding – Flame and Induction hardening – Vacuum and Plasma hardening – Thermo-mechanical treatments.

#### Unit 4 FERROUS AND NON-FERROUS METALS

9

Effect of alloying additions on steel – stainless and tool steels – HSLA - Maraging steels – Grey, white, malleable, spheroidal – alloy cast irons, Copper and its alloys – Brass, Bronze and Cupronickel – Aluminium and its alloys; Al-Cu – precipitation strengthening treatment – Titanium alloys, Mg-alloys, Ni-based super alloys – shape memory alloys- Properties and Applications – overview of materials standards

#### Unit 5 NON-METALLIC MATERIALS

9

Polymers – types of polymers, commodity and engineering polymers – Properties and applications of PE, PP, PS, PVC, PMMA, PET, PC, PA, ABS, PAI, PPO, PPS, PEEK, PTFE, Thermoset polymers – Urea and Phenol formaldehydes –Nylon, Engineering Ceramics – Properties and applications of Al2O3, SiC, Si3N4, PSZ and SIALON – intermetallic- Composites- Matrix and reinforcement Materials, applications of Composites - Nano composites.

TEXTBOOKS	
1	William D. Callister, Jr. (2020) "Materials Science and Engineering an Introduction",
	2nd Edition, John Wiley & Sons, Inc
2	V. Raghavan (2019), "Materials Science and Engineering", Prentice – Hall of India
	Pvt. Ltd.
3	A. Alavudeen, N. Venkateshwaran, and J. T. WinowlinJappes, A Textbook of
	Engineering Materials and Metallurgy, Laxmi Publications, 2006
REFERENCES	

1	J.M. Shackelford (2014), Introduction to Materials Science for Engineers, 5thEdition,
	Prentice Hall, Inc.
2	Suryanarayana, A. V. K. (2020), Testing of Metallic Materials, Prentice Hall India,
	New Delhi
3	W. Bolton (2013), Engineering materials technology, 3 rd Edition, Butterworth
	&Heinemann

COURSEOUTO	COMES:	Bloom's Taxonomy
At the end of the	e course, learners will be able to	Level
CO1	Explain alloys and phase diagram, Iron-Iron carbon	K2
	diagram and steel classification.	
CO2	Explain the testing of mechanical properties.	K2
	IEDDICOD	
CO3	Explain isothermal transformation, continuous cooling	K2
	diagrams and different heat treatment processes.	
CO4	Clarify the effect of alloying elements on ferrous and non-	K2
	ferrous metals.	
CO5	Summarize the properties and applications of non-	K"
	metallic materials	

	PO1	PO2	PO3	PO4	PO5	PO6	PO1	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	3	2	Z 26						27	2	2	1	2
CO2	3	1	3	2	2		O <sup>®</sup> O		零	Y/A	5	2	2	1	2
CO3	3	1	3	1		2		.1		( Pe		2	2	1	2
CO4	3	1	3			Y	2	))		9e,		2	2	1	2
CO5	3	1	3			·		iscip	me			2	2	1	2

	AAI101 INTRODUC	TION TO	DATA SCIENC	E							
ESTO 2011											
Programme &	BE & MECH	Sem.	Category	L	T	P	C				
Branch											
	•	2	ES	3	0	0	3				
Preamble	<ul> <li>To understand the da</li> <li>To learn to describe</li> <li>To learn to describe</li> <li>To utilize the Pythor</li> <li>To present and interpresent</li> </ul>	the data for the relation libraries	or the data science nship between da for Data Wrangli	e proc ita. ng.	ess.	n Pyth	ion				
Unit 1	INTRODUCTION						9				
Data Science: Benefit	s and uses – facets of data	- Data Sci	ence Process: Ov	erviev	<i>x</i> – I	Definir	ng resear				

goals - Retrieving data - Data preparation - Exploratory Data analysis - build the model-presenting

•	lding applications - Data Mining - Data Warehousing – Basic	Statistical descriptions of
Data Unit 2	DESCRIBING DATA	9
• 1	Types of Variables -Describing Data with Tables and Graph	C
	ribing Variability - Normal Distributions and Standard (z) Sco	
Unit 3	DESCRIBING RELATIONSHIPS	9
	atter plots -correlation coefficient for quantitative data	
	efficient – Regression – regression line – least squares regression	
	retation of r2 –multiple regression equations –regression towards	
Unit 4	PYTHON LIBRARIES FOR DATA WRANGLIN	
-	y arrays –aggregations –computations on arrays –comparison	_
-	- structured arrays - Data manipulation with Pandas - data	<del>-</del>
	ta – missing data – Hierarchical indexing – combining d	atasets –aggregation and
grouping – pivot		
Unit 5	DATA VISUALIZATION	9
	lotlib – Line plots – Scatter plots – visualizing errors – de	
=	gends – colors – subplots – text and annotation – customiza	ation – three dimensiona
plotting - Geogra	aphic Data with Basemap - Visualization with Seaborn.	
		Total: 4
TEXTBOOKS		
1	David Cielen, Arno D. B. Meysman, and Mohamed Ali, "In Science", Manning Publications, 2016. (Unit I)	ntroducing Data
2	Robert S. Witte and John S. Witte, "Statistics", Eleventh Ed 2017. (Units II and III	lition, Wiley Publications
3	Jake Vander Plas, "Python Data Science Handbook", O'Ro	eilly, 2016. (Units IV and
REFERENCES		
1	Allen B. Downey, "Think Stats: Exploratory Data Analys Press,2014.	is in Python", Green Te
	CONDERNIMENTAL	
COURSEOUT	COMES:	Bloom's Taxonomy
	e course, learners will be able to	Level
CO1	Define the data science process	K1
	-	
CO2	Understand different types of data description for data science process	K2
CO3	Gain knowledge on relationships between data	K2
CO4	Use the Python Libraries for Data Wrangling	К3
CO5	Apply visualization Libraries in Python to interpret and	K3

	PO1	PO2	PO3	PO4	PO5	PO6	PO1	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	2	2	-	-	-	-	1	1	2	2	2	1
CO2	2	3	2	3	2	-	-	-	2	2	3	2	3	2	1
CO3	2	3	2	1	1	-	-	-	2	2	3	2	2	3	1
CO4	2	3	2	2	3	-	-	-	2	2	3	2	2	3	1
CO5	2	3	1	2	2	ı	ı	-	ı	-	ı	1	3	2	2

	AME102 ENGINEERING MECHANICS										
Programme & Branch	BE & MECH	Sem.	Category	L	Т	P	С				
	INSTITUTE	2	PC	3	0	0	3				
Preamble	<ul> <li>To Learn the use forces in staticall</li> <li>To introduce the body diagram o study and unde and intensity.</li> <li>To learn the prince concepts of fridengineering systems.</li> <li>To develop basic energy.</li> </ul>	y determ equilibri rstand the ciples of tetional fems.	inate structures um of rigid bod e distributed fore friction, forces a forces at the o	ces, sur	face, etern	load	ods and free ling on beam the apply the of various				
Unit 1	BASICS AND STATIC	S OF PA	RTICLES				9				

Introduction – Units and Dimensions – Laws of Mechanics – Lami's theorem, Parallelogram and triangular Law of forces — Vectorial representation of forces – Vector operations of forces -additions, subtraction, dot product, cross product – Coplanar Forces – rectangular components – Equilibrium of a particle – Forces in space – Equilibrium of a particle in space – Equivalent systems of forces – Principle of transmissibility.

#### Unit 2 EQUILIBRIUM OF RIGID BODIES 9

Free body diagram – Types of supports –Action and reaction forces –stable equilibrium – Moments and Couples – Moment of a force about a point and about an axis – Vectorial representation of moments and couples – Scalar components of a moment – Varignon's theorem – Single equivalent force -Equilibrium of Rigid bodies in two dimensions – Equilibrium of Rigid bodies in three dimensions.

#### Unit 3 PROPERTIES OF SURFACES AND SOLIDS 9

Centroids and centre of mass— Centroids of lines and areas - Rectangular, circular, triangular areas by integration — T section, I section, - Angle section, Hollow section by using standard formula — Theorems of Pappus - Area moments of inertia of plane areas — Rectangular, circular, triangular areas by integration — T section, I section, Angle section, Hollow section by using standard formula — Parallel axis theorem and perpendicular axis theorem — Principal moments of inertia of plane areas — Principal axes of inertia-

principie – Re	elation to area moments of inertia.					
Unit 4	DYNAMICS OF PARTICLES	9				
Displacements	s, Velocity and acceleration, their relationship - Relative motion	n – Curvilinear motion				
Newton's laws	s of motion – Work Energy Equation– Impulse and Momentum –	Impact of elastic bodies				
Unit 5	FRICTION AND ELEMENTS OF RIGID BODY	9				
	DYNAMICS					
Friction force	- Laws of sliding friction - equilibrium analysis of simple system	ns with sliding friction -				
wedge friction	a Rolling resistance -Translation and Rotation of Rigid Bodies - Y	Velocity and acceleration				
– General Plar	ne motion of simple rigid bodies such as cylinder, disc/wheel and	sphere.				
		Total: 4				
TEXTBOOK	S					
1	Beer, F.P and Johnston Jr. E.R., "Vector Mechanics for Engine	eers (In SI Units): Static				
	and Dynamics", 8th Edition, Tata McGraw-Hill Publishin	g company, New Delh				
	(2004).					
2	Vela Murali, "Engineering Mechanics", Oxford University P	ress (2010).				
3	Kumar, K.L., "Engineering Mechanics", 3rd Revised Edi	tion, Tata McGraw-Hil				
	Publishing company, New Delhi 2008.					
REFERENCI	ES					
1	Hibbeller, R.C and Ashok Gupta, "Engineering Mechanics: Statics and Dynamics",					
	11th Edition, Pearson Education 2010.					
2	Irving H. Shames and Krishna Mohana Rao. G., "Engineer	ing Mechanics – Static				
	and Dynamics", 4th Edition, Pearson Education 2006.					
3	Meriam J.L. and Kraige L.G., " Engineering Mechanic	s- Statics - Volume 1				
	Dynamics- Volume 2", Third Edition, John Wiley & Sons,19	93.				
4	Rajasekaran S and Sankarasubramanian G., "Engineering	Mechanics Statics and				
	Dynamics", 3rd Edition, Vikas Publishing House Pvt. Ltd., 2	.005				
5	Bhavikatti, S.S and Rajashekarappa, K.G., "Engineering	Mechanics", New Age				
	International (P) Limited Publishers, 1998.					
	- INTRIBADUA.					
COURSEOU		Bloom's Taxonomy				
At the end of	the course, learners will be able to	Level				
CO1	Illustrate the vector and scalar representation of forces and	K2				
	moments.					
CO2	Analyse the rigid body in equilibrium.	K4				
CO3	Evaluate the properties of distributed forces.	K4				
CO4	Determine the friction and the effects by the laws of	K3				
	friction.					
CO5	Calculate dynamic forces exerted in rigid body.	<b>K</b> 4				

	PO1	PO2	PO3	PO4	PO5	PO6	PO1	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	2				-	-	-	2	3	1	1
CO2	3	2	2	1	2				-	-	-	2	3	1	1
CO3	3	2	2	1	2				-	-	-	2	3	1	2
CO4	3	2	2	1	2				-	-	-	2	3	1	2
CO5	3	2	2	1	2				ı	-	ı	2	3	1	2

	ACS104 FUNDAMENTALS OF CLOUD COMPUTI	NG				
Programme & Branch	BE & MECH Sem. Category L	ГР	С			
	ES 3	0 0	3			
Preamble  To understand the principles of cloud architecture, models and infrastructure.  To understand the concepts of virtualization and virtual machines.  To gain knowledge about virtualization Infrastructure.  To explore and experiment with various Cloud deployment environments.						
	> To learn about the security issues in the cloud environ	ment.				
Unit 1	BASIC CONCEPTS OF CLOUD COMPUTING		9			
<u> </u>	ns- Concepts of Distributed Systems. Definition of Cloud, vice Providers, NIST Cloud Computing, Cloud Characteristic		epts of Cloud			
Unit 2	CLOUD INFRASTRUCTURE		9			
	Layered Architectural Design, Cloud Delivery Models.  Design Challenges, Cloud Storage - Storage-as-a-Service – A e Providers - S3.					
Unit 3	VIRTUALIZATION BASICS		9			
Virtualization for Clo	ts architecture—VM primitive operations- Virtual Infrastructure Computing—Levels of Virtualization Implementation zation Support at the OS Level, Physical versus Virtual	- V	MM Design			
Unit 4	BUILDING CLOUD NETWORKS		9			
Designing and Implementing a Data Center-Based Cloud Installing Open Source Cloud service. Virtual Box – Eucalyptus Public Cloud Platforms: Google App Engine, Amazon Web Services (AWS). Google Cloud Platform. Emerging Cloud Software Environments						
Unit 5	CLOUD SECURITY AND APPLICATIONS		9			
Cloud Security Infrast	ructure Security Network level security- Host level security and security Issues. Access Control and Authentication in clo					

1	Kai Hwang, Geoffrey C. Fox, Jack G. Dongarra, "Distributed and Cloud Computing,					
	From Parallel Processing to the Internet of Things, Morgan Kaufmann Publishers,					
	2012.					
2	Mastering Cloud Computing Foundations and Ap	oplications Programming				
	RajkumarBuyya, Christian Vechhiola, S. ThamaraiSelvi					
REFERENCES						
1	Cloud Computing: Concepts, Technology & Architecture	e by Thomas Erl, Ricardo				
	Puttini, Zaigham Mohammad 2013					
2	Krutz, R. L., Vines, R. D, "Cloud security. A Comprehens	Krutz, R. L., Vines, R. D, "Cloud security. A Comprehensive Guide to Secure Cloud				
	Computing", Wiley Publishing, 2010					
COURSEOUTO	COMES:	Bloom's Taxonomy				
	COMES: e course, learners will be able to	Bloom's Taxonomy Level				
		· ·				
At the end of the	e course, learners will be able to	Level				
At the end of the	Understand the design challenges in the cloud.	Level K2				
CO1 CO2 CO3	Understand the design challenges in the cloud.  Apply the concept of virtualization and its types.  Experiment with virtualization of hardware resources.	K2  K3  K3				
At the end of the CO1	Understand the design challenges in the cloud.  Apply the concept of virtualization and its types.	K2 K3				

CO5

	PO1	PO2	PO3	PO4	PO5	PO6	PO1	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	3	1	(Oc		ी	2	3	1	2	3	3	3
CO2	2	2	2	3	3	-<	Self		1	2	2	3	1	1	3
CO3	3	3	3	3	3	I	1	Iscip	2	1	1	2	2	1	3
CO4	3	3	1	1	1	_	_	_	_1_	3	1	3	2	1	1
CO5	3	2	2	2	3	ell	D-F	11-17	2	3	2	2	2	3	3

K2

Explain security challenges in the cloud environment.

	AHS101 8	மிழர்	மரபு				
Programme & Branch	BE& MECH	Sem.	Category	L	T	P	C
		2	HS	1	0	0	1
Preamble	1. தமிழர் களின்பன் 2. அறத் தோடுவாழ்		ட் டிணிறிதல்				
அலகு I	மொழிமற் றும் (	இலக்	கியம்				3
இந் தியமொழிக்	குடும் பங் கூறைரா	മിഥ ഒ	)மாழிகள்-தமிழ்	<u> </u> 6	உரு	செ	்ம் மொழ

இந் தியமொழிக் குடும் பங் கூறூராவிட் மொழிகள்-தமிழ் ஒரு செம் மொழி தமிழ் செவ் விலக் கியங்-கூள் கூஇலக் கியத் திக்கையச் சார்பற் றதன் மை சங் க இலக் கியத் தில் பகிர் அற்ம் – திருக் குறளில் மேலாண் மைக்

கருத் தாக் கூ	தா்மிழ் க் காப் பியங் கூதா்மிழகத் தில் சமணபௌத் த
	ன் தாக் கட்வக் தி இலக் கிய <u>ட்</u> ழும் வார் கள் மற் றுட்
	கூளிற் றிலக் கியங்- <b>தூவி</b> ழில் நவீன இலக் கியத் திண்ளர் ச் சி
	கியவளர் ச் சியின்றையார் மற் அம்பாரதிதாசன் ஆகியோரின்
பங் களிப். பு	
அலகு II	
	ஓவியங்கள் வரை சிற்பக்கலை
	ல் நவீன சிற் பங் கள் – ஜும்ரைபொன் சிலைகட்டைநட் குடியினர்
மற் அம் அ	அவர் கள் தயாரிக் கும் கைவினைப் ப <b>ிறா</b> ட்ம் கூள்மைகள் –
தேர் செய் யு	பும் ககைடுமெண் சிற் பங் கூறாட் டுப் புறத் தெய் வங்குகூறி
முனையில்	திருவள் ளுவர் சிண <b>ூ</b> சைக் கருவிகள்– மிருதங் கட், பறை,
வீணை, யாழ்	், நாதஸ் வரம்– தமிழர் களின் சமூகபொருளாதார வாழ் வில்
கோவில் களி	ன் பங் கு
அலகு III	நாட்டுப் புறக்கலைகள் மற்றும் 3
	வீ ரவிளையாட்டுகள்
தெருக் கூத்,ச	தூகாட் டம் வில் லுப் பாட் இணியான் கூத், துஒயிலாட் டம்
	யக் கூத் தூலம் பாட் டம்வளரி, புலியாட் டம் தமிழர் களின்
விளையாட் டூ	
அலகு IV	தமிழர்களின் திணைக் கோட்பாடுகள் 3
தமிழகத் தின்	ர தாவரங் க <b>ுள்</b> ம்ங் குகளும் தொல் காப் பியம் மற் றும் சங்
இலக் கியத்	தில் அகம் மற் றும் புறக் கோட் தாடிைந்ள்கள் போற் றிய
அறக் கோட்	பாடு சங் ககாலத் தில் தமிழகத் தில் எழுத் <b>தூறிஷ்</b> யியும்–
	கரங் களும் துறைமுகங் களும் ககாலத் தில் ஏற் அமதி மற் அட
இறக் குமதிக	கடல் கடந் தநாடுகளில் சோழர் களின் .வெற் றி
அலகு V	இந் திய தேசிய இயக் கம் மற் இறு்ம்திய 3
	பண் பாட் டிற் குத்
<u> </u>	தமிழர் களின் பங் களிப் பு
	ிடுதலைப் போரில் தமிழர்களின் பங் இதை தியாவின்
,	ளில் தமிழ் ப் பண் பாட் டின் – தாமைற்கோம்றதை இயக் கம்-
-	ருத் துவத், திகித் த மருத் துவத் தின் பங் தூல் வெட் டுகள்
கையெழுத் த	தப் படிகத்மிழ் ப் புத் தகங் களின் அச் சுவரலாறு
TENTED OOK	Total: 15
TEXTBOOKS	தமிழகவரலாறு – மக் களும் பண் பாடும்கே.கே. பிள் ளை
-	
	(வெளியீடு:தமிழ் நாடு பாட்நூல் மற் றும் கல் வியியல் ப <b>ு</b> ளிக
)	

3	Social Life of Tamils (Dr.K.K.Pillay) A joint publication of TNTB & ESC and RMRL
	– (in print)
REFERENCES	
1	கீழடி – வைகை நதிக் கரையில் சங் க கால நகர நாகர
	(தொல் லியல் துறைவெளியீடு
2	பொருநை ஆற் றங் கரைநாகரிகம். (தொல் லியல் துஎ
	வெளியீடு)
3	Social Life of the Tamils - The Classical Period (Dr.S.Singaravelu) (Published by:
	International Institute of Tamil Studies
4	The Contributions of the Tamils to Indian Culture (Dr.M. Valarmathi) (Published by:
	International Institute of Tamil Studies.)

AHS101 HERITAGE OF TAMILS							
	JL	OF TERM	DL DDV				
Programme & Branch	BE & MECH	Sem.	Category	L	T	P	C
		2	HS	1	0	0	1
	1. To know the c	ulture of	Tamils			•	
Preamble	2. To live virtuou	ısly					
UNIT I LANGUAGE AND LITERATURE 3					3		
Language Families in India	Language Families in India - Dravidian Languages – Tamil as a Classical Language - Classical Literature						
in Tamil – Secular Nature of Sangam Literature – Distributive Justice in Sangam Literature - Management							
Principles in Thirukural -	Tamil Epics and Impa	act of Bu	ıddhism & Jainisr	n in	Tami	il La	nd - Bakthi

Literature Azhwars and Nayanmars - Forms of minor Poetry - Development of Modern literature in Tamil - Contribution of Bharathiyar and Bharathidhasan.

UNIT II	HERITAGE - ROCK ART PAINTINGS TO	3
	MODERN ART – SCULPTURE	

Hero stone to modern sculpture - Bronze icons - Tribes and their handicrafts - Art of temple car making -Massive Terracotta sculptures, Village deities, Thiruvalluvar Statue at Kanyakumari, Making of musical instruments - Mridhangam, Parai, Veenai, Yazh and Nadhaswaram - Role of Temples in Social and Economic Life of Tamils.

#### **UNIT III** FOLK AND MARTIAL ARTS

Therukoothu, Karagattam, VilluPattu, KaniyanKoothu, Oyillattam, Leather puppetry, Silambattam, Valari, Tiger dance - Sports and Games of Tamils.

#### **UNIT IV** THINAI CONCEPT OF TAMILS 3

Flora and Fauna of Tamils & Aham and Puram Concept from Tholkappiyam and Sangam Literature - Aram Concept of Tamils - Education and Literacy during Sangam Age - Ancient Cities and Ports of Sangam Age - Export and Import during Sangam Age - Overseas Conquest of Cholas

-		
UNIT V	CONTRIBUTION OF TAMILS TO INDIAN	3
	NATIONAL MOVEMENT AND INDIAN	
	CULTURE	

Contribution of Tamils to Indian Freedom Struggle - The Cultural Influence of Tamils over the other parts of India - Self-Respect Movement - Role of Siddha Medicine in Indigenous Systems of Medicine -Inscriptions & Manuscripts – Print History of Tamil Books.

	Total: 15
TEXTBOOKS	
1	தமிழகவரலாறு – மக் களும் பண் பாடும்கே.கே. பிள் ளை
	(வெளியீடு:தமிழ் நாடுபாடநூல் மற் அம்கல் வியியல்பணிகள்
	கழகம்).
2	கணினித் தமிழ் முனைவர் இலசுந் தரம்(விகடன் பிரசுரம்
3	Social Life of Tamils (Dr.K.K.Pillay) A joint publication of TNTB & ESC and RMRL
	– (in print)
REFERENCES	
1	கீழடி – வைகை நதிக் கரையில் சங் க கால நகர நாகரிகப்
	(தொல் லியல் துறைவெளியீடு
2	பொருநை ஆற் றங் கரைநாகரிகம். (தொல் லியல் துறை
	வெளியீடு)
3	Social Life of the Tamils - The Classical Period (Dr.S.Singaravelu) (Published by:
	International Institute of Tamil Studies
4	The Contributions of the Tamils to Indian Culture (Dr.M. Valarmathi) (Published
	by: International Institute of Tamil Studies.)

	PO1	PO2	PO3	PO4	PO5	PO6	PO1	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	-	-	1	-	- 1	-		-	- /	1 -	-	-	-	-
CO2	-	-	-	-	1	-	-		_	-//	A=	-	-	-	-
CO3	-	-	ı	İ	1	-	- <del>1</del>		4		) ) )	ı	-	-	-
CO4	-	-	ı	ı	1	0-	3-1	2	$\mathcal{N}$	1,0	-	2	-	-	-
CO5	-	-	1	ı	-	200	2			self.	-	-	-	-	-

	AMC103 INDIA	N CONS	STITUTION					
PIDERIMRIDUA								
Programme &	BE& MECH	Sem.	Category	L	T	P	Credit	
Branch	ESTI	. 201						
		2	MC	2	0	0	0	
Preamble  This course intends to impart a comprehensive outlook about the nature the Indian constitution; rights and duties of the citizens, Political Institution of Central and State governments and its relationship with each other at the organization and functions of local government.  A detailed analysis of the functions of the statutory bodies are incorporation this course.								
Unit 1							9	
Constitutional Assemb	oly – Philosophy – Preamble	– Salier	nt Features of Ind	ian Co	nstit	ution		
Unit 2		•		•			9	

Fundamental Rig	hts – Directive Principles of State Policy – Fundamental Dutie	S.						
Unit 3		9						
Union Executive	President: Election – Powers and Functions – Council of Mir	nisters – Prime Minister:						
Position and Pow	ers – Relationship between Prime Minister and President. State	e Executive – Governor:						
Powers and funct	ions – Chief Minister: Position and Powers – Relationship betw	ween Chief Minister and						
Governor.								
Unit 4		9						
_	e: Structure, Powers and Functions – Speaker: Power and Functions							
	nendment – State Legislature: Structure, Powers and Functions	9						
Unit 5	County Downers and Eventions High County Downers and Even							
Judiciary – Supre	me Court: Powers and Functions – High Court: Powers and Func	Total: 45						
TEXTBOOKS		10tal; 45						
	Siyyach I.D. Dynamica of Indian Covamment and Dalitica Na	yy Dolhi: Storling 1005						
1	Siwach, J.R, Dynamics of Indian Government and Politics, Ne							
2 DEFEDENCES	Narang, A.S., Indian Government and Politics New Delhi: Git	tanjan ,1995						
REFERENCES	The law D. The Covernment and Politics of India Landau M	Jameillan 1005						
1	Thanks, It The Soveriment and I shales of mala. Bolicon, Hardinian, 1996.							
2	Gupta, D.C, Indian Government and Politic, New Delhi, 1996	0						
COURSEOUTC	OMEC.	Bloom's Taxonomy						
		Level						
CO1	Understand the meaning and importance of Constitution,	K2						
COI	Fundamental rights and duties, union government, state and	KZ						
	local governments, other statutory bodies.							
CO2	Create awareness about social responsibilities.	K3						
CO2	create awareness about social responsionities.	KJ						
CO3	To apply the functioning of Union, State and Local	K3						
	Governments in Indian federal system.							
GO.4	(SCIDII)	***						
CO4	To analyze election commission and amendment procedure	K4						
	for various statuary bodies.							
CO5	Understand the meaning and importance of Constitution,	K2						
	Fundamental rights and duties, union government, state and							
	local governments, other statutory bodies.							

	PO1	PO2	PO3	PO4	PO5	PO6	PO1	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	-	-	-	-	3	3	3	-	3	-	2	-	1	1
CO2	2	-	-	-	1	3	3	3		3	-	2	-	1	2
CO3	2	-	-	-	-	3	3	3	-	3	-	2	-	1	2
CO4	-	3	-	-	-	3	3	3	-	3	-	2	-	1	-

AMI	E301 BASIC CIVIL AN	D MECHA	NICAL LABOI	RATO	RY		
Programme & Branch	BE & MECH	Sem.	Category	L	T	P	C
	1	2	ES	0	0	4	2
Preamble	To provide exposure to the students with hands on experience on basic engineering practices in Civil, and Mechanical Engineering						

#### LIST OF EXPERIMENTS

#### I CIVIL ENGINEERING PRACTICE

#### **Buildings:**

Study of plumbing and carpentry components of residential and industrial buildings. Safety aspects.

### 1.Plumbing Works:

- (a) Study of pipeline joints, its location and functions: valves, taps, couplings, unions, reducers, elbows in household fittings.
- (b) Study of pipe connections requirements for pumps and turbines.
- (c) Preparation of plumbing line sketches for water supply and sewage works.
- (d) Hands-on-exercise: Basic pipe connections Mixed pipe material connection Pipe connections with different joining components.
- (e) Demonstration of plumbing requirements of high-rise buildings.

### 2. Carpentry using Power Tools only:

- (a) Study of the joints in roofs, doors, windows and furniture.
- (b) Hands-on-exercise:

Wood work, joints by sawing, planning and cutting

### II MECHANICAL ENGINEERING PRACTICE

#### 1.Welding:

- (a) Preparation of arc welding of butt joints, lap joints and tee joints.
- (b) Gas welding practice

#### 2.Basic Machining:

- (a) Simple Facing, Turning and Taper turning
- (b) Drilling Practice

### 3.Sheet Metal Work:

- (a) Forming & Bending:
- (b) Model making Trays, funnels, etc.
- (c) Different type of joints.

#### 4. Machine assembly practice:

- (a) Study of centrifugal pump
- (b) Study of air conditioner

#### **5.Demonstration on:**

- (a) Smithy operations, upsetting, swaging, setting down and bending. Example Exercise Production of hexagonal headed bolt.
- (b) Foundry operations like mould preparation for gear and step cone pulley.
- (c) Fitting Exercises Preparation of square fitting and vee fitting models.

		Total: 60
COURSEOU'		Bloom's Taxonomy Level
CO1	Fabricate carpentry components and pipe connections including plumbing works.	K3
CO2	Use welding equipments to join the structures.	К3
CO3	Carry out the basic machining operations.	К3
CO4	Make the models using sheet metal works.	К3
CO5	Illustrate on centrifugal pump, Air conditioner, operations of smithy, foundry and fittings.	K3

							*****								
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2			1	1	1					2	2	1	1
CO2	3	2			1	1	1					2	2	1	1
CO3	3	2			1	1	1					2	2	1	1
CO4	3	2			1	1	1					2	2	1	1
CO5	3	2		,	1	1	1					2	2	1	1

	ACS302 CLOUD COMP	UTING LA	ABUKATURY					
Programme & Branch	BE & MECH	Sem.	Category	L	Т	P	С	
	COUDE	2	ES	0	0	4	2	
Preamble  To learn the basics and types of Virtualization  To understand the Hypervisors and its types  To Explore the Virtualization Solutions  To Experiment the virtualization platforms								

- 1. Create type 2 virtualization in VMWARE or any equivalent Open Source Tool. Allocate memory and storage space as per requirement. Install Guest OS on that VMWARE.
- 2. Find a procedure for the following
  - a. Shrink and extend virtual disk
  - b. Create, Manage, Configure and schedule snapshots
  - c. Create Spanned, Mirrored and Striped volume
  - d. Create RAID 5 volume
- 3. Desktop Virtualization using VNC and Chrome Remote Desktop

- 4. Create type 2 virtualization on ESXI 6.5 server
- 5. Create a VLAN in CISCO packet tracer
- 6. Install KVM in Linux
- 7. Create Nested Virtual Machine (VM under another VM)
- 8. Install a C compiler in the virtual machine created using a virtual box and execute Simple Programs
- 9. Install Google App Engine. Create a hello world app and other simple web applications using python/java.

10. Find a procedure to transfer the files from one virtual machine to another virtual machine

**Total: 60** 

COURSEOU' At the end of	ΓCOMES: the course, learners will be able to	Bloom's Taxonomy Level
CO1	Analyze the virtualization concepts and Hypervisor	K3
CO2	Apply the Virtualization for real-world applications	К3
CO3	Install & configure the different VM platforms	К3
CO4	Experiment with the VM with various software	К3

	PO1	PO2	PO3	PO4	PO5	PO6	PO1	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	3	1	- <	-		2	3	1	2	3	3	3
CO2	2	2	2	3	3	-	-		1	2	2	3	1	1	3
CO3	3	3	3	3	3		_ <del>_</del>		2	1	Ø 1	2	2	1	3
CO4	3	3	1	1	1	0,-			1	3	1	3	2	1	1
CO5	3	2	2	2	3	8	0	0 <u>1</u> _1	2	3	2	2	2	3	3





AME103 - ENGINEERING THERMODYNAMICS										
Programme	BE & MECH	Sem.	Category	L	T	P	С			
& Branch			<i>.</i>							
		3	PC	3	0	0	3			
Preamble	➤ Impart knowledge on the	he basic	es and application	of ze	eroth	and	first law of			
	thermodynamics.									
	> Impart knowledge on the second law of thermodynamics in analysing the									
	performance of thermal devices.									
	➤ Impart knowledge on availability and applications of second law of									
	thermodynamics.									
	Teach the various propert	ties of st	eam through steam	tables	and	Moll	ier chart.			
	> Impart knowledge on the macroscopic properties of ideal and real gases.									
Unit 1 BASICS, ZEROTH AND FIRST LAW 9										
Review of Bas	ics – Thermodynamic systems,	Propert	ies and processes T	hermo	odyna	mic	Equilibrium			
Displacement	work - P-V diagram. Thermal	equilibri	um - Zeroth law -	- Conc	ept c	of ten	nperature an			
Temperature S	cales. First law – application t	o closed	l and open systems	s – ste	ady a	and u	insteady flow			
processes.										
Unit 2	SECOND LAW AND AVAIL	ABILI	ΓYANALYSIS				9			
Heat Reservoir	, source and sink. Heat Engine,	Refrige	rator, Heat pump. S	econd	law a	and it	s corollaries			
Clausius inequ	ality - Concept of entropy, T	-s diagr	am, Tds Equations	s, entr	opy	chang	ge for - pur			
substance, idea	al gases - different processes, p	rinciple	of increase in entr	ору	Appli	catio	ns of II Law			
Available and 1	non-available energy of a source	and fini	te body. Energy and	irreve	rsibi	lity -	Irreversibilit			
I and II law Ef	ficiency.									
Unit 3	PROPERTIES OF PURE SU	JBSTAN	NCE AND STEAM	I			9			
	POWER CYCLE	<u>/ a, </u>	.00							
	team and its thermodynamic pr	_			_	_				
Use of Steam 7	Table and Mollier Chart. Determ	ination o	of dryness fraction.	Applic	catior	of I	and II law fo			
pure substanc	es. Ideal and actual Rankine	cycles.	Cycle Improvem	nent N	<b>leth</b> c	ds -	Reheat and			
	ycles, Economizer, preheater, B	inary an	d Combined cycle.							
Unit 4	IDEAL AND REAL GASES,	THEM	IODYNAMIC				9			
	RELATIONS	o TD O	011							
		3 1 1 1 7	44 F C	_						
•	leal gas - Equations of state for i			-	•		•			
factor - Princi	leal gas - Equations of state for it ple of Corresponding states - G Equations, Difference and rati	eneralis	ed Compressibility	Chart	and	its u	se - Maxwe			

Coefficient, Clausius Clapeyron equation, Phase Change Processes. Simple Calculations.

#### Unit 5 GAS MIXTURES AND PSYCHROMETRY

Mole and Mass fraction, Dalton's and Amagat's Law. Properties of gas mixture - Molar mass, gas constant, density, change in internal energy, enthalpy, entropy and Gibbs function. Psychrometric terms - Psychrometric properties - Psychrometric charts. Property calculations of air vapour mixtures by using chart and expressions. Psychrometric process – cooling load calculations - simple Applications

**Total: 45** 

#### **TEXTBOOKS**

1	Nag.P.K., "Engineering Thermodynamics", 6th Edition, Tata McGraw Hill, 2017.
2	R.K.Rajput, "A Text Book Of Engineering Thermodynamics", 5th Edition, 2017.
3	Rathakrishnan, E, "Fundamentals of Engineering Thermodynamics", 2nd Edition, Prentice
	Hall of India Pvt Ltd, 2006.
4	Venkatesh A, "Basic Engineering Thermodynamics", Universities Press (India) Limited, 2007.
REFERI	ENCES
1	Cengel, Y and M. Boles, Thermodynamics - An Engineering Approach, Tata McGraw Hill,9th
	Edition, 2019.
2	Chattopadhyay, P, "Engineering Thermodynamics", 2nd Edition Oxford University Press,
	2016.
3	Claus Borgnakke and Richard E. Sonntag, "Fundamentals of Thermodynamics", 10th Edition,
	Wiley Eastern, 2019.
4	Michael J. Moran, Howard N. Shapiro, "Fundamentals of Engineering Thermodynamics", 8th
	Edition, 2014.

	INSTITUTE OF TEPUNDING OF	
COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Apply the zeroth and first law of thermodynamics by formulating	К3
	temperature scales and calculating the property changes in closed	
	and open engineering systems.	
CO2	Apply the second law of thermodynamics in analysing the	K3
	performance of thermal devices through energy and entropy	
	calculations.	
CO3	Apply the second law of thermodynamics in evaluating the	К3
	various properties of steam through steam tables and Mollier	
	chart.	
CO4	Apply the properties of pure substance in computing the	K3
	macroscopic properties of ideal and real gases using gas laws and	
	appropriate thermodynamic relations.	
CO5	Apply the properties of gas mixtures in calculating the properties	К3
	of gas mixtures and applying various thermodynamic relations to	
	calculate property changes.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	1								2			
CO2	3	3	2	1								2			
CO3	3	3	2	1					1		1	2	3		3
CO4	3	3	2	1		1			2		1	2	3	2	
CO5	3	3	2	1		1			2		1	2	3	2	3

		AME104 - FLUID	MECHANIC	CS AND MACHI	NERY	7		
Programi & Branc		BE & MECH	Sem.	Category	L	T	P	C
			3	PC	3	0	0	3
Variation in  Unit 2  Fluid Kine  Velocity ar	FLUI n - propertic a static flu FLUI matics: Intro	To introduce the st static conditions. To impart basic kn To expose to the a b) flow through pi To expose the student of design Pelto To impart a knowled by PROPERTIES A es of fluids - Types o id, absolute, gauge, D KINEMATICS A coduction - Lagrangia ion in a flow field - duction - Equation	owledge of the applications of pes (laminar adents to basic on wheel, Francedge about certain fluid flows atmospheric & AND DYNAM an and Euleria Potential and s	dynamics of fluid the conservation and turbulent) and principles of work the sand Kaplan tuntrifugal and reciparation. Fluid pressure at a vacuum pressure at a principles of the vacuum pressure at a proposed for fluid stream function.	laws to c) force sing of rbine. procating point ess.	bound bound bo a) fi ces or f hyd ng pu - Paso w - C	our of dary low raulications.	f fluids under ayer concept. neasurements be bends. machineries  8 law - pressure  9 nuity equation
Pitot tube. Unit 3	Flow throug	ntal - Euler's equati gh Pipes - Major & E ENSIONAL ANAL	Minor losses i	n pipe flow - Num DUNDARY LAY	nerical ERS	exer	cise.	9
laws - Unit	Quantities	ional homogeneity and Specific quanti dary layer thickness	ties, introducti					
Unit 4		RAULIC TURBIN	VA.	Sell				10
Performane Unit 5	e of hydrau PUM	on - Classification on the control of the control o	and specific q	uantities - turbine	gover	ning.		9
in series ar	d parallel -	performance charac	cteristic curves	- discharge, slip.				
TEXTBO	OKS		F010- 70					Total: 45
	Iouse, New	and Seth, S.M. "Hy	draulics and F	Fluid Mechanics",	23 <sup>rd</sup> I	Editio	on, St	andard Book
DD	ICES	Denn 2019.						
REFEREN								4
1 5	treeter, V. 1	L. and Wylie E. B.,	"Fluid Mecha	nics", McGraw H	ill Put	olishi	ng Co	o, 9 <sup>th</sup> Edition,
1 5 2 1	017.							
1 S	017. Kumar K. L 006	L. and Wylie E. B.,	d Mechanics",	Eurasia Publishii	ng Hou	ıse P	vt Lto	

COURS	E OUTCOMES:	Bloom's Taxonomy
At the e	nd of the course, learners will be able to	Level
CO1	Understand the properties and behaviour in static conditions.	K2
	Also, to understand the conservation laws applicable to fluids and	
	its application through fluid kinematics and dynamics.	
CO2	Estimate losses in pipelines for both laminar and turbulent	К3
	conditions and analysis of pipes connected in series and parallel.	
	Also, to understand the concept of boundary layer and its	
	thickness on the flat solid surface.	
CO3	Formulate the relationship among the parameters involved in the	K2
	given fluid phenomenon and to predict the performances of	
	prototype by model studies.	
CO4	Explain the working principles of various turbines and design the	K2
	various types of turbines.	
CO5	Explain the working principles of centrifugal, reciprocating and	K2
	rotary pumps and design the centrifugal and reciprocating pumps.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	1	2	2	1	2	1	1	2	3	2	3
CO2	3	3	3	2	<b>×</b> 1	2	2	1	2	1	X1-	2	3	2	3
CO3	3	3	3	3	<u>.1</u>	2	2		2	1	1	2	3	3	3
CO4	3	3	3	3	1	2	2		2	1 0	1	3	3	2	2
CO5	3	3	3	3	1	2	2	<u>_1</u>	2	1	1	3	3	2	2

	AME105 - STRI	ENGTH	OF	MATERIA	ALS						
Programme	BE & MECH	Sem.	bu	Category	$\mathbf{L}$	T	P	C			
& Branch	< \ Jii	TD C	044								
		3	UII	PC	3	0	0	3			
Preamble	<ul> <li>To understand the conconstants.</li> <li>To understand the princon and deformations induced and deformation and d</li></ul>	cipal stroced in the shearing their and their and deformance the shear and deformance the shear and shear	esses nin ar g for effe orma	and princip nd thick she ce and bend ct on stress tion in circ	pal planes ells. ding mom ses. ular shaft	and t ent d	o stuc ue to c	ly the stresses external loads cal spring due			
Unit 1	STRESS AND STRAIN			·				9			

Introduction, Properties of materials, Stress, Strain and Hooke's law, Stress strain diagram for brittle and ductile materials, True stress and strain, Shear stress and strain, Lateral strain and Poisson's ratio, Elastic constants and relations between them. Calculation of stresses in straight, Stepped and tapered sections, Composite sections, Stresses due to temperature change.

#### Unit 2 **ANALYSIS OF STRESS AND STRAIN**

Compound Stresses: Principal stresses and maximum shear stress, Planes of Principal stress and Maximum Shear stress, Normal stress on the planes of maximum shear stress, Mohr's circle for plane stress conditions. Cylinders: Thin cylinder: Hoop's stress, maximum shear stress, circumferential and longitudinal strains, thin spherical Shell, thin cylinder with spherical ends. Thick cylinders: Lame's theory.

#### Unit 3 SHEAR FORCES AND BENDING MOMENT

Shear Forces and Bending Moments: Type of beams, Loads and reactions, Relationship between loads, Shear force and bending moments of cantilever, simply supported and overhanging beams subjected to concentrated loads and uniformly distributed constant / varying loads. Stress in Beams: Bending Theory, Bending and shear stress distribution in rectangular, I and T section beams.

#### Unit 4 **TORSION**

Torsion formulation stresses and deformation in circular and hollows shafts – Stepped shafts – Deflection in shafts fixed at the both ends – Stresses in helical springs – Deflection of helical springs, carriage springs.

#### Unit 5 STRAIN ENERGY

Strain Energy Strain Energy: Strain energy due to axial, shear, bending, torsion and impact load, Castigliano's theorem and their applications.

Theories of Failure: Introduction, maximum principal stress theory, Maximum shearing stress theory, maximum principal strain theory, Maximum Strain energy theory and Maximum Shear Strain Energy Theory.

Total: 45

#### **TEXTBOOKS**

- 1 Bansal, R.K., "Strength of Materials", Laxmi Publications (P) Ltd., 2011 2
  - Jindal U.C., "Strength of Materials", Asian Books Pvt. Ltd., New Delhi, 2012.

#### REFERENCES

- Egor. P.Popov "Engineering Mechanics of Solids" Prentice Hall of India, New Delhi, 2001 Subramanian R., "Strength of Materials", Oxford University Press, Oxford Higher Education 2
  - Series, 2<sup>nd</sup> edition, 2010. Hibbeler, R.C., "Mechanics of Materials", Pearson Education, 10th Edition, 2022. 3
  - Ferdinand P. Been, Russell Johnson, J.r. and John J. Dewole "Mechanics of Materials", Tata McGraw Hill Publishing 'co. Ltd., New Delhi, 5th Edition, 2009.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Calculate stress and strain for different geometries under different	K2
	loading conditions.	
CO2	Calculate the stresses and strains associated with thin and thick	K2
	cylindrical pressure vessels under axial and circumferential loads.	

CO3	Construct shear force and bending moment diagrams for statically	К3
	determinate beams.	
CO4	Calculate the shear stress for bodies subjected to torsion and	K2
	bending stresses for columns.	
CO5	Discuss theories of failure as applied to materials.	K2

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3
CO2	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3
CO3	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3
CO4	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3
CO5	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3

	AME106 - MANUFACTURING PROCESSES										
Programme	BE & MECH	Sem.		Categor	y L	T	P	С			
& Branch											
		3		PC	3	0	0	3			
Preamble	> To illustrate the working	ng princi	ples	of various	metal cas	ting p	roces	sses.			
	To learn and apply the working principles of various metal joining processes.										
	To analyse the working principles of bulk deformation of metals.										
	To learn the working principles of sheet metal forming process.										
	To study and practice t	he work	ing p	rinciples	of plastics	mold	ing.				
Unit 1	CASTING PROCESS	· A:	ine	5				9			

Casting- Introduction, Advantages and applications; Principle of casting processes – Sand casting, Centrifugal casting, pressure die casting, Investment casting, stir casting, solidification of casting, Gating-Principles, requirements and types, Riser – Function, types, design, Defects in castings. Patterns – Types, making, materials and allowances.

#### Unit 2 METAL FORMING 9

Hot working & cold working, plastic deformation, yield criteria, strain hardening, recovery, recrystallization and grain growth. Rolling types & process, drawing types, sheet forming types & process, Extrusion process types, Forging Processes, classification & types- Power forging, Impression die forging, press forging, upset forging, defects in forging.

#### Unit 3 WELDING PROCESS 9

Welding process: Classification, morphology of fusion weld, working principle, Fusion welding: Arc welding- Gas Metal Arc Welding (MIG), Gas Tungsten Arc Welding (TIG), Shielded Metal Arc Welding (SMAW), plasma arc welding, oxyfuel gas welding, Resistance welding- spot, seam, projection, Solid state welding: Friction, friction stir welding, ultrasonic welding, forge welding, electromagnetic pulse welding, hot isostatic pressure welding, Laser welding, Electron beam welding, thermit welding.

Unit 4	PROCESSING OF PLASTICS	9

Classification of Polymers, Forms of raw plastic material, Types and characteristics of plastics, methods of processing plastics, moulding of thermoplastics – working principles and applications, compression moulding, Transfer Moulding, blow moulding, rotational moulding, Film blowing, Thermoforming.

Unit 5 SHEET METAL PROCESSES	
------------------------------	--

9

Sheet metal characteristics – shearing, bending and drawing operations – Stretch forming operations – Formability of sheet metal – Test methods –special forming processes-Working principle and applications – Hydro forming – Rubber pad forming – Metal spinning – Introduction of Explosive forming, magnetic pulse forming, peen forming, Super plastic forming – Micro forming.

**Total: 45** 

#### **TEXTBOOKS**

- Hajra Chouldhary S.K and Hajra Choudhury. AK., "Elements of workshop Technology", volume I and II, Media promoters and Publishers Private Limited, Mumbai, 2008
- 2 Kalpakjian. S, "Manufacturing Engineering and Technology", Pearson Education India Edition, 7<sup>th</sup> edition, 2018.

#### REFERENCES

- Gowri P. Hariharan, A.Suresh Babu, "Manufacturing Technology I", Pearson Education, 2008.

  Paul Degarma E, Black J.T and Ronald A. Kosher, "Materials and Processes, in
- Paul Degarma E, Black J.T and Ronald A. Kosher, "Materials and Processes, in Manufacturing" Eight Edition, Prentice Hall of India, 2007.
- Rao, P.N. "Manufacturing Technology Foundry, Forming and Welding", 4<sup>th</sup> Edition, TMH 2013
- 4 Roy. A. Lindberg, "Processes and Materials of Manufacture", PHI / Pearson education, 2006
- 5 Sharma, P.C., "A Text book of production Technology", S.Chand and Co. Ltd., Imprint, 2022.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Explain different metal casting processes, associated defects, merits and demerits.	K2
CO2	Compare different metal joining processes.	K2
CO3	Explain various welding processes.	K2
CO4	Distinguish various methods of manufacturing plastic components.	K2
CO5	Explain various sheet metal making processes.	K2

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3		2			2	3	1	1			1	3	1	2
CO2	3		2			2	3	1	1			1	3	1	2
CO3	3		2			2	2	1	1			1	3	1	2
CO4	3		2			2	2	1	1			1	3	1	2
CO5	3		2		2	2	2	1	1			1	3	1	2

AMC104 - ENVIRONMENTAL ENGINEERING AND SUSTAINABILITY										
Programme &	BE& MECH	Sem.	Category	L	T	P	C			
Branch	DEC MECH	Sciii.	Category	L	1	1				
		3	MC	2	0	0	0			
	> To introduce the	basic	concepts of envir	onm	ent,	ecos	ystems and			
	biodiversity and emphasize on the biodiversity of India and its conservation.									
	➤ To impart knowledge on the causes, effects and control or prevention measures of environmental pollution and natural disasters.									
	To facilitate the						scenario of			
			ble resources, cause							
Duo o mala lo				01	tiloi	acs	radation and			
Preamble	measures to preserve them.  To familiarize the concept of sustainable development goals and									
			ndence of economic							
	THE INCLUSE I	IL ILI7UN	nd analyze climate c				_			
			of environmental ma				1			
		_	sustainability practi	_			op a broader			
			aterials, energy cyc				_			
	sustainable urbani		, 2, 3			J				
Unit 1	ENVIRONMENT AND	RIOD	VFDSITV				6			
	mportance of environment			. E	20.61	ratam	-			
	ssion. Types of biodiversity									
=	mega-diversity nation – hot									
=	dlife, man-wildlife conflic						=			
= =	ersity: In-situ and ex-situ.				· · · I					
Unit 2	ENVIRONMENTAL PO	LLUT	ION				6			
Causes, Effects and Pre	eventive measures of Water,	Soil, A	ir and Noise Pollution	ons.	Soli	d, Ha	zardous and			
E-Waste management.	Case studies on Occur	oational	Health and Safe	ety	Man	agen	nent system			
(OHASMS). Environm	ental protection, Environme	ental pr	otection acts.	•			·			
Unit 3	RENEWABLE SOURC	ES OF	ENERGY				6			
Energy management ar	nd conservation, New Energ	gy Sour	ces: Need of new s	ourc	es. I	Diffe	ent types of			
new energy sources.	Applications of- Hydroge	en ener	gy, Ocean energy	res	ource	es, T	idal energy			
conversion. Concept, o	rigin and power plants of ge	eotherm	al energy.							
Unit 4	SUSTAINABILITY AND	D MAN	AGEMENT				6			
_	ustainability- concept, nee		•				-			
<u> </u>	sustainability to sustainabi	=	<del>-</del>		_		_			
=	ent Goals-targets, indicato						_			
_	ironmental issues and possi			Cond	cept o	of Ca	rbon Credit,			
	ronmental management in i									
Unit 5	SUSTAINABILITY PRA						6			
	ncept, Circular economy,					•				
Havironmental Impact	Assessment. Sustainable	habitat:	Green huildings	( tre	en n	nater	iale Energy			

efficiency, Sustainable transports. Sustainable energy: Non-conventional Sources, Energy Cycles - carbon cycle, emission and sequestration, Green Engineering: Sustainable urbanization- Socio economic and technological change.

		Total: 30						
TEXTBOOKS								
1	Anubha Kaushik and C. P. Kaushik's "Perspectives in En	vironmental Studies", 6th						
	Edition, New Age International Publishers ,2018.							
2	Benny Joseph, 'Environmental Science and Engineering',	Tata McGraw-Hill, New						
	Delhi, 2016.							
3	Gilbert M.Masters, 'Introduction to Environmental Engin	eering and Science', 2nd						
	edition, Pearson Education, 2004.							
4	Allen, D. T. and Shonnard, D. R., Sustainability Engineeri	ng: Concepts, Design and						
	Case Studies, Prentice Hall.							
5	Bradley. A.S; Adebayo, A.O., Maria, P. Engineering and	oplications in sustainable						
	design and development, Cengage learning.							
6	Environment Impact Assessment Guidelines, Notification	of Government of India,						
	2006.							
7	Mackenthun, K.M., Basic Concepts in Environment	al Management, Lewis						
	Publication, London, 1998.							
REFERENCES	S							
1	R.K. Trivedi, 'Handbook of Environmental Laws, Rules,	Guidelines, Compliances						
	and Standards', Vol. I and II, Enviro Media. 38. Edition 20	10.						
2	Cunningham, W.P. Cooper, T.H. Gorhani, 'Environmental E	Encyclopedia', Jaico Publ.,						
	House, Mumbai, 2001.	House, Mumbai, 2001.						
3	Dharmendra S. Sengar, 'Environmental law', Prentice hall	of India PVT. LTD, New						
	Delhi, 2007.							
4	Rajagopalan, R, 'Environmental Studies-From Crisis to	Cure', Oxford University						
	Press, Third Edition, 2015.	·						
5	Erach Bharucha "Textbook of Environmental Studies for	Undergraduate Courses"						
	Orient Blackswan Pvt. Ltd. 2013.	-						
	✓ CRIPENUIVIDUUID /							
COURSEOUT	COMES:	Bloom's Taxonomy						
At the end of th	ne course, learners will be able to	Level						
CO1	To recognize and understand the functions of environment,	K2						
	ecosystems and biodiversity and their conservation.							
CO2	To identify the causes, effects of environmental pollution	K2						
	and natural disasters and contribute to the preventive							
	measures in the society.							
CO3	To identify and apply the understanding of renewable and	K2						
	non-renewable resources and contribute to the sustainable							
CO4	measures to preserve them for future generations.	K2						
CO4	To recognize the different goals of sustainable development and apply them for suitable technological	<b>N</b> ∠						
	advancement and societal development.							

CO5	To demonstrate the knowledge of sustainability practices	K2
	and identify green materials, energy cycles and the role of	
	sustainable urbanization.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1				2	3					2			
CO2	3	2				3	3					2			
CO3	3		1			2	2					2			
CO4	3	2	1	1		2	2					2			
CO5	3	2	1			2	2					1			

A	AME302 - FLUID MECHANICS AND MACHINERY LABORATORY								
	INSTITUTE OF TECHNOLOGY								
Programme	BE & MECH	Sem.	Catego	ry L	T	P	C		
& Branch									
		3	PC	0	0	4	2		
Preamble	Upon Completion of this subj	ect, the s	students can b	e able to ha	ve ha	ands	on experience		
	in flow measurements using	different	devices and	also perfori	n cal	lculat	ion related to		
	losses in pipes and also perform characteristic study of pumps, turbines etc.,								

#### LIST OF EXPERIMENTS

- 1. Determination of the Coefficient of discharge of given Orifice meter.
- 2. Determination of the Coefficient of discharge of given Venturi meter.
- 3. Calculation of the rate of flow using Rota meter.
- 4. Determination of friction factor for a given set of pipes.
- 5. Conducting experiments and drawing the characteristic curves of centrifugal pump/ submergible pump
- 6. Conducting experiments and drawing the characteristic curves of reciprocating pump.
- 7. Conducting experiments and drawing the characteristic curves of Gear pump.
- 8. Conducting experiments and drawing the characteristic curves of Pelton wheel.
- 9. Conducting experiments and drawing the characteristics curves of Francis turbine.
- 10. Conducting experiments and drawing the characteristic curves of Kaplan turbine.

Total: 60

COURS	E OUTCOMES:	Bloom's Taxonomy				
At the en	nd of the course, learners will be able to	Level				
CO1	Ability to use measurement equipment for flow measurement.	K2				
CO2	Analyze the coefficient of discharge in the orifice meter, venturi meter and rotameter.	K3				
CO3	Visualize the flow net and verify the 57ernoulli's equation.	K2				

CO4	Determine the losses in flow through pipes	K2
CO5	Analyze the performance characteristic curves of turbines and	K3
	pumps	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1		2			2							2	2	
COI	1														
CO2	1		2		2	2							2	2	
CO3	2		2	1							2		2	2	
	_		_	-							_		_	_	
CO4	3		2	3			2				2	2	2	2	
CO5	2		2	1	2								2	2	
COS	2		3	1	2								2	2	





	AME107 - 1	THEORY O	F MACHINES				
Programme & Branch	BE & MECH	Sem.	Category	L	T	P	C
		4	PC	3	0	0	3
Preamble  Unit 1	<ul> <li>To understand the basystem machine.</li> <li>To understand the particle displacement, velocities.</li> <li>To understand the formula forces and analysis of the fo</li></ul>	principles in ty, and accel rce-motion rof standard nondesirable esm.	ents and layout of analysing the a eration at any point elationship in connechanisms.  If a connection of the connection	ssemb nt in a nponer ces res	ges in ly w link its su sultin	the a ith re of a re bjector g fro	espect to the mechanism. ed to external m prescribed
	Terminology and definition		of fundom Cu	ıhlan'a			
inversions of 4 motion Mecha	bar and slide crank chain – nisms - Straight line motion niversal Hooke's Joint.	kinematics	analysis in simpl	e mecl	nanis	ms -	Quick return
Unit 2	KINEMATICS OF LINKA	AGE MECH	IANISM				9
	on of particles in a common	link and co	oincident Particle	s on s	epara	ate li	nks- Coriolis
Analysis of vel	acceleration. Velocity Analystocity and acceleration of sing		taneous Center M	1ethod	. Kle		Construction:
Analysis of vel Unit 3	FORCE ANALYSIS	gle slider cra	taneous Center M nk mechanism.			in's (	Construction: 9
Analysis of veluant 3  Dynamic force in reciprocating	ocity and acceleration of sing	nertia torque	taneous Center Mark mechanism.	princip	ole –	in's (	Construction:  9 mic Analysis
Analysis of veluant 3  Dynamic force in reciprocating	FORCE ANALYSIS  analysis – Inertia force and I g engines – Gas forces – Ine	nertia torque rtia effect of neels.	taneous Center Mark mechanism.	princip	ole –	in's (	Construction:  9 mic Analysis
Analysis of veluation  Unit 3  Dynamic force in reciprocating torque – Turning  Unit 4  Static and Dynamic – free vibration	FORCE ANALYSIS  analysis – Inertia force and I g engines – Gas forces – Ine g moment diagrams –Fly Wh	nertia torque rtia effect of neels. TON of revolving a ural Frequen	taneous Center Mark mechanism.  e – D Alembert's connecting rodund reciprocating cy – Damped Vib	princip Beari masses	ole – ng lo	Dyna  oads -	9 mic Analysis - Crank shaft 9 ing machines
Analysis of veluation  Unit 3  Dynamic force in reciprocating torque – Turning  Unit 4  Static and Dynamic – free vibration	FORCE ANALYSIS  analysis – Inertia force and I g engines – Gas forces – Ine g moment diagrams –Fly Wh BALANCING & VIBRAT amic balancing – Balancing o s – Equations of motion – nature	nertia torque rtia effect of neels. TON of revolving a ural Frequen	taneous Center Mark mechanism.  e – D Alembert's connecting rodund reciprocating cy – Damped Vib	princip Beari masses	ole – ng lo	Dyna  oads -	9 mic Analysis - Crank shaft 9 ing machines
Analysis of veluation  Unit 3  Dynamic force in reciprocating torque – Turning  Unit 4  Static and Dynamic free vibration of simple shaft Unit 5  Cams and follor Governors: Type Gyroscopic controls of the state of	FORCE ANALYSIS  analysis – Inertia force and I g engines – Gas forces – Ine g moment diagrams –Fly Wh BALANCING & VIBRAT amic balancing – Balancing o s – Equations of motion – nate – Torsional vibration – Force MECHANISMS  wers. Development of cam proces – characteristics - force and pole, effect of gyroscopic countered in the content of the content	nertia torque ritia effect of neels.  TON  f revolving a ural Frequence vibration -	taneous Center Mark mechanism.  e – D Alembert's fronnecting rod- and reciprocating cy – Damped Vib – harmonic Forcing ious types of folloscope: Vector representations.	masses ration of the powers a resenta	ole – ng lo s – Ba – ben  and it	Dyna  pads -  alanc  ding  s diff  of an	mic Analysis Crank shaft  9 ing machines critical speed  9 erent motion. gular motion.
Analysis of veluation  Unit 3  Dynamic force in reciprocating torque – Turning  Unit 4  Static and Dynamic free vibration of simple shaft Unit 5  Cams and follor Governors: Type Gyroscopic controls of the state of	FORCE ANALYSIS  analysis – Inertia force and I g engines – Gas forces – Ine g moment diagrams –Fly Wh BALANCING & VIBRAT amic balancing – Balancing o s – Equations of motion – nate – Torsional vibration – Force MECHANISMS wers. Development of cam proces – characteristics - force and	nertia torque ritia effect of neels.  TON  f revolving a ural Frequence vibration -	taneous Center Mark mechanism.  e – D Alembert's fronnecting rod- and reciprocating cy – Damped Vib – harmonic Forcing ious types of folloscope: Vector representations.	masses ration of the powers a resenta	ole – ng lo s – Ba – ben  and it	Dyna  pads -  alanc  ding  s diff  of an	mic Analysis Crank shaft  9 ing machines critical speed  9 erent motion. gular motion.
Analysis of veluation  Unit 3  Dynamic force in reciprocating torque – Turning  Unit 4  Static and Dynamic free vibration of simple shaft Unit 5  Cams and follor Governors: Type Gyroscopic controls of the state of	FORCE ANALYSIS  analysis – Inertia force and I g engines – Gas forces – Ine g moment diagrams –Fly Wh BALANCING & VIBRAT amic balancing – Balancing o s – Equations of motion – nate – Torsional vibration – Force MECHANISMS wers. Development of cam propes – characteristics - force and pole, effect of gyroscopic courgearing - epicyclic gear train.	nertia torque ritia effect of neels.  TON  f revolving a ural Frequence vibration -	taneous Center Mark mechanism.  e – D Alembert's fronnecting rod- and reciprocating cy – Damped Vib – harmonic Forcing ious types of folloscope: Vector representations.	masses ration of the powers a resenta	ole – ng lo s – Ba – ben  and it	Dyna  pads -  alanc  ding  s diff  of an	mic Analysis Crank shaft  9 ing machines critical speed  9 erent motion. gular motion. Gear trains –
Analysis of veluated Unit 3  Dynamic force in reciprocating torque – Turning Unit 4  Static and Dynamic free vibration of simple shaft Unit 5  Cams and follo Governors: Type Gyroscopic conclaw of toothed  TEXTBOOKS  1 F. B	FORCE ANALYSIS  analysis – Inertia force and I g engines – Gas forces – Ine g moment diagrams –Fly Wh BALANCING & VIBRAT amic balancing – Balancing o s – Equations of motion – nate – Torsional vibration – Force MECHANISMS wers. Development of cam propes – characteristics - force and pole, effect of gyroscopic courgearing - epicyclic gear train.	nertia torquentia effect of neels.  TON  of revolving a ural Frequented vibration -  rofile for varialysis. Gyrouple on ship,	taneous Center Mark mechanism.  e – D Alembert's fronnecting rod— and reciprocating cy – Damped Vib—harmonic Forcing ious types of followscope: Vector repurplement of the plane disc, aero	masses ration and plane.	ole – ng lo s – Ba – ben  und it ution Gear	Dyna  pads -  alanc  ding  s diff  of an	9 mic Analysis - Crank shaft  9 ing machines critical speed  9 erent motion. gular motion. Gear trains –  Total: 45

3	Uicker, J.J., Pennock G.R and Shigley, J.E., "Theory of Machines and Mechanisms", 6th
	Edition, Oxford University Press, 2023.
REFERI	ENCES
1	Cleghorn. W. L, "Mechanisms of Machines", Oxford University Press, 2016
2	Ghosh. A and Mallick, A.K., "Theory of Mechanisms and Machines", 3 <sup>rd</sup> Edition Affiliated
	East-West Pvt. Ltd., New Delhi, 2006.
3	Rao.J.S. and Dukkipati.R.V. "Mechanisms and Machine Theory", Wiley-Eastern Ltd., New
	Delhi, 1992.
4	Robert L. Norton, "Kinematics and Dynamics of Machinery", Tata McGraw-Hill, 2017.
5	V.Ramamurthi, "Mechanics of Machines", Narosa Publishing House, 2002.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Discuss the fundamentals of various mechanisms and its	K2
	inversion.	
CO2	Perform velocity and acceleration analysis of a particle in each	K3
	system and angular velocity of rigid bodies that are in plane	
	motion.	
CO3	Solve the problems related to balancing the parts in rotating and	K4
	reciprocating systems.	
CO4	Apply the principles of balancing of masses to various systems	K4
	and engines.	
CO5	Construct the cam profile for a desired motion. Recognize the	K4
	fundamentals of governor and gyroscope.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2		2			1				1	3		1
CO2	3	2	2		2		CD	1	DIID			1	3		1
CO3	3	2	2		2	2m	1411	1	JUU	UR /		1	3		1
CO4	3	2	2		2	1	EST	]. <sup>1</sup> 2(	111	7		1	3		1
CO5	3	2	2		2			1			7	1	3		1

	AME108 - METROLOGY AND MEASUREMENTS								
Programme & Branch	BE & MECH	Sem.	Category	L	Т	P	C		
		4	PC	3	0	0	3		
Preamble  To learn basic concepts of the metrology and importance of measurements.									

- > To teach measurement of linear and angular dimensions assembly and transmission elements.
- > To study the tolerance analysis in manufacturing.
- ➤ To develop the fundamentals of GD & T and surface metrology.
- To provide the knowledge of the advanced measurements for quality control in manufacturing industries.

#### Unit 1 MEASUREMENT SYSTEMS AND PERFORMANCE

9

Introduction to Metrology – Need – Elements – Work piece, Instruments – Persons – Environment – their effect on Precision and Accuracy – Errors – Errors in Measurements – Types – Control – Types of standards.

#### Unit 2 LINEAR, ANGULAR AND FORM MEASUREMENTS

9

Linear Measuring Instruments – Vernier calliper, Micrometre, Vernier height gauge, Depth Micrometre, bore gauge, Telescoping gauge; Gauge blocks – Use and precautions, Comparators – Working and advantages; Opto-mechanical measurements using measuring microscope and Profile projector - Angular measuring instruments – Bevel protractor, Clinometer, Angle gauges, Precision level, Sine bar, Autocollimator, Angle dekkor, Alignment telescope. Measurement of Screw threads - Single element measurements – Pitch Diameter, Lead, Pitch. Measurement of Gears – purpose – Analytical measurement – Runout, Pitch variation, Tooth profile, Tooth thickness, Lead – Functional checking – Rolling gear test.

#### Unit 3 TOLERANCE ANALYSIS

9

Tolerancing—Interchangeability, Selective assembly, Tolerance representation, Terminology, Limits and Fits, Problems (using tables IS919); Design of Limit gauges, Problems. Tolerance analysis in manufacturing, Process capability, tolerance stackup, tolerance charting.

#### Unit 4 METROLOGY OF SURFACES

9

Fundamentals of GD & T- Conventional vs Geometric tolerance, Datums, Inspection of geometric deviations like straightness, flatness, roundness deviations; Simple problems – Measurement of Surface finish – Functionality of surfaces, Parameters, Comparative, Stylus based and Optical Measurement techniques, Filters, Introduction to 3D surface metrology- Parameters.

#### Unit 5 ADVANCES IN METROLOGY

9

Lasers in metrology - Advantages of lasers - Laser scan micrometers; Laser interferometers - Applications - Straightness, Alignment; Ball bar tests, Computer Aided Metrology - Basic concept of CMM - Types of CMM - Constructional features - Probes - Accessories - Software - Applications - Multi sensor CMMs. Machine Vision - Basic concepts of Machine Vision System - Elements - Applications - On-line and in process monitoring in production - Computed tomography - White light Scanners.

Total: 45

# TEXTBOOKS 1 Detsor

- Dotson Connie, "Dimensional Metrology", Cengage Learning, 6<sup>th</sup>, 2016.
- Mark Curtis, Francis T. Farago, "Handbook of Dimensional Measurement", Industrial Press, 5<sup>th</sup> edition, 2013.
- Beckwith Marangoni and Lienhard, "Mechanical Measurements", Pearson Education, 6<sup>th</sup> Edition, 2013.
- 4 R.K. Jain, "Engineering Metrology", Khanna Publishers, 22<sup>nd</sup> edition, 2022.

#### REFERENCES

1	Ammar Grous J, "Applied Metrology for Manufacturing Engineering", Wiley-ISTE, 2013.
2	Galyer, J.F.W. Charles Reginald Shot bolt, "Metrology for Engineers", Cengage Learning
	EMEA; 5th revised edition, 1990.
3	National Physical Laboratory Guide No. 40, No. 41, No. 42, No. 43, No. 80, No. 118, No. 130,
	No. 131.
4	Raghavendra N.V. and Krishnamurthy. L., Engineering Metrology and Measurements, Oxford
	University Press, 2013.
5	Venkateshan, S. P., "Mechanical Measurements", Second edition, John Wiley &Sons, 2015.

	E OUTCOMES: nd of the course, learners will be able to	Bloom's Taxonomy Level
CO1	Discuss the concepts of measurements to apply in various metrological instruments.	K2
CO2	Apply the principle and applications of linear and angular measuring instruments, assembly, and transmission elements.	K2
CO3	Apply the tolerance symbols and tolerance analysis for industrial applications.	K2
CO4	Apply the principles and methods of form and surface metrology.	K2
CO5	Apply the advances in measurements for quality control in manufacturing Industries.	K2

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2		(20)			1	11/4		1	3	2	1
CO2	3	2	2	2			elf Di	a diali	1			1	3	2	1
CO3	3	2	2	2				SCIP	1			1	3	2	1
CO4	3	2	2	2					1			1	3	2	1
CO5	3	2	2	2	1	381	EN	UIYI	1//	IR I		1	3	2	1

AME109 - CONVENTIONAL AND UNCONVENTIONAL MACHINING PROCESSES									
Programme & Branch	BE & MECH	Sem.	Category	L	T	P	С		
		4	PC	3	0	0	3		
Preamble	<ul> <li>To study the concep affecting machinabili</li> <li>To learn working of b</li> <li>To teach the basics of motions and abrasive</li> <li>To study the basic content</li> </ul>	ty pasic and ad f special pu finishing p	vanced turning m rpose machines w rocesses.	achine vith rec	es. cipro	cating	g and rotating		

TT *	To learn the concepts of unconventional machining process			
Unit 1		9		
	s of chip formation, single point cutting tool, forces in machining, Types of			
	ure, orthogonal metal cutting, thermal aspects, cutting tool materials	, tool wear, tool life,		
	ish, cutting fluids and Machinability.			
Unit 2		9		
	he, constructional features, specification, operations – taper turning me	_		
	special attachments, machining time and power estimation. Capstan a			
	utomatic lathes: semi-automatic – single spindle: Swiss type, automatic			
Unit 3		9		
_	rilling, reaming, boring, Tapping. Milling operations-types of milling			
-	ng, hobbing and gear shaping processes. Abrasive processes: grinding v	-		
and selection	on, types of grinding process-cylindrical, surface, centreless and interna-	al grinding. Broaching		
machines:	broach construction – push, pull, surface & continuous machines.	<del></del>		
Unit 4		9		
_	Numerical Control machine tools, construction, special features – Driv	<del>-</del>		
screws, too	ol changers; Control systems - Turning and machining centres - We	ork holding methods		
Coolant sy	ystems - Coordinates, axis and motion, Absolute vs Incremental,	Interpolators, Pola		
coordinates	s, Program planning, G and M codes, Manual part programming – Fix	ted cycles, Loops and		
subroutines	S.			
Unit 5	UNCONVENTIONAL MACHINING PROCESSES	9		
Introduction				
muouucii0	on – Need for non-traditional machining process – Classification - Med	chanical energy based		
	on – Need for non-traditional machining process – Classification - Med Electrical based process – Chemical and electro chemical energy base	= -		
process – l		= -		
process – l	Electrical based process - Chemical and electro chemical energy base	= -		
process – l energy base	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.	ed process – Therma		
process – lenergy base	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.	ed process – Therma  Total: 45		
process – lenergy base  FEXTBOO  1 I	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS	Total: 45 Promoters 2023.		
rextbook  1 I 2 I	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media	Total: 48 Promoters 2023.		
rextraction in the process – I be pr	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To	Total: 45  Promoters 2023.  ols", 3 <sup>rd</sup> Edition, Tata		
rextbook  TEXTBOOK  1 I  2 I  N  3 J	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.	Total: 45  Promoters 2023.  ols", 3 <sup>rd</sup> Edition, Tata		
PEXTBOO  1 I 2 I 3 J	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.  Jagadeesha T, "Non-Traditional Machining Processes", I.K. Internation Pvt. Ltd., New Delhi, India, 2017.	Total: 45  Promoters 2023.  ols", 3 <sup>rd</sup> Edition, Tata		
PEXTBOO  1 I 2 I 3 J REFEREN	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.  Jagadeesha T, "Non-Traditional Machining Processes", I.K. Internatio Pvt. Ltd., New Delhi, India, 2017.  NCES	Total: 45  Promoters 2023. ols", 3 <sup>rd</sup> Edition, Tata		
PEXTBOO  1 I 2 I 3 J REFEREN 1 I	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.  Jagadeesha T, "Non-Traditional Machining Processes", I.K. Internatio Pvt. Ltd., New Delhi, India, 2017.	Total: 45  Promoters 2023. ols", 3 <sup>rd</sup> Edition, Tata		
rextbook  TEXTBOOK  1 I  2 I  N  REFEREN  1 I	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.  Jagadeesha T, "Non-Traditional Machining Processes", I.K. Internation Pvt. Ltd., New Delhi, India, 2017.  NCES  Richerd R Kibbe, John E. Neely, Roland O. Merges and Warren J. V. Practices", Prentice Hall of India, 2011.	Total: 45  Promoters 2023. ols", 3 <sup>rd</sup> Edition, Tata nal Publishing House White "Machine Too		
PEXTBOO  I I I I I I I I I I I I I I I I I I	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.  Jagadeesha T, "Non-Traditional Machining Processes", I.K. Internatio Pvt. Ltd., New Delhi, India, 2017.  NCES  Richerd R Kibbe, John E. Neely, Roland O. Merges and Warren J. V.	Total: 45  Promoters 2023. ols", 3 <sup>rd</sup> Edition, Tata nal Publishing House White "Machine Too		
TEXTBOO	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.  Jagadeesha T, "Non-Traditional Machining Processes", I.K. Internatio Pvt. Ltd., New Delhi, India, 2017.  NCES  Richerd R Kibbe, John E. Neely, Roland O. Merges and Warren J. V. Practices", Prentice Hall of India, 2011.  Geofrey Boothroyd, "Fundamentals of Metal Machining and Machine To 2005.	Total: 45  Promoters 2023. ols", 3 <sup>rd</sup> Edition, Tata nal Publishing House White "Machine Too		
PEXTBOO  I I I I I I I I I I I I I I I I I I	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.  Jagadeesha T, "Non-Traditional Machining Processes", I.K. Internatio Pvt. Ltd., New Delhi, India, 2017.  NCES  Richerd R Kibbe, John E. Neely, Roland O. Merges and Warren J. V. Practices", Prentice Hall of India, 2011.  Geofrey Boothroyd, "Fundamentals of Metal Machining and Machine To 2005.  HMT, "Production Technology", Tata McGraw Hill, 2017.	Total: 45  Promoters 2023. ols", 3 <sup>rd</sup> Edition, Tata nal Publishing House White "Machine Too Tools", Mc Graw Hill		
TEXTBOO   1	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.  Jagadeesha T, "Non-Traditional Machining Processes", I.K. Internation Pvt. Ltd., New Delhi, India, 2017.  NCES  Richerd R Kibbe, John E. Neely, Roland O. Merges and Warren J. V. Practices", Prentice Hall of India, 2011.  Geofrey Boothroyd, "Fundamentals of Metal Machining and Machine To 2005.  HMT, "Production Technology", Tata McGraw Hill, 2017.  Roy. A. Lindberg, "Process and Materials of Manufacture," Fourth	Total: 45  Promoters 2023. ols", 3 <sup>rd</sup> Edition, Tata nal Publishing House White "Machine Too Fools", Mc Graw Hill		
PEXTBOO  I I I I I I I I I I I I I I I I I I	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.  Jagadeesha T, "Non-Traditional Machining Processes", I.K. Internatio Pvt. Ltd., New Delhi, India, 2017.  NCES  Richerd R Kibbe, John E. Neely, Roland O. Merges and Warren J. V. Practices", Prentice Hall of India, 2011.  Geofrey Boothroyd, "Fundamentals of Metal Machining and Machine To 2005.  HMT, "Production Technology", Tata McGraw Hill, 2017.	Total: 45  Promoters 2023. ols", 3 <sup>rd</sup> Edition, Tata nal Publishing House White "Machine Too Tools", Mc Graw Hill		
TEXTBOO   1	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.  Jagadeesha T, "Non-Traditional Machining Processes", I.K. Internatio Pvt. Ltd., New Delhi, India, 2017.  NCES  Richerd R Kibbe, John E. Neely, Roland O. Merges and Warren J. V. Practices", Prentice Hall of India, 2011.  Geofrey Boothroyd, "Fundamentals of Metal Machining and Machine To 2005.  HMT, "Production Technology", Tata McGraw Hill, 2017.  Roy. A. Lindberg, "Process and Materials of Manufacture," Fourth Education 2015.	Total: 45  Promoters 2023.  Promoters 20		
PEXTBOO	Electrical based process – Chemical and electro chemical energy based process – equipment - effect of process parameters – applications.  OKS  Hajra Choudhury, "Elements of Workshop Technology", Vol.II., Media Rao. P.N "Manufacturing Technology – Metal Cutting and Machine To McGraw-Hill, New Delhi, 2017.  Jagadeesha T, "Non-Traditional Machining Processes", I.K. Internatio Pvt. Ltd., New Delhi, India, 2017.  NCES  Richerd R Kibbe, John E. Neely, Roland O. Merges and Warren J. V. Practices", Prentice Hall of India, 2011.  Geofrey Boothroyd, "Fundamentals of Metal Machining and Machine To 2005.  HMT, "Production Technology", Tata McGraw Hill, 2017.  Roy. A. Lindberg, "Process and Materials of Manufacture," Fourth Education 2015.	Total: 4:  Promoters 2023. ols", 3 <sup>rd</sup> Edition, Tata nal Publishing House White "Machine Too Tools", Mc Graw Hill Edition, PHI/Pearson		

CO1	Explain the mechanism of material removal processes.	K2
CO2	Describe the constructional and operational features of centre	K2
	lathe and other special purpose lathes.	
CO3	Describe the constructional and operational features of shaper,	K2
	planner, milling, drilling, sawing and broaching machines.	
CO4	Summarize numerical control of machine tools and write a part	K2
	program.	
CO5	Explain the various unconventional machining processes and the	K2
	influence of process parameters.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	1	1	1	3			3		2	3	3	2
CO2	3	3	3	1	1	11/57	3	OF TEC	HNOL	GY3		2	3	2	2
CO3	3	3	3	1	1	1	3			3		2	3	2	2
CO4	3	3	3	1	1	1	3			3		2	3	2	2
CO5	3	3	3	1	1	1	3			3		2	3	2	3

	AMA106 - STATISTICS	SAND	NUMERICAL MET	HOI	)S		
	<i>y</i> \ \						
Programme	BE & MECH	Sem.	Category	L	T	P	С
& Branch							
	The second secon	4	BS	3	1	0	4
Preamble	<ul> <li>This course aims at prand numerical method kinds of problems occu</li> <li>To acquaint the knowled which plays an importation.</li> <li>To introduce the base equations.</li> <li>To introduce the numerical techniques of role in engineering and</li> <li>To acquaint the knowledge of the control of /li></ul>	s and garring in edge of ant role conduction to the different technology when the different tech	engineering and tech testing of hypothesis in real life problems. cepts of solving algorithmiques of interpolate entiation and integration logy disciplines.	lvin nolo for s gebra ion i	g nur egy. small aic a in va	and ind trious plays	cally different large samples ranscendental intervals and s an important
Unit 1	TESTING OF HYPOTHESI	S					9+3
	ributions – Tests for single mea						•
_ ·	sts for single variance and equa	lity of	variances – Chi squar	e te	st for	goo	dness of fit –
Independence							
Unit 2	DESIGN OF EXPERIMENT	ΓS					9+3

One way and two way classifications - Completely randomized design - Randomized block design -Latin square design – 2 2 factorial design. SOLUTION OF EQUATIONS AND EIGEN VALUE Unit 3 9+3 **PROBLEMS** Solution of algebraic and transcendental equations – Fixed point iteration method – Newton Raphson method- Solution of linear system of equations – Gauss elimination method – Pivoting – Gauss Jordan method – Iterative methods of Gauss Jacobi and Gauss Seidel – Eigenvalues of a matrix by Power method and Jacobi's method for symmetric matrices. Unit 4 INTERPOLATION, NUMERICAL DIFFERENTATION 9+3 AND NUMERICAL INTEGRATION Lagrange's and Newton's divided difference interpolations – Newton's forward and backward difference interpolation - Approximation of derivates using interpolation polynomials - Numerical single and double integrations using Trapezoidal and Simpson's 1/3 rules. Unit 5 NUMERICAL SOLUTION OF ORDINARY 9+3 DIFFERENTIAL EQUATIONS Single step methods: Taylor's series method – Euler's method – Modified Euler's method – Fourth order Runge-Kutta method for solving first order differential equations – Multi step methods: Milne's and Adams – Bash forth predictor corrector methods for solving first order differential equations. Total: 60 **TEXTBOOKS** Grewal, B.S., and Grewal, J.S., "Numerical Methods in Engineering and Science", Khanna Publishers, 10<sup>th</sup> Edition, New Delhi, 2015. Johnson, R.A., Miller, I and Freund J., "Miller and Freund's Probability and Statistics for 2 Engineers", Pearson Education, Asia, 8th Edition, 2015. Gupta S.C. and Kapoor V. K., "Fundamentals of Mathematical Statistics", Sultan Chand & 3 Sons, New Delhi, 12<sup>th</sup> Edition, 2020. REFERENCES Burden, R.L and Faires, J.D, "Numerical Analysis", 9th Edition, Cengage Learning, 2016. Devore. J.L., "Probability and Statistics for Engineering and the Sciences", Cengage Learning, 2 New Delhi, 9<sup>th</sup> Edition, 2016. Gerald. C.F. and Wheatley. P.O. "Applied Numerical Analysis" Pearson Education, Asia, New 3 Delhi, 7<sup>th</sup> Edition, 2007. Spiegel. M.R., Schiller. J. and Srinivasan. R.A., "Schaum's Outlines on Probability and Statistics ", Tata McGraw Hill Edition, 4th Edition, 2012. Walpole. R.E., Myers. R.H., Myers. S.L. and Ye. K., "Probability and Statistics for Engineers 5 and Scientists", 9th Edition, Pearson Education, Asia, 2016. **COURSE OUTCOMES: Bloom's Taxonomy** Level At the end of the course, learners will be able to Apply the concept of testing of hypothesis for small and large CO<sub>1</sub> K2 samples in real life problems. Apply the basic concepts of classifications of design of CO<sub>2</sub> K3

experiments in the field of agriculture.

CO3	Appreciate the numerical techniques of interpolation in various	
	intervals and apply the numerical techniques of differentiation	K2
	and integration for engineering problems.	
CO4	Understand the knowledge of various techniques and methods for	K4
	solving first and second order ordinary differential equations.	Κ4
CO5	Solve the partial and ordinary differential equations with initial	
	and boundary conditions by using certain techniques with	K3
	engineering applications.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	1	1	1				2		2	3			
CO2	3	3	1	1	1			וונ	2	D	2	3			
CO3	3	3	1	1	1	J			2	N	2	3			
CO4	3	3	1	1	1	IN51	IIUIL	UF <u>TE</u> C	2	ωY	2	3			
CO5	3	3	1	1	1				2		2	3			

	AME110 - THE	'RMAI	FNCINFFR	ING									
	AVIETO - THE	ANVIAL	ENGINEER										
Programme	BE & MECH	Sem.	Catego	ry	L	T	P	C					
& Branch	× \												
		4_	PC		3	0	0	3					
Preamble	> To integrate the conce	epts, la	ws and meth	odologie	s fr	om 1	the fi	rst course in					
	thermodynamics into analysis of cyclic processes												
	> To apply the thermod	lynamic	concepts int	o variou	s th	nerma	al ap	plication like					
	Steam Turbines, Comp	ressors	and Refrigera	tion and	Air	cond	lition	ing.					
Unit 1	GAS POWER CYCLES	<b>P</b> ISIGILE						9					
Air standard O	otto, Diesel and Dual cycles -Ai	r standa	rd Brayton c	ycle –Ca	lcul	ation	of n	nean effective					
pressure and ai	r standard efficiency, effect of re	eheat, re	egeneration ar	d interco	oliı	ng.							
Unit 2	STEAM NOZZLES AND IN	JECTO	OR					9					
Types and Sha	pes of nozzles, Flow of steam the	hrough	nozzles, Critic	cal pressi	are	ratio	, Vari	ation of mass					
flow rate with	pressure ratio. Effect of friction.	Metasta	able flow.										
Unit 3	STEAM AND GAS TURBIN	IES						9					
Types, Impulse	and reaction principles, Velocity	y diagra	ms, Work don	e and eff	icie	ncy -	- opti	mal operating					
conditions. Mu	ulti-staging, compounding and g	governin	ig. Gas turbin	e cycle a	anal	ysis	– ope	en and closed					
cycle. Perform	nance and its improvement -	Regene	rative, Interc	ooled, F	Rehe	eated	cyc]	les and their					
combination.													
Unit 4	AIR COMPRESSOR							9					
Reciprocating	compressors, Effect of clearance	ce and	volumetric ef	ficiency.	Ad	iabat	ic, Is	othermal and					

Mechanical efficiencies, staging of reciprocating compressors, optimal stage pressure ratio, effect of

intercooling, minimum work for multistage reciprocating compressors.

Unit 5	REFRIGERATION & AIR CONDITIONING	9
Refrigerants ar	nd their desirable properties- COP - Vapor compression refrigera	tion system – Vapor
absorption refi	rigeration system – Ammonia refrigeration system – Li-Br Ref	frigeration system -
Cascaded refrig	geration system – Air conditioning – Summer, winter, year around,	window, split – Split
Airconditioning		

	Total: 45
TEXTB	OOKS
1	R. K. Rajput, "Thermal Engineering", 11 <sup>th</sup> Edition, Laxmi Publication, 2020.
2	M. Mahesh Rathore, "Thermal Engineering", Edition: 1, Mcgraw Hill edition, 2012
3	Kothandaraman.C.P, S,Domkundwar. A.V, "A course in thermal Engineering", 5th Edition,
	Dhanpat Rai & sons, 2016.
REFER	ENCES
1	Sarkar, B.K, "Thermal Engineering", Tata McGraw-Hill Publishers, 2017.
2	Ramalingam. K.K, "Thermal Engineering", SCITECH Publications (India) Pvt Ltd, 2 <sup>nd</sup>
	Edition, 2018.
3	Rudramoorthy R, "Thermal Engineering", 3 <sup>rd</sup> Edition, Tata McGraw Hill Publishers, 2017
4	Arora.C.P, "Refrigeration and Air Conditioning", 3 <sup>rd</sup> edition, Tata McGraw-Hill Publishers,
	2017.

	E OUTCOMES:	Bloom's Taxonomy
At the e	nd of the course, learners will be able to	Level
CO1	Apply thermodynamic concepts to different air standard cycles	K3
	and solve problems.	
CO2	To solve problems in steam nozzle and calculate critical pressure	K2
	ratio.	
CO3	Explain the flow in steam turbines, draw velocity diagrams, flow	K3
	in Gas turbines and solve problems.	
CO4	Analyse and acquire solutions to the problems involved in the air	K3
	compressors.	
CO5	Apply the basics of thermodynamics on Refrigeration and Air	K3
	conditioning.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1								1	2	1	
CO2	3	2	2	1								1	2	1	
CO3	3	2	2	1								1	2	1	
CO4	3	2	1	1								1	2	1	
CO5	3	2	1	1								1	2	1	

	AME303 - MACHI	NE TO	OLS LABORATOR	Y			
Programme & Branch	BE & MECH	Sem.	Category	L	T	P	C
		4	PC	0	0	4	2
Preamble	<ul> <li>To Select appropriate t</li> <li>To Study and acquire special purpose mach components in the indu</li> </ul>	knowle	edge on various bas	ic m	achii	ning	operations in

#### LIST OF EXPERIMENTS

- 1. Taper Turning and Eccentric Turning on circular parts using lathe machine.
- 2. Knurling, external and internal thread cutting on circular parts using lathe machine.
- 3. Shaping Square and Hexagonal Heads on circular parts using shaper machine.
- 4. Drilling and Reaming using vertical drilling machine.
- 5. Milling contours on plates using vertical milling machine.
- 6. Cutting spur and helical gear using milling machine.
- 7. Generating gears using gear hobbing machine.
- 8. Generating gears using gear shaping machine.
- 9. Grinding components using cylindrical and centerless grinding machine.
- 10. Grinding components using surface grinding machine.
- 11. Cutting force calculation using dynamometer in lathe & milling machine
- 12. Tool angle grinding with tool and Cutter Grinder.

**Total: 60** 

COURS	E OUTCOMES:	Bloom's Taxonomy
At the e	nd of the course, learners will be able to	Level
CO1	Demonstrate the safety precautions exercised in the mechanical	К3
	workshop.	
CO2	The students able to make the work piece as per given shape and	К3
	size using machining process such as rolling, drawing, turning,	
	shaping, drilling and milling.	
CO3	The students become make the gears using gear making machines	K3
	and analyze the defects in the cast and machined components.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3						1		2			1	1	2	2
CO2	3						1		2			1	1	2	2
CO3	3						1		2			1	1	2	2

	AME304 - STRENGT	H OF MATI	ERIALS LABOI	RATO	RY		
Programme	BE & MECH	Sem.	Category	L	T	P	C
& Branch							
		4	PC	0	0	4	2
Droomblo	To supplement the theoretic	cal knovyloda	a gained in Meel	onice	of Sc	dida	with proctical

Preamble To supplement the theoretical knowledge gained in Mechanics of Solids with practical testing for determining the strength of materials under externally applied loads.

#### LIST OF EXPERIMENTS

- 1. Tension test on a mild steel rod
- 2. Double shear test on Mild steel and Aluminium rods
- 3. Torsion test on mild steel rod
- 4. Impact test on metal specimen
- 5. Hardness test on metals Brinnell and Rockwell Hardness Number
- 6. Deflection test on beams
- 7. Compression test on helical springs
- 8. Strain Measurement using Rosette strain gauge
- 9. Effect of hardening- Improvement in hardness and impact resistance of steels.
- 10. Tempering- Improvement Mechanical properties Comparison
- (i) Unhardened specimen, (ii) Quenched Specimen and, (iii) Quenched and tempered specimen.
- 11. Microscopic Examination of (i) Hardened samples and (ii) Hardened and tempered samples.

**Total: 60** 

	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Determine the compression and hardness test on different materials.	К3
CO2	Analyze the tension and double shear test with mild steel.	K3
CO3	Apply the deflection test on various types of beams.	К3
CO4	Analyse the impact test for different materials.	K3
CO5	Determine the torsional characteristics for the given materials.	K3

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1			2		2	2							2	2	
CO2	2		1		1	2							2	1	
CO3	2		2	3							2		1	2	
CO4	3		2	3			2				2	2	2	2	
CO5	2		3	1	2								2	2	



Drogramma	BE & MECH	Som	Cotogowy	т	Т	P	С
Programme & Branch	DE & WIECH	Sem.	Category	L	1	r	
w Branch		5	PC	3	0	0	3
Preamble	> To Learn designing						
	<ul> <li>To Learn designing shafts and couplings for various applications.</li> <li>To gain knowledge on the principles and procedure for the design of Mechanica</li> </ul>						
	power Transmission components.						
	To understand the standard procedure available for Design of Transmission of						
	Mechanical elements spur, helical & bevel gears.						
	To learn the concepts of design multi and variable speed gear box for machin						
	tool applications.						
	➤ To Learn designing	and select	sliding and rollin	g cont	act b	earin	gs, seals an
	gaskets.						
	(Use of PSG Design Data b	ook is permi	tted)				
Unit 1	DESIGN OF SHAFTS AN	D COUPLI	NGS				9
Shafts and Axl	es – Design of solid and hollo	w shafts base	ed on strength, rig	idity a	nd cr	itical	speed – Key
and splines – F	Rigid and flexible couplings.						
Unit 2	DESIGN OF FLEXIBLE	ELEMENT	S				9
Design of Flat	belts and pulleys – Selection	of V belts an	d pulleys – Select	ion of	hoist	ing v	vire ropes an
pulleys – Desig	gn of Transmission chains and	d Sprockets.					
Unit 3	SPUR, HELICAL AND B	EVEL CEA	DC				9
	nd number of teeth-Force ana			ic effe	cts –	Fatig	
Speed ratios ar Factor of safet	nd number of teeth-Force ana y – Gear materials – Design	lysis -Tooth of straight to	stresses – Dynam oth spur & helica	ıl gear	s bas	ed on	gue strength a strength an
Speed ratios and Factor of safet wear considerates	nd number of teeth-Force and y – Gear materials – Design ations – Pressure angle in the	lysis -Tooth of straight to e normal and	stresses – Dynam ooth spur & helica I transverse plane	ıl gear -Equiv	s bas valen	ed on t nun	gue strength a strength an aber of teeth
Speed ratios are Factor of safet wear considerate forces for heli	nd number of teeth-Force and y – Gear materials – Design ations – Pressure angle in the cal gears. Straight bevel gea	lysis -Tooth of straight to e normal and r: Tooth terr	stresses – Dynam ooth spur & helica I transverse plane ninology, tooth fo	al gear -Equivorces a	s bas valen	ed on t nun	gue strength a strength an aber of teeth
Speed ratios and Factor of safet wear considerate forces for heli number of teet	nd number of teeth-Force and y – Gear materials – Design ations – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions	lysis -Tooth of straight to e normal and r: Tooth terr	stresses – Dynam ooth spur & helica I transverse plane ninology, tooth fo	al gear -Equivorces a	s bas valen	ed on t nun	gue strength a strength an aber of teeth es, equivaler
Speed ratios and Factor of safet wear considerate forces for heli number of teet  Unit 4	nd number of teeth-Force analy – Gear materials – Design ations – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions  GEAR BOX DESIGN	lysis -Tooth of straight to e normal and r: Tooth terr of pair of sta	stresses – Dynam both spur & helica I transverse plane minology, tooth for aight bevel gears.	al gear -Equiv orces a	s base valent and s	ed on t nun tresse	gue strength a strength an aber of teeth es, equivaler
Speed ratios are Factor of safet wear considera forces for heli number of teet  Unit 4  Geometric pro	nd number of teeth-Force analy – Gear materials – Design entions – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions    GEAR BOX DESIGN   Gression – Standard step rations	lysis -Tooth of straight to e normal and r: Tooth terr of pair of str	stresses – Dynam both spur & helica I transverse plane minology, tooth for raight bevel gears.	al gear E-Equivorces a	s basevalendand s	ed on t nun tresse gn of	gue strength an aber of teethes, equivaler
Speed ratios and Factor of safet wear considerate forces for heli number of teet  Unit 4  Geometric progear box – De	nd number of teeth-Force analy – Gear materials – Design of ations – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions    GEAR BOX DESIGN     Gression – Standard step rations     Standard step rations     Gear box     Gea	lysis -Tooth of straight to e normal and r: Tooth terr of pair of straight o – Ray diago	stresses – Dynam both spur & helica I transverse plane minology, tooth for raight bevel gears. ram, kinematics la	al gear E-Equivorces a Eayout -	s basevalent and s Designstan	ed on t nun tresse gn of t mes	gue strength an aber of teethes, equivalence of sliding messah gear box
Speed ratios are Factor of safet wear considerations for heli number of teet  Unit 4  Geometric progear box – De Speed reducer	nd number of teeth-Force analy – Gear materials – Design entions – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions    GEAR BOX DESIGN   Gression – Standard step rations	lysis -Tooth of straight to e normal and r: Tooth terr of pair of straight o – Ray diago	stresses – Dynam both spur & helica I transverse plane minology, tooth for raight bevel gears. ram, kinematics la	al gear E-Equivorces a Eayout -	s basevalent and s Designstan	ed on t nun tresse gn of t mes	gue strength an aber of teethes, equivaler  9  Siliding messible gear box
Speed ratios and Factor of safet wear considerate forces for heli number of teet Unit 4  Geometric progear box – De Speed reducer applications.	nd number of teeth-Force analy – Gear materials – Design of ations – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions  GEAR BOX DESIGN  gression – Standard step rations ign of multi speed gear box unit. – Variable speed gear	lysis -Tooth of straight to e normal and r: Tooth terr of pair of str  - Ray diagr for machine box, Fluid	stresses – Dyname of the spur & helical transverse plane ninology, tooth for aight bevel gears.  Tam, kinematics late tool applications Couplings, Torque	al gear E-Equivorces a Eayout -	s basevalent and s Designstan	ed on t nun tresse gn of t mes	gue strength an aber of teethes, equivaler  9  Siliding messh gear box or automotiv
Speed ratios and Factor of safet wear considerate forces for heli number of teet  Unit 4  Geometric progear box – De	nd number of teeth-Force analy – Gear materials – Design of ations – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions  GEAR BOX DESIGN  gression – Standard step rations ign of multi speed gear box unit. – Variable speed gear  DESIGN OF BEARINGS	lysis -Tooth of straight to e normal and r: Tooth terr of pair of str  - Ray diagr for machine box, Fluid	stresses – Dyname of the spur & helical transverse plane ninology, tooth for aight bevel gears.  Tam, kinematics late tool applications Couplings, Torque	al gear E-Equivorces a Eayout -	s basevalent and s Designstan	ed on t nun tresse gn of t mes	gue strength an aber of teethes, equivaler  9  S sliding mes sh gear box
Speed ratios and Factor of safet wear considerations for heli number of teet  Unit 4  Geometric professer box – De Speed reducer applications.  Unit 5	nd number of teeth-Force analy – Gear materials – Design of ations – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions GEAR BOX DESIGN gression – Standard step rations ign of multi-speed gear box unit. – Variable speed gear DESIGN OF BEARINGS ELEMENTS	lysis -Tooth of straight to e normal and r: Tooth terr of pair of str o – Ray diagr for machine box, Fluid	stresses – Dynam ooth spur & helical transverse plane ninology, tooth for aight bevel gears.  Tam, kinematics last tool applications Couplings, Torque	el gear e-Equivorces a expout - es – Co el Cor	s basevalent	ed on t nun tresse gn of t mes	gue strength an aber of teeth es, equivaler g  f sliding mes sh gear box or automotiv
Speed ratios are Factor of safet wear considerations for heli number of teet  Unit 4  Geometric progear box – De Speed reducer applications.  Unit 5  Sliding contact	nd number of teeth-Force analy – Gear materials – Design of ations – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions  GEAR BOX DESIGN  gression – Standard step rations ign of multi speed gear box unit. – Variable speed gear  DESIGN OF BEARINGS  ELEMENTS  t and rolling contact bearing	lysis -Tooth of straight to e normal and r: Tooth terr of pair of str o – Ray diago for machine box, Fluid  AND MISC s – Hydrody	stresses – Dyname of the spur & helical transverse plane ninology, tooth for aight bevel gears.  Tram, kinematics late tool applications Couplings, Torque  ELLANEOUS  Tramic journal be	al gear -Equivorces a 	Designstan	ed on t nun tresse gn of t mes ers fo	gue strength and s
Speed ratios are Factor of safet wear considerations forces for helinumber of teet  Unit 4  Geometric progear box – De Speed reducer applications.  Unit 5  Sliding contact	nd number of teeth-Force analy – Gear materials – Design of ations – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions GEAR BOX DESIGN gression – Standard step rations ign of multi-speed gear box unit. – Variable speed gear DESIGN OF BEARINGS ELEMENTS	lysis -Tooth of straight to e normal and r: Tooth terr of pair of str o – Ray diagr for machine box, Fluid  AND MISC s – Hydrody	stresses – Dyname of the spur & helical transverse plane ninology, tooth for aight bevel gears.  Tram, kinematics late tool applications Couplings, Torque  ELLANEOUS  Tramic journal be	al gear -Equivorces a 	Designstan	ed on t nun tresse gn of t mes ers fo	gue strength and s
Speed ratios and Factor of safet wear considerate forces for helinumber of teet Unit 4 Geometric program box – De Speed reducer applications. Unit 5 Sliding contact Raimondi & B	nd number of teeth-Force analy – Gear materials – Design of ations – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions   GEAR BOX DESIGN  gression – Standard step rations ign of multi speed gear box unit. – Variable speed gear DESIGN OF BEARINGS  ELEMENTS  t and rolling contact bearing oyd graphs, Selection of Rolling contact bear selection of Rollin	lysis -Tooth of straight to e normal and r: Tooth terr of pair of str o – Ray diagr for machine box, Fluid  AND MISC s – Hydrody	stresses – Dyname of the spur & helical transverse plane ninology, tooth for aight bevel gears.  Tram, kinematics late tool applications Couplings, Torque  ELLANEOUS  Tramic journal be	al gear -Equivorces a 	Designstan	ed on t nun tresse gn of t mes ers fo	gue strength and s
Speed ratios are Factor of safet wear considerate forces for helinumber of teet  Unit 4  Geometric progear box – De Speed reducer applications.  Unit 5  Sliding contact Raimondi & B	nd number of teeth-Force analy – Gear materials – Design of ations – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions GEAR BOX DESIGN gression – Standard step rations are gear box unit. – Variable speed gear DESIGN OF BEARINGS ELEMENTS  t and rolling contact bearing oyd graphs, Selection of Rolling Contact bearing oyd graphs.	lysis -Tooth of straight to e normal and r: Tooth terr of pair of str o – Ray diagr for machine box, Fluid  AND MISC s – Hydrody olling Contact	stresses – Dynam both spur & helical transverse plane ninology, tooth for aight bevel gears. Tam, kinematics last tool applications Couplings, Torque ELLANEOUS	al gear -Equivorces a -Equivor	Designstan	gn of t mes	gue strength and s
Speed ratios and Factor of safet wear considerate forces for helinumber of teet  Unit 4  Geometric progear box – De Speed reducer applications.  Unit 5  Sliding contact Raimondi & B  TEXTBOOKS  1 Bhar	nd number of teeth-Force analy – Gear materials – Design of tions – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions   GEAR BOX DESIGN   GEAR	lysis -Tooth of straight to e normal and r: Tooth terr of pair of str  O – Ray diagr for machine box, Fluid  AND MISC  s – Hydrody olling Contact e Elements",	stresses – Dyname of the spur & helical transverse plane ninology, tooth for aight bevel gears.  Tam, kinematics late tool applications Couplings, Torque  ELLANEOUS  Transic journal been bearings – Designation of the serings – Designation of the se	al gear -Equivorces a -Equivor	Designstan	gn of t mes	gue strength an aber of teethes, equivaler  9 Siliding mess sh gear box or automotive  9 feld Numbe Gaskets.  Total: 4
Speed ratios are Factor of safet wear considerations forces for helinumber of teet  Unit 4  Geometric progear box – De Speed reducer applications.  Unit 5  Sliding contact Raimondi & B  TEXTBOOKS  1 Bhare 2 Jose	nd number of teeth-Force analy – Gear materials – Design of attions – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions   GEAR BOX DESIGN  gression – Standard step rations ign of multi-speed gear box unit. – Variable speed gear box ELEMENTS  t and rolling contact bearing oyd graphs, – Selection of Rolling Contact Budyling Shigley, Richard G. Budyling Shigley,	lysis -Tooth of straight to e normal and r: Tooth terr of pair of str o – Ray diagr for machine box, Fluid  AND MISC s – Hydrody olling Contact e Elements", nas and J. Ko	stresses – Dyname of the spur & helical transverse plane ninology, tooth for aight bevel gears.  Tam, kinematics late tool applications Couplings, Torque  ELLANEOUS  Transic journal been bearings – Designation of the serings – Designation of the se	al gear -Equivorces a -Equivor	Designstan	gn of t mes	gue strength an astrength an aber of teethes, equivalences, equivalences of solutions and solutions of solutions of automotive of saskets.  Total: 4  Dook Co, 2020
Speed ratios are Factor of safet wear considerations forces for helinumber of teet  Unit 4  Geometric progear box – De Speed reducer applications.  Unit 5  Sliding contact Raimondi & B  TEXTBOOKS  1 Bhare 2 Jose 11th	nd number of teeth-Force analy – Gear materials – Design of tions – Pressure angle in the cal gears. Straight bevel geath. Estimating the dimensions   GEAR BOX DESIGN   GEAR	lysis -Tooth of straight to e normal and r: Tooth terr of pair of str o – Ray diagr for machine box, Fluid  AND MISC s – Hydrody olling Contact e Elements", nas and J. Ke 2020.	stresses – Dyname of the spur & helical transverse plane ininology, tooth for aight bevel gears.  Tram, kinematics late tool applications Couplings, Torque  ELLANEOUS  Tramic journal be of the bearings – Designation of the second of the sec	al gear -Equivorces a -AyoutS - Co	Designstan verte	gn of t mesers for and Cill Boginee	gue strength an astrength an aber of teethes, equivalences, equivalences of solutions and solutions of solutions of automotive of saskets.  Total: 4  Dook Co, 2020

1	Ansel C Ugural, "Mechanical Design – An Integral Approach", 1st Edition, Tata McGraw-Hill
	Book Co, 2004.
2	Merhyle Franklin Spotts, Terry E. Shoup, and Lee Emrey Hornberger, "Design of Machine
	Elements" 8 <sup>th</sup> Edition, Printice Hall, 2004.
3	Robert C. Juvinall and Kurt M. Marshek, "Fundamentals of Machine component Design",7th
	Edition, Wiley, 2019.
4	Sundararajamoorthy T. V. and Shanmugam .N, "Machine Design", Anuradha Publications,
	Chennai, 2003.
5	E. Shoup, "Design of Machine Elements", 8th Edition, Pearson Publications, 2019.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the e	nd of the course, learners will be able to	Level
CO1	Apply the concepts design to shafts, key and couplings.	К3
CO2	Apply the concepts of design to belts, chains and rope drives.	K3
CO3	Apply the concepts of design to spur, helical and bevel gears.	К3
CO4	Apply the concepts of design to gear boxes.	К3
CO5	Apply the concepts of design and select sliding and rolling contact bearings, seals and gaskets.	К3

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	3	1		(20)		11	1	1110		2	3	2	2
CO2	3	2	3	1			e/f Di		$n^{-1}$			1	2	3	2
CO3	3	2	3	1				1	1			1	2	3	2
CO4	3	2	3	1			rn	1	1			1	2	3	2
CO5	2	2	3	1		BiF	En	1		UR /		2	3	2	2
	ESTD. 2011														

	AME112 - AUTOMOBILE ENGINEERING										
Programme & Branch	BE & MECH	Sem.	Category	L	Т	P	С				
		4	PC	3	0	0	3				
Preamble	automobile.	<ul> <li>To understand the construction and working principle of various parts of an automobile.</li> <li>To have the practice for assembling and dismantling of engine parts and</li> </ul>									
Unit 1	VEHICLE STRUCTURE A	ND ENG	INES				9				

Types of automobiles vehicle construction and different layouts, chassis, frame and body, Vehicle aerodynamics (various resistances and moments involved), IC engines –components-functions and materials, variable valve timing (VVT).

#### Unit 2 ENGINE AUXILIARY SYSTEMS

9

Electronically controlled gasoline injection system for SI engines, Electronically controlled diesel injection system (Unit injector system, Rotary distributor type and common rail direct injection system), Electronic ignition system (Transistorized coil ignition system, capacitive discharge ignition system), Turbo chargers (WGT, VGT), Engine emission control by three way catalytic converter system, Emission norms (Euro and BS).

#### Unit 3 TRANSMISSION SYSTEMS

9

Clutch-types and construction, gear boxes- manual and automatic, gear shift mechanisms, Over drive, transfer box, fluid flywheel, torque converter, propeller shaft, slip joints, universal joints, Differential and rear axle, Hotchkiss Drive and Torque Tube Drive.

#### Unit 4 STEERING, BRAKES AND SUSPENSION SYSTEMS

9

Steering geometry and types of steering gear box-Power Steering, Types of Front Axle, Types of Suspension Systems, Pneumatic and Hydraulic Braking Systems, Antilock Braking System (ABS), electronic brake force distribution (EBD) and Traction Control.

#### Unit 5 | ALTERNATIVE ENERGY SOURCES

9

Use of Natural Gas, Liquefied Petroleum Gas, Bio-diesel, Bio-ethanol, Gasohol and Hydrogen in Automobiles - Engine modifications required –Performance, Combustion and Emission Characteristics of SI and CI engines with these alternate fuels – Electric and Hybrid Vehicles, Fuel Cell.

**Total: 45** 

#### **TEXTBOOKS**

- Jain K.K. and Asthana .R.B, "Automobile Engineering" Tata McGraw Hill Publishers, New Delhi, 2017.
- 2 Kirpal Singh, "Automobile Engineering", Vol 1 & 2, Seventh Edition, Standard Publishers, New Delhi, 13<sup>th</sup> Edition 2021.

#### **REFERENCES**

- 1 Ganesan V. "Internal Combustion Engines", Third Edition, Tata McGraw-Hill, 2017.
  - Heinz Heisler, "Advanced Engine Technology", SAE International Publications USA, 1998.
  - Joseph Heitner, "Automotive Mechanics", Second Edition, East-West Press, 1999.
  - S K Gupta, "A Textbook of Automobile Engineering", S Chand Publications, 2<sup>nd</sup> Edition, 2020.
  - 5 Newton, Steeds and Garet, "Motor Vehicles", Butterworth Publishers, 1989.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Recognize the various parts of the automobile and their functions	K2
	and materials.	
CO2	Discuss the engine auxiliary systems and engine emission control.	K2
CO3	Distinguish the working of different types of transmission	K2
	systems.	

CO4	Explain the Steering, Brakes and Suspension Systems.	K2
CO5	Predict possible alternate sources of energy for IC Engines.	K3

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	2	1					1			1	1	2	1
CO2	2	1	2	1					1			1	1	2	1
CO3	2	1	2	1					1			1	1	2	1
CO4	2	1	2	1					1			1	1	2	1
CO5	2	1	2	1					1			1	1	2	1

	AME305 - COMPUTER	RAIDED	DESIGN LABOR	ATO]	RY		
	ANALSOS CONTETEI	(IIIDED)	DEDIGI LIBOR	1110			
Programme	BE & MECH	Sem.	Category	L	T	P	C
& Branch							
		5	PC	0	0	4	2
Preamble	To gain practical experience systems.	e in hand	ling 2D drafting a	and 3	D m	odel	ling software
LIST OF EXP	PERIMENTS		l.x				
1. Introduction	of 3D Modelling software						
Creation of 3D	assembly model of following	machine e	ements using 3D N	Model	ling	softw	are
2. Flange Coup	oling		200				
3. Plummer Bl	ock	OII	- 015				
4. Screw Jack	0	PDianinii	ne				
5. Lathe Tailsto	ock	iscipii					
6. Universal Jo	int						
7. Machine Vio	ce Sell-	EKUM	SUNIID Z				
8. Stuffing box	( ) giiii						
9. Crosshead		210. ZU					
10. Safety Valv	res						
11. Non-return	valves						
12. Connecting	grod						
13. Piston							
14. Crankshaft							
* Students may	also be trained in manual drav	wing of soi	ne of the above co	mpon	ents		
							Total: 60
COURSE OU						s Tax	konomy
At the end of	the course, learners will be ab	ole to		Le	vel		

CO1	Design experience in handling 2D drafting and 3D modelling	К3
	software systems.	
CO2	Design 3-Dimensional geometric model of parts, sub-assemblies,	К3
	assemblies and export it to drawing.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	2	3				2			1	3	3	1
CO2	2	2	2	2	3				2			1	3	3	1

	AME306 - METROLOGY & DYNAMICS LABORATORY								
			on L			1	T		
Programme	BE & MECH	Sem.	Category	$\mathbf{L}$	T	P	C		
& Branch	INC	STITUTE OF THE	INDIDGY						
		5	PC	0	0	4	2		
Preamble	To study the difference	nt measureme	ent equipment and t	ise of	this i	indus	try for quality		
	inspection.								
	To supplements the principles learnt in dynamics of machinery.								
	To understand how	certain measu	uring devices are u	sed f	or dy	nami	c testing.		

#### LIST OF EXPERIMENTS – METROLOGY

- 1. Calibration and use of linear measuring instruments Vernier caliper, micrometer, Vernier height gauge, depth micrometer, bore gauge, telescopic gauge, Comparators.
- 2. Measurement of angles using bevel protractor, sine bar, autocollimator, precision level.
- 3. Measurement of assembly and transmission elements screw thread parameters Screw thread Micrometers, three wire method, Toolmaker's microscope.
- 4. Measurement of gear parameters Micrometers, Vernier caliper..
- 5. Measurement of features in a prismatic component using Coordinate Measuring Machine (CMM), Programming of CNC Coordinate Measuring Machines for repeated measurements of identical components.
- 6. Non-contact (Optical) measurement using Measuring microscope / Profile projector and Video measurement system.
- 7. Measurement of Surface finish in components manufactured using various processes (turning, milling, grinding, etc.,) using stylus-based instruments.

#### LIST OF EXPERIMENTS – DYNAMICS

- 1. Study of gear parameters.
- 2. Epicycle gear Train.
- 3. Determination of moment of inertia of flywheel and axle system.
- 4. Determination of mass moment of inertia of a body about its axis of symmetry.
- 5. Undamped free vibrations of a single degree freedom spring-mass system.
- 6. Torsional Vibration (Undamped) of single rotor shaft system.
- 7. Dynamic analysis of cam mechanism.
- 8. Experiments on Governors

9	<b>Experiment</b>	on	motorized	gyroscope.
<i>一</i> .	LADOITHICH	OH	motorized	gyroscope.

10. Determination of critical speed of shafts.

Total: 60

COURS	E OUTCOMES:	Bloom's Taxonomy
At the e	nd of the course, learners will be able to	Level
CO1	The students able to measure the gear tooth dimensions, angle	К3
	using sine bar, straightness.	
CO2	Determine mass moment of inertia of mechanical element,	K3
	governor effort and range of sensitivity.	
CO3	Determine the natural frequency and damping coefficient, critical	K3
	speeds of shafts.	

CC	<b>)-PO</b> ]	Марр	ing			J	E P	PI	AA	R					
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1		2	3	3		2	2		1	2	2		3	2	2
CO2		2	3	3		2	2		1	2	2		2	2	2
CO3		2	3	3		2	2		1	2	2		3	2	2





AME113 - HEAT AND MASS TRANSFER											
Programme	BE & MECH	Sem.	Category	L	T	P	C				
& Branch	ch										
		6	PC	3	1	0	4				
Preamble	<ul> <li>To Learn the principal mechanism of heat transfer under steady state and transient conditions.</li> <li>To learn the fundamental concept and principles in convective heat transfer.</li> <li>To learn the theory of phase change heat transfer and design of heat exchangers.</li> <li>To study the fundamental concept and principles in radiation heat transfer.</li> <li>To study the basic concept of mass transfer and electronic cooling.</li> </ul>										
Unit 1	CONDUCTION						9+3				

Modes of heat transfer – Fundamental Laws – Applications – Thermal contact resistance; Overall heat transfer coefficient. One dimensional steady state conduction in simple geometries – General equation of heat conduction in Cartesian, cylindrical and spherical coordinates – Conduction in plane wall, cylindrical and spherical shells; Electrical analogy; Conduction in composite walls and shells; Critical thickness of insulation; Heat transfer through fins; Unsteady state heat transfer – Systems with negligible internal resistance -lumped heat capacity analysis; Infinite bodies; Semi-infinite bodies.

#### Unit 2 | CONVECTION

9+3

Mechanism of convection – classification – Types of Flow – non-dimensional numbers in heat transfer; Boundary layer concepts for flow over a flat plate and flow through circular pipes; Forced convection – External flow over flat plate, cylinder, sphere and bank of tubes; Internal flow through circular pipes; Natural convection: Steady one-dimensional flow over vertical, horizontal plates, horizontal cylinders and spheres; combined free and forced convection.

# Unit 3 CONVECTIVE PHASE CHANGE HEAT TRANSFER AND HEAT EXCHANGERS

9+3

Condensation and boiling – boiling modes, correlations, forced convection boiling, laminar film condensation on a vertical plate, turbulent film condensation; Heat exchangers – design procedure for heat exchanger – LMTD and NTU analysis, fouling factor, effectiveness.

#### Unit 4 RADIATION

9+3

Thermal Radiation – Black body and real surface radiation; Radiation properties and governing laws; Radiation heat transfer – view factor and its relations – Radiation heat exchange between black and grey surfaces, Radiosity – Radiation shields and the radiation effects.

## Unit 5 MASS TRANSFER AND COOLING OF ELECTRONIC EQUIPMENTS

9+3

Mass transfer – Fick's law of diffusion, diffusion mass transfer, forced convective mass transfer, heat and mass transfer analogies; Cooling of electronic equipment; Conduction in Cooling – Chip Carriers – PCB – TCM; Air cooling in forced and Natural convection.

Total: 60

#### **TEXTBOOKS**

Yunus A. Cengel, Afshin J. Ghajar, "Heat and Mass Transfer: Fundamentals and Applications", Tata Mc Graw Hill publications, 6<sup>th</sup> Edition 2020.

2	Sachdeva, R. C, "Fundamentals of Engineering Heat and Mass Transfer", New Age							
	International Publishers, 6 <sup>th</sup> Edition, 2022.							
REFERENCES								
1	Frank, P., Incropera and David, P. D, "Fundamentals of Heat and Mass Transfer", John Wiley							
	publication, 7 <sup>th</sup> Edition, 2017.							
2	Rajput, R. K, "A Textbook of Heat and Mass Transfer", S. Chand Publication, 7 <sup>th</sup> edition, 2019.							
3	Holman, J.P, "Heat and Mass Transfer", Tata McGraw-Hill, 10 <sup>th</sup> edition, 2011.							
4.	Kothandaraman C.P and Subramanyan S, "Fundamentals of Heat and Mass Transfer", New							
	Age International, 10 <sup>th</sup> edition, 2022.							

COURS	E OUTCOMES:	Bloom's Taxonomy
At the e	nd of the course, learners will be able to	Level
CO1	Apply and interpret the radical concepts on steady and transient	К3
	state heat conduction problems.	
CO2	Solve free and forced convection problems using correlations and	K4
	perform experimentation.	
CO3	Investigate the phenomenon of boiling, condensation and heat	K4
	exchanger equipment design.	
CO4	Conduct and investigate the basic occurrence of radiational	K4
	concepts.	
CO5	Interpret the fundamental concepts on mass transfer and cooling	K4
	of electronic equipment.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2		(0,0)		°П	1	19		1	3	2	1
CO2	3	3	3	3			e/f D	scipli	nel			1	3	2	1
CO3	3	3	3	2					1			1	3	2	1
CO4	3	3	3	2			TO		1			1	3	2	1
CO5	3	3	3	2	1	$\mathcal{F}_{\mathcal{F}}$		UIVII		UR /		1	3	2	1

	AME114 - FINITE ELEMENT ANALYSIS								
Programme & Branch	BE & MECH	Sem.	Category	L	Т	P	C		
		6	PC	3	0	0	3		
Preamble	> To introduce the con-	cepts of Ma	thematical Model	ing of	Engi	neeri	ng Problems.		
	To appreciate the use	of FEM to	a range of Engine	ering	Probl	lems.			
Unit 1	INTRODUCTION 9								
Historical Background - Mathematical Modeling of field problems in Engineering - Governing									
Equations – D	iscrete and continuous models	s – Boundai	y, Initial and Eige	en Valı	ue pr	oblen	ns- Weighted		

Dagidagal	Mathada Variational Formulation of Doundary Valva Bushlama	DitaTashniana Dagia
	Methods – Variational Formulation of Boundary Value Problems – of the Finite Element Method.	Ritz lecillique – Basic
Unit	1	9
	nensional Second Order Equations – Discretization – Element types-	-
	s – Derivation of Shape functions and Stiffness matrices and force vector	=
	•	•
	n of problems from solid mechanics and heat transfer. Longitudinal vapes. Fourth Order Beam Equation –Transverse deflections and Natura	<del>-</del>
Unit		
	Order 2D Equations involving Scalar Variable Functions – Variation	
	formulation – Triangular elements – Shape functions and elemen	
	ion to Field Problems - Thermal problems - Torsion of Non circul	
	<ul> <li>Higher Order Elements.</li> </ul>	ar sharts —Quadrilaterar
Unit		S 9
	s of elasticity – Plane stress, plane strain and axisymmetric proble	
-	ure effects – Stress calculations - Plate and shell elements.	oms – body forces and
Unit		9
	co-ordinate systems – Isoparametric elements – Shape functions for is	
	two dimensions – Serendipity elements – Numerical integration and a	-
	s - Matrix solution techniques – Solutions Techniques to Dynamic pro	-
-	Software.	introduction to
1 11141 ) 515	Software.	Total: 45
TEXTB	OOKS	10001110
1	Reddy J.N, "An Introduction to the Finite Element Method", 4 <sup>th</sup> Edi	tion Tata McGraw-Hill
1	2020.	iron, rata ivic Gravi IIIII,
2	Seshu P, "Text Book of Finite Element Analysis", Prentice-Hall of Inc	lia Pyt Ltd. New Delhi
_	2007.	2
REFER	No.	
1	Rao, S.S, "The Finite Element Method in Engineering", Butterworth	Heinemann, 6 <sup>th</sup> Edition,
	2017.	, , , , , , , , , , , , , , , , , , , ,
2	Logan, D.L, "A first course in Finite Element Method", Thomson A	sia Pvt. Ltd, 6 <sup>th</sup> Edition,
	2016.	, ,
3	Robert D. Cook, David S. Malkus, Michael E. Plesha, Robert	J. Witt, "Concepts and
	Applications of Finite Element Analysis", 4th Edition, Wiley Student	-
4.	Chandrupatla & Belagundu, "Introduction to Finite Elements in En	
	Cambridge University Press, 2021.	
5.	Bhatti Asghar M, "Fundamental Finite Element Analysis and Appli	cations", John Wiley &
	Sons, 2005 (Indian Reprint 2013)	•
	E OUTCOMES: B	loom's Taxonomy
<b>COURS</b>		· ·
	nd of the course, learners will be able to	evel
	Summarize the basics of finite element formulation.	K2

CO2	Apply finite element formulations to solve one dimensional	К3
	Problems.	
CO3	Apply finite element formulations to solve two dimensional scalar	К3
	Problems.	
CO4	Apply finite element method to solve two dimensional Vector	К3
	problems.	
CO5	Apply finite element method to solve problems on iso parametric	К3
	element and dynamic problems.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	2		1		1			1	3	2	2
CO2	3	3	2	2	2		1		1	D		1	3	2	2
CO3	3	3	2	2	2	JI	1		1	1		1	3	2	2
CO4	3	3	2	2	2	IN51	llit	UF IEU	HMIJLU	lGΥ		1	3	2	2
CO5	3	3	2	2	2		1		1			1	3	2	2

A	ME307 - COMPUTER AII	DED MANU	FACTURING L	ABO	RAT	ORY	
Programme & Branch	ве & месн	Sem.	Category	L	T	P	C
		5	PC	0	0	4	2
Preamble	<ul> <li>To study the feature</li> <li>To expose students</li> <li>To know the application</li> <li>Machining centre, prototyping.</li> </ul>	to modern con tion of variou	ntrol systems (Fa s CNC machines	like C	NC 1	athe,	CNC Vertical

#### LIST OF EXPERIMENTS

Manual Part Programming.

- (i) Part Programming CNC Machining Centre
- a) Linear Cutting, b) Circular cutting, c) Cutter Radius Compensation, d) Canned Cycle Operations.
- (ii) Part Programming CNC Turning Centre
- a) Straight, Taper and Radius Turning, b) Thread Cutting, c) Rough and Finish Turning Cycle, d) Drilling and Tapping Cycle.
- (iii) Computer Aided Part Programming
- a) CL Data and Post process generation using CAM packages, b) Application of CAPP in Machining and Turning Centre.

**Total: 60** 

COURSE OUTCOMES:

At the end of the course, learners will be able to

Bloom's Taxonomy
Level

CO1	Demonstrate manual part programming with G and M codes	К3
	using CAM.	

CO/P	O PO	O1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO	2	2	2	2	2	3				2			1	3	3	1

Programme	BE & MECI	H Sem.	Category	L	Т	P	С
& Branch		i sem	Category				
·		6	PC	0	0	4	2
Preamble	<ul> <li>To Study the</li> <li>To study the</li> <li>To study the implementation</li> </ul>	value timing-V dia characteristics of Performance of ste heat transfer pho on performance of re	fuels/Lubricates eam generator/ tu enomena, predic	used in I arbine t the rel	C En	gines	3

#### LIST OF EXPERIMENTS – IC ENGINES LAB

- 1. Valve Timing and Port Timing diagrams.
- 2. Actual p-v diagrams of IC engines.
- 3. Performance Test on 4 stroke Diesel Engine.
- 4. Heat Balance Test on 4 stroke Diesel Engine.
- 5. Morse Test on Multi-cylinder Petrol Engine.
- 6. Retardation Test on a Diesel Engine.
- 7. Determination of Flash Point and Fire Point of various fuels / lubricants
- 8. Performance test on a reciprocating air compressor.

#### LIST OF EXPERIMENTS – HEAT TRANFER LAB

- 1. Thermal conductivity measurement using guarded plate apparatus.
- 2. Thermal conductivity measurement of pipe insulation using lagged pipe apparatus.
- 3. Determination of heat transfer coefficient under natural convection from a vertical cylinder.
- 4. Determination of heat transfer coefficient under forced convection from a tube.
- 5. Determination of Thermal conductivity of composite wall.
- 6. Determination of Thermal conductivity of insulating powder.
- 7. Heat transfer from pin-fin apparatus (natural & forced convection modes)
- 8. Determination of Stefan Boltzmann constant.
- 9. Determination of emissivity of a grey surface.
- 10. Effectiveness of Parallel / counter flow heat exchanger.

#### LIST OF EXPERIMENTS - STEAM LAB

1. Study on Steam Generators and Turbines

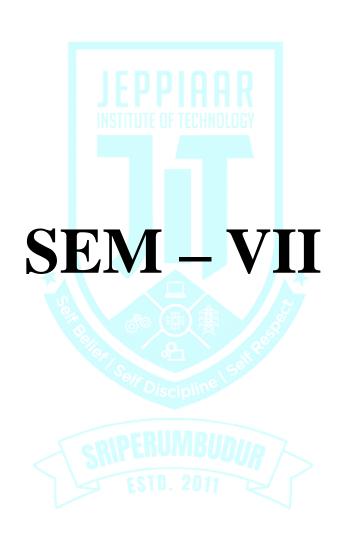
#### LIST OF EXPERIMENTS - REFRIGERATION AND AIR CONDITIOING LAB

- 1. Determination of COP of a refrigeration system
- 2. Determination of COP of air conditioning test rig
- 3. Performance test in a fluidized Bed Cooling Tower

	E OUTCOMES: nd of the course, learners will be able to	Bloom's Taxonomy Level
CO1	Conduct performance and retardation tests on internal combustion engines.	K4
CO2	Conduct tests on natural and forced convective heat transfer apparatus and evaluate heat transfer coefficient.	K4
CO3	Conduct tests on radiative heat transfer apparatus and evaluate Stefan Boltzmann constant and emissivity.	K4
CO4	Conduct tests to evaluate the performance of parallel/counter flow heat exchanger apparatus and reciprocating air compressor.	K4
CO5	Conduct tests to evaluate the performance of refrigeration and air conditioning test rigs.	K4

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	1					1			1	1	1	1
CO2	2	2	1	1	KAN				1		X	1	1	1	1
CO3	2	2	1	1	5				1		27	1	1	1	1
CO4	2	2	1	1					<b>1</b> 1	7/3		1	1	1	1
CO5	2	2	1	1		160		ം	1	. ¢°		1	1	1	1





	AME115 - ROB	OTICS	& AUTOMATION								
Programme & Branch	BE & MECH	Sem.	Category	L	T	P	C				
		7	PC	3	0	0	3				
Preamble	> To study the kinematic	s, drive	systems and program	nming	g of r	obots	5.				
	> To study the basics of	robot lav	ws and transmission	syste	ns.						
	To familiarize students	s with th	e concepts and tech	nique	s of	robot	manipulator,				
	its kinematics.										
	➤ To familiarize student	ts with	the various Progra	mmin	g and	d Ma	chine Vision				
application in robots.											
	To build confidence among students to evaluate, choose and incorporate robots										
in engineering systems.											
Unit 1	FUNDAMENTALS OF ROI		. W . F . 1			1 1	9				
	tion – Robot Anatomy – Co-ord				_						
	- Pitch, yaw, Roll, Joint Notation		ed of Motion, Pay	Load -	– Kol	oot P	arts and their				
	ed for Robots – Different Applie	cations.									
Unit 2	ROBOT KINEMATICS	1: 00	C 11:	<u>,.</u>	1 .		9				
	natics, inverse kinematics and the										
of Manipulators with two, three degrees of freedom (in 2 dimensional), four degrees of freedom (in 3											
dimancional)	darizations and problems I	Homogo	naous transformation		_						
	- derivations and problems. I	Homoge	neous transformation		_						
rotation matric	es.				_		anslation and				
rotation matric Unit 3	es.  ROBOT DRIVE SYSTEMS	AND E	ND EFFECTORS	on ma	atrice	s, tra	anslation and				
Unit 3 Pneumatic Dri	es.  ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mech	AND E	ND EFFECTORS  Orives – Electrical	on ma	atrice	s, tra	9 dervo Motors,				
Unit 3 Pneumatic Dri Stepper Motor,	es.  ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mech  A.C. Servo Motors – Salient Fe	AND Expansion An	ND EFFECTORS  Orives – Electrical Applications and Con	Drives	s – D	.C. S	9 servo Motors, These Drives.				
Unit 3 Pneumatic Dri Stepper Motor, End Effectors	es.  ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mech  A.C. Servo Motors – Salient Fe  Grippers – Mechanical Grippe	AND Enanical I eatures, A	ND EFFECTORS  Drives – Electrical Applications and Connaction and Hydraulic	Drives	s – D	.C. S	9 Servo Motors, These Drives. netic grippers,				
Unit 3 Pneumatic Dri Stepper Motor, End Effectors	es.  ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mechanical Grippe Grippers – Mechanical Grippers, internal grippers and external	AND Enanical I eatures, A	ND EFFECTORS  Drives – Electrical Applications and Connaction and Hydraulic	Drives	s – D	.C. S	9 Servo Motors, These Drives. netic grippers,				
Unit 3 Pneumatic Dri Stepper Motor, End Effectors - vacuum grippe Unit 4	res.  ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mechanical Grippe Grippers – Mechanical Grippe rs, internal grippers and external  SENSORS IN ROBOTS	AND E. nanical I eatures, Ars, Pneur I gripper	ND EFFECTORS  Drives – Electrical Applications and Communication and Hydraulic s, selection and design	Drives mparis Gripp gn con	s – D son of pers, l	s, tra .C. S f All Magr	9 servo Motors, These Drives. These grippers, as of a gripper 9				
Pneumatic Driv Stepper Motor, End Effectors - vacuum grippe Unit 4	es.  ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mechanical Grippe Grippers – Mechanical Grippers, internal grippers and external	AND Expandical II catures, Arrs, Pneur II gripper	ND EFFECTORS  Drives – Electrical in Applications and Communication and Hydraulical in Section and designations, non-contact sections.	Drives mparis Gripp gn con	s – D son opers, l nsider	S, tra	pervo Motors, These Drives. These grippers, as of a gripper 9 siderations in				
Pneumatic Driving Stepper Motor, End Effectors - vacuum grippe  Unit 4  Force sensors, robotic cell, prince Stepper Motor, end Effectors - vacuum grippe Unit 4	rs, internal grippers and external SENSORS IN ROBOTS touch and tactile sensors, proximoximity sensors, fail safe hazar	AND Expandical I statures, Arrs, Pneur ll gripper mity sensor d sensor	ND EFFECTORS  Drives – Electrical Applications and Commatic and Hydraulic stands, selection and designations, non-contact ser systems, and command com	Drives mparis Gripp gn con nsors, plianc	s – D son obers, l safety	S, tra	9 servo Motors, These Drives. These Drives. These of a gripper 9 siderations in the family of the f				
Pneumatic Driving Stepper Motor, End Effectors - vacuum grippe Unit 4  Force sensors, robotic cell, provision system	es.  ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mechanical Grippers – Mechanical Grippers, internal grippers and external SENSORS IN ROBOTS  touch and tactile sensors, proxir	AND Expandical I catures, Arrs, Pneur l gripper mity sensor d sensor and d	ND EFFECTORS  Drives – Electrical implications and Communication and Hydraulical implication and designation and designation and communication implication image data	Drives mparis Gripp gn con nsors, plianc a – si	s – D son or bers, l nsider safety	S, tra	pervo Motors, These Drives. These Drives. These drippers, as of a gripper  9 siderations in asm. Machine tersion, image				
Pneumatic Drives Stepper Motor, End Effectors - vacuum grippe Unit 4  Force sensors, robotic cell, provision system storage, lighting	ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mechanical Grippers – Mechanical Grippers, internal grippers and external SENSORS IN ROBOTS  touch and tactile sensors, proximoximity sensors, fail safe hazar-camera, frame grabber, sensing	AND Expandical II catures, A rs, Pneur ll gripper mity sensor d sensor and dang and dang and a	ND EFFECTORS  Drives – Electrical Applications and Commatic and Hydraulic stands, selection and designations, non-contact sense as systems, and commissiving image data analysis – data reduced.	Drives mparis Gripp gn con nsors, pliance a – signetion	s – D son of bers, I safety e me gnal	.C. S f All ' Magratior y con chanic	9 dervo Motors, These Drives. These Drives. These drippers, as of a gripper 9 siderations in tism. Machine tersion, image ation, feature				
Pneumatic Drives Stepper Motor, End Effectors - vacuum grippe Unit 4  Force sensors, robotic cell, provision system storage, lighting	ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mechanical Grippers – Mechanical Grippers, internal grippers and external SENSORS IN ROBOTS  touch and tactile sensors, proximoximity sensors, fail safe hazar-camera, frame grabber, sensing techniques, image processing techniques, other algorithm	AND Expandical II catures, A rs, Pneur ll gripper mity sensor d sensor and dang and dang and a	ND EFFECTORS  Drives – Electrical Applications and Commatic and Hydraulic stands, selection and designations, non-contact sense as systems, and commissiving image data analysis – data reduced.	Drives mparis Gripp gn con nsors, pliance a – signetion	s – D son of bers, I safety e me gnal	.C. S f All ' Magratior y con chanic	9 dervo Motors, These Drives. These Drives. These of a gripper  9 siderations in tism. Machine tersion, image that the particular in the				
Pneumatic Dri Stepper Motor, End Effectors - vacuum grippe Unit 4  Force sensors, robotic cell, pr vision system storage, lightir extraction, obje	ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mechanical Grippers – Mechanical Grippers, internal grippers and external SENSORS IN ROBOTS  touch and tactile sensors, proximoximity sensors, fail safe hazar-camera, frame grabber, sensing techniques, image processing techniques, other algorithm	AND Expandical I catures, Arrs, Pneur l gripper mity sensor and dang and a s, applic	ND EFFECTORS  Drives – Electrical implications and Communic and Hydraulic implications, selection and designations, non-contact sensitives, and communications image data analysis – data reductions – Inspection,	Drives mparis Gripp gn con nsors, pliance a – sign ident	s – D son of bers, I safety e me gnal	.C. S f All ' Magratior y con chanic	9 dervo Motors, These Drives. These Drives. These drippers, as of a gripper 9 siderations in tism. Machine tersion, image ation, feature				
rotation matric  Unit 3  Pneumatic Dri Stepper Motor, End Effectors - vacuum grippe  Unit 4  Force sensors, robotic cell, pr vision system storage, lightin extraction, obje and navigation  Unit 5	ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mechanical Grippers Grippers – Mechanical Grippers, internal grippers and external  SENSORS IN ROBOTS  touch and tactile sensors, proximoximity sensors, fail safe hazar camera, frame grabber, sensing techniques, image processing techniques, other algorithms	AND Expandical Interactions, And Expansion Interactions, And Interaction Interactions, And Interaction Interactions, And Interaction Interactions, And Interaction	Drives – Electrical Applications and Commatic and Hydraulic standing, selection and designations, non-contact serence systems, and commingitizing image data analysis – data reductions – Inspection,	Drives mparis Gripp gn con nsors, plianc a – signiction ident	s - D son of pers, I safety e me gnal , seguificat	S, tra	panslation and  gervo Motors, These Drives. The service of th				
rotation matric  Unit 3  Pneumatic Dri Stepper Motor, End Effectors- vacuum grippe  Unit 4  Force sensors, robotic cell, pr vision system storage, lightir extraction, obje and navigation  Unit 5  Teach pendant	ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mech A.C. Servo Motors – Salient Fe Grippers – Mechanical Grippe rs, internal grippers and external SENSORS IN ROBOTS  touch and tactile sensors, proxinoximity sensors, fail safe hazar camera, frame grabber, sensing techniques, image processing ect recognition, other algorithm  PROGRAMMING AND AP	AND Expandical II catures, A rs, Pneur II gripper mity sensor and	ND EFFECTORS  Drives – Electrical implications and Communicate and Hydraulical implications, selection and desired implications, non-contact sensitive image data inalysis – data reductions – Inspection, artions – Inspection, implications – Inspection – In	Drives mparis Gripp gn con nsors, pliance a – significant ident	s - D son of bers, I safety e me gnal segnal ificat	.C. S f All ' Magration chanic	parameter of the service of a gripper of the service of the servi				
rotation matric  Unit 3  Pneumatic Dri Stepper Motor, End Effectors - vacuum grippe  Unit 4  Force sensors, robotic cell, pr vision system storage, lightin extraction, obje and navigation  Unit 5  Teach pendant programming -	ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mechanical Grippe Grippers – Mechanical Grippers, internal grippers and external SENSORS IN ROBOTS  touch and tactile sensors, proximoximity sensors, fail safe hazar camera, frame grabber, sensing techniques, image processing techniques, image processing techniques, other algorithm  PROGRAMMING AND AP  programming, lead through	AND Expansion and a second and	Applications and Commatic and Hydraulic s, selection and designations, non-contact ser systems, and commiting image data analysis – data reductions – Inspection, and comming, robot programming, robot pro	Drives mparis Gripp gn con nsors, plianc a – sign ident ramm	safety e me gnal saficat	S, tra	Pervo Motors, These Drives. The Drives. The				
rotation matric  Unit 3  Pneumatic Dri Stepper Motor, End Effectors - vacuum grippe  Unit 4  Force sensors, robotic cell, pr vision system storage, lightin extraction, obje and navigation  Unit 5  Teach pendant programming -	ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mech A.C. Servo Motors – Salient Fe Grippers – Mechanical Grippe rs, internal grippers and external SENSORS IN ROBOTS  touch and tactile sensors, proxinoximity sensors, fail safe hazar camera, frame grabber, sensing techniques, image processing tect recognition, other algorithm  PROGRAMMING AND AP  programming, lead through Motion Commands, Sensors co	AND Expansion and a second and	Applications and Commatic and Hydraulic s, selection and designations, non-contact ser systems, and commiting image data analysis – data reductions – Inspection, and comming, robot programming, robot pro	Drives mparis Gripp gn con nsors, plianc a – sign ident ramm	safety e me gnal saficat	S, tra	servo Motors, These Drives. T				
rotation matric  Unit 3  Pneumatic Dri Stepper Motor, End Effectors - vacuum grippe  Unit 4  Force sensors, robotic cell, pr vision system storage, lightin extraction, obje and navigation  Unit 5  Teach pendant programming -	ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mechanical Grippe A.C. Servo Motors – Salient Fe Grippers – Mechanical Grippe rs, internal grippers and external SENSORS IN ROBOTS  touch and tactile sensors, proximoximity sensors, fail safe hazar camera, frame grabber, sensing techniques, image processing ect recognition, other algorithm  PROGRAMMING AND AP programming, lead through Motion Commands, Sensors coss in inspection, assembly, mater	AND Expansion and a second and	Applications and Commatic and Hydraulic s, selection and designations, non-contact ser systems, and commiting image data analysis – data reductions – Inspection, and comming, robot programming, robot pro	Drives mparis Gripp gn con nsors, plianc a – sign ident ramm	safety e me gnal saficat	S, tra	parental and paren				
rotation matric  Unit 3  Pneumatic Dri Stepper Motor, End Effectors - vacuum grippe  Unit 4  Force sensors, robotic cell, pr vision system storage, lightir extraction, obje and navigation  Unit 5  Teach pendant programming - Role of robot	ROBOT DRIVE SYSTEMS  ves – Hydraulic Drives – Mechanical Grippe A.C. Servo Motors – Salient Fe Grippers – Mechanical Grippe rs, internal grippers and external SENSORS IN ROBOTS  touch and tactile sensors, proximoximity sensors, fail safe hazar camera, frame grabber, sensing techniques, image processing ect recognition, other algorithm  PROGRAMMING AND AP programming, lead through Motion Commands, Sensors coss in inspection, assembly, mater	AND Expansion And Example And And Expansion And And And And And And And And And An	ND EFFECTORS  Drives – Electrical implications and Communicate and Hydraulical street, selection and designations of the construction of the communication o	Drives mparis Gripp gn con mance are are	safety e me gnal safety ing las, an	.C. S f All ' Magration y con chanic converse ion, v	pervo Motors, These Drives. Th				

2	Mikell P Groover, "Industrial Robotics - Technology, Programming and applications",
	McGraw Hill, 2 <sup>nd</sup> edition 2012.
REFERI	ENCES
1	Fu K.S. Gonalz R.C. and Ice C.S.G, "Robotics Control, Sensing, Vision and Intelligence",
	McGraw Hill book co. 2007.
2	Yoram Koren, "Robotics for Engineers", McGraw Hill Book, Co., 2002.
3	Janakiraman P.A., "Robotics and Image Processing", Tata McGraw Hill 2005.
4	John. J. Craig, "Introduction to Robotics: Mechanics and Control" 2nd Edition, 2002.
5	Jazar, "Theory of Applied Robotics: Kinematics, Dynamics and Control", Springer India
	reprint, 2010.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Interpret the features of robots and technology involved in the	K2
	control.	
CO2	Apply the basic engineering knowledge and laws for the design	K2
	of robotics.	
CO3	Explain the basic concepts like various configurations,	K2
	classification and parts of end effectors compare various end	
	effectors and grippers and tools and sensors used in robots.	
CO4	Explain the concept of kinematics, degeneracy, dexterity and	K2
	trajectory planning.	
CO5	Demonstrate the image processing and image analysis techniques	K2
	by machine vision system.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1				sella				1			3
CO2	3	2	1	1								1			3
CO3	3	2	1	1	7	SRII	PEH	JIVI	SUD	llR .	2	1			3
CO4	3	2	1	1	7	5	TOT	20	11	1		1			3
CO5	3	2	1	1			COL		1 2 2			1			3

	AME309 - AUTOMATION LABORATORY											
Programme BE & MECH Sem. Category L T P												
& Branch												
		7	PC	0	0	4	2					
Preamble	To know the method of progra	mming	the microprocessor an	d al	so the	e desi	ign, modeling					
	& analysis of basic electrical, hydraulic & pneumatic Systems which enable the students											
	to understand the concept of mechatronics.											
LIST OF EXPERIMENTS												

- 1. Assembly language programming of 8085 Addition Subtraction Multiplication Division Sorting Code Conversion.
- 2. Stepper motor interface.
- 3. Traffic light interface.
- 4. Speed control of DC motor.
- 5. Study of various types of transducers.
- 6. Study of hydraulic, pneumatic and electro-pneumatic circuits.
- 7. Modelling and analysis of basic hydraulic, pneumatic and electrical circuits using Software.
- 8. Study of PLC and its applications.
- 9. Study of image processing technique.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the e	nd of the course, learners will be able to	Level
CO1	Demonstrate the functioning of mechatronics systems with	К3
	various pneumatic, hydraulic and electrical systems.	
CO2	Demonstrate the microcontroller and PLC as controllers in	К3
	automation systems by executing proper interfacing of I/O	
	devices and programming.	
CO3	Demonstrate the functioning of Image processing.	К3

#### **CO-PO Mapping**

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	3	1	1	0	2//		$\int_{\mathcal{C}}$	3	125		3	1	1	3
CO2	2	3	1	1		CAL.			3	elli .		3	1	1	3
CO3	2	3	3	3			S/F Di	scipli	3			3	3	3	3

	AME310 - SIMULATION AND ANALYSIS LABORATORY												
Programme	Programme BE & MECH Sem. Category L T P C												
& Branch													
		7		PC	0	0	4	2					
Preamble	Preamble > To give exposure to software tools needed to analyze engineering problems.												
To expose the students to different applications of simulation and analysis tools.													

#### LIST OF EXPERIMENTS – SIMULATION

- 1. MATLAB basics, Dealing with matrices, Graphing-Functions of one variable and two variables
- 2. Use of Matlab to solve simple problems in vibration
- 3. Mechanism Simulation using Multibody Dynamic software

#### LIST OF EXPERIMENTS – ANALYSIS

- 1. Force and Stress analysis using link elements in Trusses, cables etc.
- 2. Stress and deflection analysis in beams with different support conditions.

- 3. Stress analysis of flat plates and simple shells.
- 4. Stress analysis of axi symmetric components.
- 5. Thermal stress and heat transfer analysis of plates.
- 6. Thermal stress analysis of cylindrical shells.
- 7. Vibration analysis of spring-mass systems.
- 8. Model analysis of Beams.
- 9. Harmonic, transient and spectrum analysis of simple systems.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Simulate the working principle of air conditioning system,	К3
	hydraulic and pneumatic cylinder and cam follower mechanisms	
	using MATLAB.	
CO2	Analyze the stresses and strains induced in plates, brackets and	K4
	beams and heat transfer problems.	
CO3	Calculate the natural frequency and mode shape analysis of 2D	К3
	components and beams.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	3	2	2	1	1		A			X	2	1	1	3
CO2	2	3	2	2	1	1					27	2	1	1	3
CO3	2	3	2	2	1	1	(PO)		賽 `	1/.5	7	2	1	1	3





	AME311 - PROJECT WORK													
Programme & Branch	BE & MECH	Sem.	Category	L	Т	P	С							
		8	EEC	0	0	12	10							
Preamble	> To develop the abili	ty to solve a s	specific problem r	ight fro	om its	s iden	tification and							

- literature review till the successful solution of the same. To train the students in preparing project reports and to face reviews and viva voce examination.
- The students in a group of 4 in maximum and 1 in minimum works on a topic approved by the head of the department under the guidance of a faculty member and prepares a comprehensive project report after completing the work to the satisfaction of the supervisor. The progress of the project is evaluated based on a minimum of three reviews. The review committee may be constituted by the Head of the Department. A project report is required at the end of the semester. The project work is evaluated based on oral presentation and the project report jointly by external and internal examiners constituted by the Head of the Department.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the e	nd of the course, learners will be able to	Level
CO1	Improve their understating more towards real problem.	К3
CO2	Solve the subjective problem using latest available technology.	K4
CO3	Understand different perspective of problem-solving using software tools.	K2
CO4	Prepare documentation for the solution.	K2

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	3	2	2 <	1	1	2	2	2	2	1	2	1	1	3
CO2	2	3	2	2	1	1	2	2	2	2	1	2	1	1	3
CO3	2	3	2	2	1	1	2	2	2	2	1	2	1	1	3
CO4	1	2	1	1	3	1	1	1	3	3	2	2	1	1	1



Programm & Branch Preamble		Sem.	Category	L	T	P	C								
Preamble		nch													
Preamble		5	PE	3	0	0	3								
	> To introduce the basics	of 6 SIG	MA				l								
	> To learning about the le	an manu	facturing tools.												
	To study about the deep	er under	standing methodolo	gies o	f Lea	n ma	nufacturing.								
	To study the lean conce	pts and it	s elements.												
	To learn implementation	n and cha	llenges of lean mar	ufacti	ıring	•									
Unit 1	BASICS OF 6 SIGMA						9								
Introduction	to 6 Sigma, basic tools of six si	igma like	problem solving a	approa	ch, s	tanda	ard deviation,								
normal distr	ibution, various sigma levels with	n some e	xamples, value for	the en	terpr	ise, V	Variation, and								
sources of v	ariation, Mean and moving the me	ean, Vario	ous quality costs, co	st of p	oor o	qualit	y.								
Unit 2	INTRODUCTION TO LEA	N MAN	UFACTURING TO	OOLS	,		9								
Process Cap	ability Indices, Cause and Effect	diagram	Control Charts, Ir	ntrodu	ction	to F	MEA, APQP,								
PPAP. 3 fou	ndational 6 Sigma methodologies:	DMAIC	, DMEDI, and Proc	ess M	anag	emer	nt DMEDI for								
process crea	tion, DMAIC for process improve	ement and	l <mark>PDCA</mark> for s <mark>u</mark> staini	ng im	prove	emen	ts.								
Unit 3	LEAN ELEMENTS						9								
Introduction	to Lean Concepts like In-Built Qu	uality, Co	ncept of Right Part	at the	Righ	t Tin	ne, Lead Time								
reduction, C	ptimum utilization of Capital, Opt	imum uti	lization of People. U	Jnders	tandi	ng th	e Zero-defect								
concept and	Metrics, Focus on Human Re	sources,	Quality, Delivery,	Cost.	Bui	lding	Zero defect								
capabilities,	Cultural and Organizational aspec	ets													
Unit 4	DEEPER UNDERSTANDIN	NG MET	HODOLOGIES				9								
What is a pr	ocess, Why Process management,	Keys to p	rocess managemen	t, Diff	erenc	e bet	ween process								
managemen	t and 6 Sigma, Introduction to Den	ning cycl	e, PDCA, DMAIC	and co	ntinu	ious i	improvement,								
DMEDI for	creation process, DMAIC Vs DI	MEDI wi	th examples, Introd	duction	n to '	Toyo	ta Production								
System, Six	Sigma and Production System int	egration	ine												
Unit 5	IMPLEMENTATION AND	CHALL	ENGES				9								
Implementin	ng Checks and Balances in the pro	cess, Ro	oust Information Sy	stems	, Das	shboa	ard, follow up								
and robust c	orrective and preventive mechanis	sm. Conc	ept of Audits, and c	ontinu	ious i	impro	ovement from								
gap analysis	, risk assessments etc.	STD. 2													
		OID. Z					Total: 45								
TEXTBOO	KS														
1 J	M Juran & F M Gryna, "Quality P	Planning a	and Analysis", Tata	Mc G	raw I	Hill									
2 A	khilesh N. Singh, "Lean Manufact	turing: Pr	inciples to Practice	", Bib	lioph	ile S	outh Asia								
3 T	ne Toyota Way: 14 Management P	rinciples													
4 G	emba, "Kaizen: A Commonsense	Approach	to a Continuous In	nprove	emen	t Stra	ategy"								
		_ = =					= -								
REFEREN			111 1 1 1		•	/1									
REFEREN	uality Council of India https://qcin	ı.org/ & it	s library. https://qci	n.org/	nbqp.	/knov	wledge_bank/								
REFEREN 1 Q	uality Council of India https://qcin ternational Society of Six Sigma I						wledge_bank/								

Older / Previous editions of AIAG manuals on APQP, FMEA and PPAP. These are great sources of information on Quality Planning and has basics of Project Management and required skills.

	E OUTCOMES: nd of the course, learners will be able to	Bloom's Taxonomy Level
CO1	Discuss the basics of 6 SIGMA.	K2
CO2	Elaborate the lean manufacturing tools.	K2
CO3	Discuss lean concepts and its elements.	K2
CO4	Illustrate about the deeper understanding methodologies of Lean manufacturing.	K2
CO5	Describe the implementation and challenges of lean manufacturing.	K2

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	2	1	1						3	1	1	2	1
CO2	1	1	2	1	1	4					3	1	1	2	1
CO3	1	1	2	1	1						3	1	1	2	1
CO4	1	1	2	1	1				₩		3	1	1	2	1
CO5	1	1	2	1	1		(1) (1)		實 .	, go	3	1	1	2	1

	AME502 - PROCESS PLA	NNING	AND COST ESTI	MAT	ION	Ī	
Programme	BE & MECH	Sem.	Category	L	T	P	$\mathbf{C}$
& Branch	SHIPE	num					
	T ES	T 5 9	PE	3	0	0	3
Preamble	To understand the application	of com	puters in various as	pects	of N	<b>I</b> anuf	acturing viz.,
	Design, Proper planning, Man	ufacturir	ng cost, Layout & M	ateria	ıl Ha	ndlin	g system.
Unit 1	INTRODUCTION						9
Introduction o	f Process Planning- methods	of proc	ess planning, draw	ing i	nterp	oretat	ion. Material
evaluation, step	ps in process selection, production	on equip	ment and tooling se	lectio	n.		
Unit 2	PROCESS PLANNNING AC	CTIVIT	IES				9
Process planning	ng activities- process parameter	calculati	on for various produ	ıctior	pro	cesses	s, selection of
jigs and fixture	es. selection of quality assurance	method	s, documents for pro	ocess	planı	ning,	economics of
process planning	ng, case studies						
Unit 3	INTRODUCTION TO COST	T ESTIN	MATION				9

Introduction to cost estimation- importance of costing and estimation, methods of costing, elements of cost estimation. types of estimates, estimating procedure, estimation of labor cost, material cost, allocation of overhead charges, calculation of depreciation cost.

#### Unit 4 MACHINING TIME CALCULATIONS 9

Machining time estimation- importance of machine time calculation, machining time for different lathe operations, drilling and boring time calculations. Machining time calculation for Milling, Shaping, Planning and Grinding.

#### Unit 5 PRODUCTION COST ESTIMATIONS

9

Production costs- different production processes for different jobs, estimation of forging cost, estimation of welding cost, estimation of machining cost

**Total: 45** 

#### **TEXTBOOKS**

- Peter scalon, "Process planning, Design/Manufacture Interface", Elsevier science technology Books, Dec 2002.
- 2 Sinha B.P, "Mechanical Estimating and Costing", Tata-McGraw Hill publishing co, 1995.

#### **REFERENCES**

- 1 Chitale A.V. and Gupta R.C., "Product Design and Manufacturing", 2nd Edition, PHI, 2002.
  2 Ostwalal P.F. and Munez J., "Manufacturing Processes and systems", 9 th Edition, John Wiley,
- Ostwalal P.F. and Munez J., "Manufacturing Processes and systems", 9 th Edition, John Wiley, 1998.
- Russell R.S and Tailor B.W, "Operations Management", 4th Edition, PHI, 2003.
- 4 Mikell P. Groover, "Automation, Production, Systems and Computer Integrated Manufacturing", Pearson Education 2001.
- 5 K.C. Jain & L.N. Aggarwal, "Production Planning Control and Industrial Management", Khanna Publishers 1990.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the er	nd of the course, learners will be able to	Level
CO1	Select the process, equipment and tools for various industrial products.	K2
CO2	Prepare process planning activity chart.	K3
CO3	Explain the concept of cost estimation.	K2
CO4	Calculate the machining time for various machining operations.	K4
CO5	Compute the job order cost for different type of shop floor.	K4

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2					1		1	1	2	1	1
CO2	3	3	2	1					1		1	1	2	1	1

CO3	3	3	2	2			1	1	1	2	1	1
CO3	נ	נ	2				1	1	1	2	1	1
CO4	3	3	2	2			1	1	1	2	1	1
CO5	3	3	2	2			1	1	1	2	1	1
				ĺ	ĺ	ĺ		1	1	1	1	

	DE A SEECH			1 -	75		~		
Programme & Branch	BE & MECH	Sem.	Category	L	T	P	С		
		5	PE	3	0	0	3		
Preamble	To understand the applicatio	-	•	•					
	Design, Proper planning, Ma	nufacturir	ng cost, Layout & N	<b>l</b> ateria	al Ha	ndlin	g system.		
Unit 1	INRODUCTION	DDL	0.0.0				9		
Brief introduct	ion to CAD and CAM – Manut	facturing	Planning, Manufact	uring	contr	ol- Iı	ntroduction to		
CAD/CAM - C	Concurrent Engineering-CIM c	concepts -	- Computerised eler	nents	of CI	M sy	stem – Types		
of production -	- Manufacturing models and M	1etrics – N	Mathematical mode	ls of F	Produ	ction	Performance		
<ul> <li>Simple prob</li> </ul>	lems – Manufacturing Contro	l – Simpl	e Problems – Basi	c Elei	nents	of a	n Automated		
system – Level	ls of Automation – L <mark>e</mark> an Produ	ction and	Just-In-Time Produ	ction.					
Unit 2	PRODUCTION PLANNIN	G AND C	CONTROL AND				9		
	COMPUTERISED PROCE	ESS PLAI	NNING						
Process planni	ng - Computer Aided Proces	s Plannin	ig (CAPP) – Logic	al ste	ps in	Coı	nputer Aided		
Process Planni	ng - Aggregate Production P	lanning a	and the Master Pro	ductio	n Sc	hedu	le – Materia		
Requirement p	lanning – Capacity Planning-	Control S	ystems-Shop Floor	Cont	rol-Ir	vent	ory Control -		
Requirement planning – Capacity Planning- Control Systems-Shop Floor Control-Inventory Control – Brief on Manufacturing Resource Planning-II (MRP-II) & Enterprise Resource Planning (ERP) - Simple									
	tacturing Resource Planning-II	(MRP-II)	& Enterprise Reso	urcc r		•	2KP) - Simple		
Brief on Manuf	facturing Resource Planning-II	(MRP-II)	) & Enterprise Reso	urce r			ERP) - Simple		
Brief on Manuf	cellular Manufact		) & Enterprise Reso				9		
Brief on Manut Problems. Unit 3		URING					9		
Brief on Manual Problems.  Unit 3  Group Technol	CELLULAR MANUFACT	URING rts Classif	fication and coding	– Sir	nple	Prob	9 lems in Opitz		
Brief on Manut Problems.  Unit 3  Group Technol Part Coding sy	CELLULAR MANUFACT logy (GT), Part Families – Par	URING rts Classif	fication and coding	– Sir g – Co	nple	Problesite p	9 dems in Opita		
Brief on Manut Problems.  Unit 3  Group Technol Part Coding sy Machine cell	CELLULAR MANUFACT logy (GT), Part Families – Part extern – Production flow Analy	URING rts Classif rsis – Cell ative anal	fication and coding Jular Manufacturing Sysis in Cellular M	– Sir g – Co Ianufa	nple ompo	Problem Proble	9 lems in Opitz part concept - Rank Order		
Brief on Manut Problems.  Unit 3  Group Technol Part Coding sy Machine cell	CELLULAR MANUFACT logy (GT), Part Families – Part stem – Production flow Analy design and layout – Quantita	URING  rts Classif  vsis – Cell  ative anal  a GT cell -	fication and coding lular Manufacturing ysis in Cellular M - Hollier Method –	– Sir g – Co Ianufa	nple ompo	Problem Proble	9 lems in Opitz part concept - Rank Order		
Brief on Manut Problems.  Unit 3  Group Technol Part Coding sy Machine cell Clustering Met	CELLULAR MANUFACT logy (GT), Part Families – Part estem – Production flow Analy design and layout – Quantitation of the control of the contro	URING rts Classif rsis – Cell ative anal a GT cell -	Fication and coding Jular Manufacturing Jular Manufacturing Juliar Method – FIN AND	– Sir g – Co Ianufa	nple ompo	Problem Proble	9 lems in Opitz part concept - Rank Order		
Brief on Manuf Problems.  Unit 3  Group Technol Part Coding sy Machine cell Clustering Met Unit 4	CELLULAR MANUFACT logy (GT), Part Families – Part extern – Production flow Analy design and layout – Quantitathod - Arranging Machines in a	URING  rts Classif  rts Classif  rsis – Cell  ative anal  a GT cell -  URING SY  TEHICLE	fication and coding lular Manufacturing ysis in Cellular M - Hollier Method – YSTEM AND	– Sir – Co Ianufa Simpl	nple ompo	Probl site p ng –	9 lems in Opita part concept - Rank Orde is.		
Brief on Manuf Problems.  Unit 3  Group Technol Part Coding sy Machine cell of Clustering Met Unit 4  Types of Flexi	CELLULAR MANUFACT logy (GT), Part Families – Part stem – Production flow Analy design and layout – Quantita shod - Arranging Machines in a FLEXIBLE MANUFACTU AUTOMATED GUIDED V	URING  rts Classif  vsis – Cell  ative anal  a GT cell -  URING SY  EHICLE  ents – FM	fication and coding lular Manufacturing lular Manufacturing lysis in Cellular Manufacturing Hollier Method – YSTEM AND SYSTEM  IS Application & E	– Sir g – Co Ianufa Simpl	nple ompo acturi e Pro	Problem Proble	9 lems in Opital part concept - Rank Orders. 9		
Brief on Manut Problems.  Unit 3  Group Technol Part Coding sy Machine cell Clustering Met Unit 4  Types of Flexi Control – Quar	CELLULAR MANUFACT logy (GT), Part Families – Part vestem – Production flow Analy design and layout – Quantita shod - Arranging Machines in a FLEXIBLE MANUFACTU AUTOMATED GUIDED V bility - FMS – FMS Component	URING  rts Classif  vsis – Cell  ative anal  a GT cell -  URING SY  EHICLE  ents – FM	fication and coding dular Manufacturing ysis in Cellular Manufacturing Hollier Method – YSTEM AND SYSTEM  AS Application & Elems. Automated Guerral	– Sir g – Co Ianufa Simpl Benefit	nple ompo acturi e Pro	Problem FMS	9 lems in Opital part concept - Rank Orders. 9		

**TEXTBOOKS** 

1

Mikell P Groover "Automation, Production Systems and Computer Integrated Manufacturing", Prentice Hall of India, 2008.

**Total: 45** 

Effectors - Sensors in Robotics - Robot Accuracy and Repeatability - Industrial Robot Applications -

Robot Part Programming – Robot Accuracy and Repeatability – Simple Problems.

2	Radhakrishnan P, Subramanyan S.and Raju V., "CAD/CAM/CIM", 2nd Edition, New Age
	International (P) Ltd, New Delhi, 2000.
REFER	ENCES
1	Gideon Halevi and Roland Weill, "Principles of Process Planning – A Logical Approach"
	Chapman & Hall, London, 1995.
2	Kant Vajpayee S, "Principles of Computer Integrated Manufacturing", Prentice Hall India.
3	Rao. P, N Tewari &T.K. Kundra, "Computer Aided Manufacturing", Tata McGraw Hill
	Publishing Company, 2000.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Explain the basic concepts of CAD, CAM and computer	K2
	integrated manufacturing systems.	
CO2	Summarize the production planning and control and	K2
	computerized process planning.	
CO3	Differentiate the different coding systems used in group	K2
	technology.	
CO4	Explain the concepts of flexible manufacturing system (FMS) and	K2
	automated guided vehicle (AGV) system.	
CO5	Classification of robots used in industrial applications.	K1

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1		2	%		,O_		2					1
CO2	2	1	1		2		0/0		<u> </u>	2					1
CO3	2	1	1		2		"Di	scipli	UE !	2					1
CO4	2	1	1		2					2					1
CO5	2	1	1		2	mil	FR	IM	Riin	2	7				1

	AME504 - SUSTA	INADLE I	MANUFACTUR	ING					
Programme & Branch	BE & MECH	Sem.	Category	L	T	P	С		
		5	PE	3	0	0	3		
Preamble	<ul> <li>To provide knowledge</li> <li>To provide the studen</li> <li>To familiarize with tree</li> </ul>	<ul> <li>To be acquainted with sustainability in manufacturing and its evaluation.</li> <li>To provide knowledge in environment and social sustainability.</li> <li>To provide the student with the knowledge of strategy to achieve sustainability.</li> <li>To familiarize with trends in sustainable operations.</li> <li>To create awareness in current sustainable practices in manufacturing industry.</li> </ul>							
Unit 1	ECONOMIC SUSTAINAB	ILITY					9		

Industrial Revolution-Economic sustainability: globalization and international issues Sustainability status - Emerging issues- Innovative products- Reconfiguration manufacturing enterprises - Competitive manufacturing strategies - Performance evaluation- Management for sustainability - Assessments of economic sustainability

#### Unit 2 SOCIAL AND ENVIRONMENTAL SUSTAINABILITY

9

Social sustainability – Introduction-Work management -Human rights - Societal commitment - Customers -Business practices -Modelling and assessing social sustainability. Environmental issues pertaining to the manufacturing sector: Pollution - Use of resources -Pressure to reduce costs - Environmental management: Processes that minimize negative environmental impacts - environmental legislation and energy costs - need to reduce the carbon footprint of manufacturing Operations-Modelling and assessing environmental sustainability

#### Unit 3 | SUSTAINABILITY PRACTICES

9

Sustainability awareness - Measuring Industry Awareness-Drivers and barriers -Availability of sustainability indicators -Analysis of sustainability practicing -Modeling and assessment of sustainable practicing -Sustainability awareness -Sustainability drivers and barriers - Availability of sustainability indicators- Designing questionnaires- Optimizing Sustainability Indexes-Elements - Cost and time model.

#### Unit 4 MANUFACTURING STRATEGY FOR SUSTAINABILITY

9

Concepts of competitive strategy and manufacturing strategies and development of a strategic improvement programme - Manufacturing strategy in business success strategy formation and formulation - Structured strategy formulation - Sustainable manufacturing system design options - Approaches to strategy formulation - Realization of new strategies/system designs.

#### Unit 5 TRENDS IN SUSTAINABLE OPERATIONS

9

Principles of sustainable operations - Life cycle assessment manufacturing and service activities - influence of product design on operations - Process analysis - Capacity management - Quality management - Inventory management - Just-In-Time systems - Resource efficient design - Consumerism and sustainable well-being.

Total: 45

#### **TEXTBOOKS**

- Ibrahim Garbie, "Sustainability in Manufacturing Enterprises Concepts, Analyses and Assessments for Industry 4.0", Springer International Publishing., United States, 2016, ISBN-13: 978-3319293042.
- Davim J.P., "Sustainable Manufacturing", John Wiley & Sons., United States, 2010, ISBN: 978-1-848-21212-1.

#### REFERENCES

- Jovane F, Emper, W.E. and Williams, D.J., "The ManuFuture Road: Towards Competitive and Sustainable High-Adding-Value Manufacturing", Springer, 2009, United States, ISBN 978-3-540-77011-4.
- 2 Kutz M., "Environmentally Conscious Mechanical Design", John Wiley & Sons., United States, 2007, ISBN: 978-0-471-72636-4.
- Seliger G., "Sustainable Manufacturing: Shaping Global Value Creation", Springer, United States, 2012, ISBN 978-3-642-27289-9.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Discuss the importance of economic sustainability.	K2
CO2	Describe the importance of sustainable practices.	K2
CO3	Identify drivers and barriers for the given conditions.	K2
CO4	Formulate strategy in sustainable manufacturing.	K2
CO5	Plan for sustainable operation of industry with environmental, cost consciousness.	K2

CC	<b>)-PO</b> ]	Марр	ing												
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3		2				2	2		1	1	2	2	2	1
CO2	3						2			1	1	2	1	2	2
CO3	3						2	3		1	1	2	1	2	2
CO4	3		3				2			1	1	2	2	2	1
CO5	3		3				2	2		1	1	2	2	2	1
				4	KA			Ā			*				

				/A``								
	AME505 - PRECI	SION I	MANU	<b>IFACTURIN</b>	١G							
Programme	BE & MECH	Sem.		Category	L	T	P	C				
& Branch	Sol	50										
		Di5cip	ine	PE	3	0	0	3				
Preamble	> To study the need, sign	ificance	and p	rogress of pi	ecision	man	ufact	turing and				
	the different levels of n	nanufac	turing.									
	To study the principle ε	ınd wor	king of	f different m	ethods	of pr	ecisio	on machining.				
	To study the special construction requirements of precision machine tools.											
	To study the errors inv	olved i	n preci	sion machin	e tools	and	calcu	late the error				
	budgets for a given situ	ation.										
	> To study the Selecting	ng a si	uitable	measureme	ent sol	ution	to	measure and				
	characterize precision i	nachine	ed feati	ares.								
Unit 1	PRECISION ENGINEEERI	NG						9				
Introduction to	Precision Engineering, Need	for pre	cision	manufactur	ing, Ta	nigu	chi d	iagram, Four				
Classes of Ac	hievable Machining Accuracy	- Nor	mal, I	Precision, H	igh-pre	cisio	n, U	ltra-precision				
Processes and I	Nanotechnology.											
Unit 2	PRECISION MACHINING							9				

Overview of Micro- and Nanomachining, Conventional micro machining techniques - micro-turning, micro milling, micro-grinding, Ultra-precision diamond turning, Non-conventional micromachining techniques – AJM, WJM, USM, EDM, PCM, ECM, LBM, EBM, FIBM, etc.

## Unit 3 MACHINE DESIGN FOR PRECISION 9 MANUFACTURING 9

Philosophy of precision machine design, Ultra-Precision Machine Elements: Guide- ways, Drive Systems, Friction Drive, Linear Motor Drive, Spindle Drive. Bearings: Applications of Rolling, Hydrodynamic, Hydrostatic, Aerostatic and Magnetic bearings.

#### Unit 4 MECHANICAL AND THERMAL ERRORS 9

Sources of error, Principles of measurement, Errors due to machine elements, bearings, spindles, Kinematic design, Structural compliance. Vibration, Thermal errors – background, thermal effects, Environmental control of precision machinery. Error mapping and error budgets.

#### Unit 5 MEASUREMENT AND CHARACTERISATION 9

Optical dimensional metrology of precision features – Machine vision, multi-sensor coordinate metrology, Laser Tracking Systems, Laser scanners, White-Light Interference 3D Microscopes, Focus-Based Optical Metrology- Fringe projection method, Measurement of Typical Nano features. Surface metrology - 3D surface topography – Chromatic confocal Microscopy, Interferometry, Non-optical Scanning Microscopy – SEM, SPM, Parameters for characterizing 3D surface topography.

TEXTBOOKS

1 Jain, V.K., "Introduction to micromachining", Narosa publishers, 2018
2 Venktesh V.C., SudinIzman, "Precision Engineering", Tata McGraw Hill Publishing Company, New Delhi 2007.

REFERENCES
1 David Dornfeld, Dae-Eun Lee, "Precision Manufacturing", Springer, 2008.
2 Jain, V.K., "Micro manufacturing Processes", CRC Press, 2012.
3 Joseph McGeough, "Micromachining of Engineered Materials", Marcel Dekker Inc., 2002.
4 Kevin Harding, "Handbook of Optical Dimensional Metrology, Series: Series in Optics and

Murty, R.L., "Precision Engineering in Manufacturing", New Age publishers, 2005

optoelectronics", Taylor & Francis, 2013.

5

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Explain the need, significance and progress of precision	K2
	manufacturing and the different levels of manufacturing.	
CO2	Explain the principle and working of different methods of	K2
	precision machining.	
CO3	Explain the special construction requirements of precision	K2
	machine tools.	
CO4	Explain the errors involved in precision machine tools and	K2
	calculate the error budgets for a given situation.	
CO5	Select a suitable measurement solution to measure and	K3
	characterize precision machined features	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	2	2				1			1	2	2	1
CO2	2	2	2	2	2				1			1	2	2	1
CO3	2	2	2	2	2				1			1	2	2	1
CO4	2	2	2	2	2				1			1	2	2	1
CO5	2	2	2	2	2				1			1	2	2	1







	DE A MEGN			-	m	ъ	
Programme & Branch	BE & MECH	Sem.	Category	$\mathbf{L}$	T	P	С
	,	7	PE	3	0	0	3
Preamble	<ul> <li>To understand the comperception, cognition</li> <li>To consider ergonomic</li> <li>To apply ergonomic</li> <li>To apply environme</li> <li>To develop aesthetic</li> </ul>	on, motor continues concept is in design of ental factors in the applicable	trol etc in manufacturing f controls and dis n ergonomics des to manufacturing	play ign.			
Unit 1	FUNDAMENTALS OF E FACTORS ENGINEERIN		CS AND HUMA	N			9
Human Biolog	ical- Ergonomic and psychological	ogical capabil	ities and limitatio	ns-Co	ncept	ts of l	numan factors
engineering an	d Ergonomics-Man-Machine	e system and	Design philosop	hy-Phy	ysical	l wor	k and energy
expenditure: M	Ianual lifting-Work posture-	Repetitive mo	otion- Provision	of ener	rgy fo	or mu	ıscular work-
Heat stress-Ro	le of oxygen physical exerti	on, -Measure	ment of energy	expend	iture	-Resp	piration-Pulse
rate and blood	pressure during physical wor	k-Physical w	ork capacity and	its eva	luatio	on.	
Unit 2	ANTHROPOMETRY AN	D ERCONO	MIC DESIGN				9

seeing, Psychology of seeing, Figure on ground effect, Gestalt's perceptions – Simplicity, Regularity, Proximity, Wholeness. Optical illusions, Influences of line and form.

Unit 3 DESIGN PRINCIPLES FOR DISPLAY AND CONTROLS 9

Displays: Design Principles of visual Displays, Classification, Quantitative displays, Qualitative displays, check readings, Situational awareness, Representative displays, Design of pointers, Signal and warning lights, colour coding of displays, Design of multiple displays Controls: Design considerations, Controls with little efforts – Push button, Switches, rotating Knobs. Controls with muscular effort – Hand wheel, Crank, Heavy lever, Pedals. Design of controls in automobiles, Machine Tools.

#### Unit 4 ENVIRONMENTAL FACTORS 9

Colour: Colour and light, Colour and objects, Colour and the eye – after Image, Colour blindness, Colour constancy, Colour terms – Colour circles, Munsel colour notation, reactions to colour and colour combination – colour on engineering equipment, Colour coding, psychological effects, colour and machine form, colour and style.

#### Unit 5 AESTHETIC CONCEPTS

Concept of unity, Concept of order with variety, Concept of purpose, Style and environment, Aesthetic expressions – Symmetry, Balance, Contrast, Continuity, Proportion. Style – The components of style, House style, Style in capital good. Introduction to Ergonomic and plant layout software's, total layout design.

Total: 45

#### **TEXTBOOKS**

Marcelo M. Soares, Francisco Rebelo, "Ergonomics in Design: Methods and Techniques (Human Factors and Ergonomics)"

REFERENCES  1 Benjamin W.Niebel, "Motion and Time Study", Richard D. Irwin Inc., 7 <sup>th</sup> Edition, 2002  2 Brain Shakel, "Applied Ergonomics Handbook", Butterworth Scientific London 1988.  3 Bridger, R.C., "Introduction to Ergonomics", McGraw Hill Publications, 2 <sup>nd</sup> Edition, 2003.  4 Martin Helander, "A Guide to human factors and Ergonomics", Taylor and Francis, 2006  5 Mayall W.H. "Industrial design for Engineers", London Hiffee books Ltd., 1988.	2	"Ergonomics in Product Design", Send points Publishing Co. Ltd
2 Brain Shakel, "Applied Ergonomics Handbook", Butterworth Scientific London 1988. 3 Bridger, R.C., "Introduction to Ergonomics", McGraw Hill Publications, 2 <sup>nd</sup> Edition, 2003. 4 Martin Helander, "A Guide to human factors and Ergonomics", Taylor and Francis, 2006	REFERI	ENCES
3 Bridger, R.C., "Introduction to Ergonomics", McGraw Hill Publications, 2 <sup>nd</sup> Edition, 2003. 4 Martin Helander, "A Guide to human factors and Ergonomics", Taylor and Francis, 2006	1	Benjamin W.Niebel, "Motion and Time Study", Richard D. Irwin Inc., 7 <sup>th</sup> Edition, 2002
4 Martin Helander, "A Guide to human factors and Ergonomics", Taylor and Francis, 2006	2	Brain Shakel, "Applied Ergonomics Handbook", Butterworth Scientific London 1988.
	3	Bridger, R.C., "Introduction to Ergonomics", McGraw Hill Publications, 2 <sup>nd</sup> Edition, 2003.
5 Mayall W.H. "Industrial design for Engineers", London Hiffee books Ltd., 1988.	4	Martin Helander, "A Guide to human factors and Ergonomics", Taylor and Francis, 2006
	5	Mayall W.H. "Industrial design for Engineers", London Hiffee books Ltd., 1988.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Appreciate ergonomics need in the industrial design.	K2
CO2	Apply ergonomics in creation of manufacturing system	К3
CO3	Discuss on design of controls and display.	K2
CO4	Consider environmental factors in ergonomics design.	K2
CO5	Report on importance of aesthetics to manufacturing system and product.	K2

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1		1	3		2		<b>3</b>		1	2		1	1	3	3
CO2		1	3		2	16.	3	្ន	1	( Pa		1	1	3	3
CO3		1	3		2		3		1 6	3)		1	1	3	3
CO4		1	3		2		3	scipl	1			1	1	3	3
CO5		1	3		2		3		1			1	1	3	3
	SRIPERUMBUDUR														

	AME507 - COMUTER AIDED DESIGN & MANUFACTURING												
Programme	T	P	С										
& Branch													
		7	PE	3	0	0	3						
Preamble	<ul> <li>To provide an overvolute component design.</li> <li>To understand the approximation viz., Design, Proper playsystem.</li> </ul>	lication of	computers in vario	ous as	spects	s of M	Manufacturing						
Unit 1	INTRODUCTION						9						

Product cycle- Design process- sequential and concurrent engineering- Computer aided design – CAD system architecture- Computer graphics – co-ordinate systems- 2D and 3D transformations-homogeneous coordinates - Line drawing -Clipping- viewing transformation-Brief introduction to CAD and CAM – Manufacturing Planning, Manufacturing control- Introduction to CAD/CAM –CAD/CAM concepts —Types of production - Manufacturing models and Metrics – Mathematical models of Production Performance.

#### Unit 2 GEOMETRIC MODELING

9

Representation of curves- Hermite curve- Bezier curve- B-spline curves-rational curves-Techniques for surface modelling – surface patch- Coons and bicubic patches- Bezier and B-spline surfaces. Solid modelling techniques- CSG and B-rep.

#### Unit 3 | STANDARDS OF CAD

9

Standards for computer graphics- Graphical Kernel System (GKS) - standards for exchange images-Open Graphics Library (OpenGL) - Data exchange standards - IGES, STEP, CALS etc. - communication standards.

#### Unit 4 FUNDAMENTAL OF CNC AND PART PROGRAMMING

9

Introduction to NC systems and CNC - Machine axis and Co-ordinate system- CNC machine tools-Principle of operation CNC- Construction features including structure- Drives and CNC controllers- 2D and 3D machining on CNC- Introduction of Part Programming, types - Detailed Manual part programming on Lathe & Milling machines using G codes and M codes- Cutting Cycles, Loops, Sub program and Macros- Introduction of CAM package.

# Unit 5 FLEXIBLE MANUFACTURING SYSTEM (FMS) AND CELLULAR MANUFACTURING

9

Group Technology(GT),Part Families—Parts Classification and coding—Simple Problems in Opitz Part Coding system—Production flow Analysis—Cellular Manufacturing—Composite part concept—Types of Flexibility - FMS – FMS Components – FMS Application & Benefits – FMS Planning and Control—Quantitative analysis in FMS

**Total: 45** 

## TEXTBOOKS

- 1 Ibrahim Zeid, "Mastering CAD CAM", Tata McGraw-Hill Publishing Co, 2007
  - Mikell P Groover, "Automation, Production Systems and Computer Integrated Manufacturing", Prentice Hall of India, 2008.
  - Radhakrishnan P, Subramanyan S and Raju V, "CAD/CAM/CIM", 2nd Edition, New Age International (P) Ltd, New Delhi, 2000.

#### **REFERENCES**

- 1 Chris McMahon and Jimmie Browne "CAD/CAM Principles", "Practice and Manufacturing management", 2<sup>nd</sup> Edition, Pearson Education, 1999.
- 2 Donald Hearn and M. Pauline Baker, "Computer Graphics", Prentice Hall, Inc,1992.
- Foley, Wan Dam, Feiner and Hughes, "Computer graphics principles & practice", Pearson Education, 2003.
- William M Neumann and Robert F Sproul, "Principles of Computer Graphics", McGraw Hill Book Co. Singapore, 1989.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Explain the 2D and 3D transformations, clipping algorithm,	K2
	Manufacturing models and Metrics.	
CO2	Explain the fundamentals of parametric curves, surfaces and	K2
	Solids	
CO3	Summarize the different types of Standard systems used in CAD	K2
CO4	Apply NC & CNC programming concepts to develop part	К3
	programme for Lathe & Milling Machines	
CO5	Summarize the different types of techniques used in Cellular	K2
	Manufacturing and FMS.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2	1	1	1	1	1	2	2	2	2	2
CO2	3	2	2	2	2	1	1	1	1	1	2	2	2	2	2
CO3	3	2	2	2	2	1	1	1	1	1	2	2	2	2	2
CO4	3	2	2	2	2	1	1	1	1	1	2	2	2	2	2
CO5	3	2	2	2	2	1	1	1	1	1	2	2	2	2	2

		40	N AT									
	AME508 - PRODUCT	DESIG	NAND DEVELOP	MEN	T							
Programme	BE & MECH	Т	P	C								
& Branch	So											
		Oi7cip	PE	3	0	0	3					
Preamble	Preamble > To introduce the fundamental concepts of the new product development.											
	To develop material sp	pecificati	ons, analysis and pro	ocess.								
	To Learn the Feasibility Studies & reporting of new product development.											
	To study the New product qualification and Market Survey on similar products											
	of new product develo	pment.										
	To learn Reverse Engi	neering.	Cloud points general	tion, c	conve	erting	cloud data to					
	3D model.											
Unit 1	FUNDAMENTALS OF PRO	ODUCT	DEVELOPMENT				9					
Introduction –	Reading of Drawing – Grid rea	ding, Re	visions, ECN (Engg	. Cha	nge N	Note)	, Component-					
material grade,	Specifications, customer speci	fic requir	ements – Basics of r	nonit	oring	of N	PD applying-					
Gantt chart, C	Critical path analysis – Funda	amentals	of BOM (Bill of	Mate	rials	), En	gg. BOM &					
Manufacturing	-BOM. Basics of MIS softw	are and	their application i	n ind	lustri	es li	ke SAP, MS					
Dynamics, Ora	cle ERP Cloud– QFD.											
Unit 2	MATERIAL SPECIFICATI	IONS, A	NALYSIS & PROC	ESS			9					

Material specification standards – ISO, DIN, JIS, ASTM, EN, etc. – Awareness on various manufacturing process like Metal castings & Forming, Machining (Conventional, 3 Axis, 4 Axis, 5 Axis), Fabrications, Welding process. Qualifications of parts mechanical, physical & Chemical properties and their test report preparation and submission. Fundamentals of DFMEA & PFMEA, Fundamentals of FEA, Bend Analysis, Hot Distortion, Metal and Material Flow, Fill and Solidification analysis.

#### Unit 3 ESSENTIALS OF PRODUCT DEVELOPMENT

9

Request of Quotation Processing – Feasibility Studies & reporting – Cross Function Team discussion on new product and reporting – Concept design, Machine selection for tool making, Machining–Manufacturing Process selection, Machining Planning, cutting tool selection – Various Inspection methods– Manual measuring, CMM – Geometric Optical Measuring, Lay out marking and Cut section analysis. Tool Design and Detail drawings preparation, release of details to machine shop and CAM programming. Tool assembly and shop floor trials. Initial sample submission with PPAP documents.

#### Unit 4 | CRITERIONS OF PRODUCT DEVELOPMENT

9

New product qualification for Dimensions, Mechanical & Physical Properties, Internal Soundness proving through X-Ray, Radiography, Ultrasonic Testing, MPT, etc. Agreement with customer for testing frequencies. Market Survey on similar products, Risk analysis, validating samples with simulation results, Lesson Learned & Horizontal deployment in NPD.

## Unit 5 REPORTING & FORWARD THINKING OF PRODUCT DEVELOPMENT

,

Detailed study on PPAP with 18 elements reporting, APQP and its 5 Sections, APQP vs PPAP, Importance of SOP – Purpose & documents, deployment in shop floor. Prototyping & RPT - Concepts, Application and its advantages, 3D Printing – resin models, Sand cores for foundries; Reverse Engineering - Cloud points generation, converting cloud data to 3D model, Concurrent Engineering – Basics, Application and its advantages in NPD.

**Total: 45** 

	OF THE TOTAL								
TEXTBO	OOKS								
1	Product Development – Sten Jonsson								
2	Product Design & Development - Karl T. Ulrich, Maria C. Young, Steven D. Eppinger								
REFERI	REFERENCES								
1	Revolutionizing Product Development – Steven C Wheelwright & Kim B. Clark								
2	Toyota Product Development System – James Morgan & Jeffrey K. Liker								
3	Product Design & Value Engineering – Dr. M.A. Bulsara &Dr. H.R. Thakkar								
4	Winning at New Products – Robert Brands 3rd Edition.								
1 2 3	Revolutionizing Product Development – Steven C Wheelwright & Kim B. Clark Toyota Product Development System – James Morgan & Jeffrey K. Liker Product Design & Value Engineering – Dr. M.A. Bulsara &Dr. H.R. Thakkar								

COURS	E OUTCOMES:	Bloom's Taxonomy			
At the er	nd of the course, learners will be able to	Level			
CO1	Discuss fundamental concepts and customer specific	K2			
	requirements of the New Product Development.				
CO2	Discuss the Material specification standards, analysis and	K2			
	fabrication, manufacturing process.				
CO3	Develop Feasibility Studies & reporting of New Product	K4			
	development.				

CO4	Analyzing the New product qualification and Market Survey on	K4
	similar products of new product development.	
CO5	Develop Reverse Engineering, Cloud points generation,	K4
	converting cloud data to 3D model.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	3	1				1	1			1	1	3	2
CO2	1	1	3	1				1	1			1	1	3	2
CO3	1	1	3	1				1	1			1	1	3	2
CO4	1	1	3	1				1	1			1	1	3	2
CO5	1	1	3	1			·n	1	1	n		1	1	3	2

	AME509 - DESIGN OF JIGS AND FIXTURES											
Programme	BE & MECH	Sem.	Catego	ry L	T	P	C					
& Branch												
		7	PE	3	0	0	3					
Preamble	> To understand the fun	nctions a	nd design pr	inciples of	Jigs,	fixtu	res and press					
	tools.											
	To gain proficiency in	the deve	lopment of re	equired view	s of	the fi	nal design					
Unit 1	LOCATING AND CLAMPI	ING PRI	NCIPLES	8			9					

Objectives of tool design- Function and advantages of Jigs and fixtures – Basic elements – principles of location – Locating methods and devices – Redundant Location – Principles of clamping – Mechanical actuation – pneumatic and hydraulic actuation Standard parts – Drill bushes and Jig buttons – Tolerances and materials used.

#### Unit 2 JIGS AND FIXTURES

9

Design and development of jigs and fixtures for given component- Types of Jigs – Post, Turnover, Channel, latch, box, pot, angular post jigs – Indexing jigs – General principles of milling, Lathe, boring, broaching and grinding fixtures – Assembly, Inspection and Welding fixtures – Modular fixturing systems- Quick change fixtures.

#### Unit 3 PRESS WORKING AND ELEMENTS OF CUTTING DIES 9

Press Working Terminologies - operations – Types of presses – press accessories – Computation of press capacity – Strip layout – Material Utilization – Shearing action – Clearances – Press Work Materials – Center of pressure- Design of various elements of dies – Die Block – Punch holder, Die set, guide plates – Stops – Strippers – Pilots – Selection of Standard parts – Design and preparation of four standard views of simple blanking, piercing, compound and progressive dies.

#### Unit 4 BENDING AND DRAWING DIES

9

Difference between bending and drawing – Blank development for above operations – Types of Bending dies – Press capacity – Spring back – knockouts – direct and indirect – pressure pads – Ejectors – Variables affecting Metal flow in drawing operations – draw die inserts – draw beads- ironing – Design

and development of bending, forming, drawing, reverse redrawing and combination dies – Blank development for axisymmetric, rectangular and elliptic parts – Single and double action dies.

### Unit 5 FORMING TECHNIQUES AND EVALUATION

9

Bulging, Swaging, Embossing, coining, curling, hole flanging, shaving and sizing, assembly, fine Blanking dies – recent trends in tool design- computer Aids for sheet metal forming Analysis – basic introduction - tooling for numerically controlled machines- setup reduction for work holding – Single minute exchange of dies – Poka Yoke.

Total: 45
OOKS
Joshi, P.H. "Jigs and Fixtures", 2 <sup>nd</sup> Edition, Tata McGraw Hill Publishing Co., Ltd., New
Delhi, 2010.
Joshi P.H "Press tools - Design and Construction", wheels publishing, 1996
Venkataraman. K, "Design of Jigs Fixtures & Press Tools", Tata McGraw Hill, New Delhi,
2005.
INCES INCESTIFE OF TECHNOLOGY
ASTME Fundamentals of Tool Design Prentice Hall of India.
Design Data Handbook, PSG College of Technology, Coimbatore.
Donaldson, Lecain and Goold "Tool Design", 5th Edition, Tata McGraw Hill, 2017.
Hoffman "Jigs and Fixture Design", Thomson Delmar Learning, Singapore, 2004.
Kempster, "Jigs and Fixture Design", Third Edition, Hoddes and Stoughton, 1974.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Summarize the different methods of Locating Jigs and Fixtures	K2
	and Clamping principles.	
CO2	Design and develop jigs and fixtures for given component.	K4
	Solve Seri	
CO3	Discuss the press working terminologies and elements of cutting	K2
	dies.	
CO4	Distinguish between Bending and Drawing dies.	K2
	SKIPEHONDOUGR	
CO5	Discuss the different types of forming techniques.	K2

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3					3					3		
CO2	3	3	3					3					3		
CO3	3	3	3					3					3		
CO4	3	3	3					3					3		
CO5	3	3	3					3					3		

Programme & Branch	BE & MECH	Sem.	Category	L	T	P	C
	1	7	PE	3	0	0	3
Preamble	<ul> <li>To introduce economer for manufacturability engineering applicated in the design of cast.</li> <li>To learn design constamped, and forged.</li> <li>To learn design conditilled, milled, plane.</li> <li>To learn design conproducts.</li> </ul>	ty in the detions. Also, a products. sideration products. sideration products. sideration products, sideration products, sideration products.	velopment and deapply design consistency design consistency of forming the control of the contro	esign of derations in the deration of the dera	of proon proof the definition the definition.	oduct incip esign	les of casting of extruded
	To learn design cons products.	sideration pr	inciples of assemb	oly in t	he de	esign	of assembled
Unit 1	INTRODUCTION AND C	CASTING					9
Introduction	- Economics of process selection						
consideration	-			for ma	ınufa	ctura	bility; Desig
consideration Unit 2	s for: Sand cast – Die cast – Pe			for ma	ınufa	ctura	bility; Design
Unit 2 Design consi parts.	s for: Sand cast – Die cast – Pe  FORMING  derations for: Metal extruded p	ermanent mo	ld cast parts.				9 parts –Forgeo
Unit 2 Design consiparts. Unit 3	FORMING derations for: Metal extruded p  MACHINING derations for: Turned parts –	ermanent mo parts – Impac	ld cast parts.	arts –	Stam	iped j	9 parts –Forgeo
Unit 2 Design consiparts. Unit 3 Design consi	FORMING derations for: Metal extruded p  MACHINING derations for: Turned parts –	ermanent mo parts – Impac	ld cast parts.	arts –	Stam	iped j	9 parts –Forgeo
Unit 2 Design consiparts. Unit 3 Design consi Ground parts Unit 4 Arc welding Weldment &	FORMING derations for: Metal extruded p  MACHINING derations for: Turned parts –	parts – Impace Drilled part	the cast parts.  ct/Cold extruded parts.  s – Milled, plane on – Minimizing on considerations	arts –	Stam	and s	9 parts –Forgeo 9 slotted parts- 9 eld strength -
Unit 2 Design consiparts.  Unit 3 Design consign consi	FORMING derations for: Metal extruded p  MACHINING derations for: Turned parts –  WELDING – Design considerations for: heat treatment. Resistance well- eset weldment.	Drilled part  Cost reducti ding – Designer	tions – Minimizing	arts – ed, sha distor for: Sp	Stam  aped  tion  oot –	and :  - We Seam	9 slotted parts  9 eld strength 1 – Projection 9 arts – Design
Unit 2 Design consiparts.  Unit 3 Design consign consign consign consideration assembly.	FORMING derations for: Metal extruded p  MACHINING derations for: Turned parts –  WELDING – Design considerations for: heat treatment. Resistance welloset weldment.  ASSEMBLY ssembly – General assembly is for: Rivets – Screw fastenes.	Drilled part  Cost reducti ding – Designer	tions – Minimizing	arts – ed, sha distor for: Sp	Stam  aped  tion  oot –	and :  - We Seam	9 parts –Forged 9 slotted parts 9 eld strength – n – Projection 9 arts – Design – Automatic
Unit 2 Design consiparts.  Unit 3 Design consi Ground parts  Unit 4 Arc welding Weldment & - Flash & Up Unit 5 Design for a consideration assembly.	FORMING  derations for: Metal extruded p  MACHINING  derations for: Turned parts –  WELDING  – Design considerations for: heat treatment. Resistance weleset weldment.  ASSEMBLY  ssembly – General assembly is for: Rivets – Screw fastenes.	Drilled part  Cost reducti ding – Designerecommendates – Gasket	t/Cold extruded parts.  s – Milled, plane on – Minimizing on considerations tions – Minimizi & Seals – Press	ed, sha distor for: Sp	Stam  apped  tion oot –  no. Snap	and seam	9 slotted parts  9 slotted parts  9 slot tength  1 – Projection  9 arts – Design  – Automati  Total: 4
Unit 2 Design consist parts.  Unit 3 Design consist Ground parts  Unit 4 Arc welding Weldment & Unit 5 Design for a consideration assembly.  TEXTBOOL  1 Jan 2 O.	FORMING derations for: Metal extruded p  MACHINING derations for: Turned parts –  WELDING – Design considerations for: heat treatment. Resistance welloset weldment.  ASSEMBLY ssembly – General assembly is for: Rivets – Screw fastenes.	Drilled part  Cost reducti ding – Designerecommendates – Gasket  roduct Designerecy (Designer)	tions – Minimizing & Seals – Press	arts – ed, sha distor for: Sp ng the fits –	Stam  Inped  Inped  Ition  Inped  Inp	and :  - We Seam of partition of partition in the seam of the seam	9 slotted parts  9 slotted parts  9 sld strength  1 – Projection  9 arts – Design  Automatic  Total: 4:
Unit 2 Design consist parts.  Unit 3 Design consist Ground parts  Unit 4 Arc welding Weldment & Unit 5 Design for a consideration assembly.  TEXTBOOL  1 Jan 2 O.	FORMING  derations for: Metal extruded p  MACHINING  derations for: Turned parts –  WELDING  Design considerations for: theat treatment. Resistance welcoset weldment.  ASSEMBLY  ssembly – General assembly the for: Rivets – Screw fastenes  KS  mes G. Bralla, "Handbook of Promotion of the content of the con	Drilled part  Cost reducti ding – Designerecommendates – Gasket  roduct Designerecy (Designer)	tions – Minimizing & Seals – Press	arts – ed, sha distor for: Sp ng the fits –	Stam  Inped  Inped  Ition  Inped  Inp	and :  - We Seam of partition of partition in the seam of the seam	9 slotted parts  9 slotted parts  9 sld strength  1 – Projection  9 arts – Design  Automatic  Total: 4:

2	Da vid M. Anderson, "Design for Manufacturability & Concurrent Engineering: How to
	Design for Low Cost, Design in High Quality, Design for Lean Manufacture, and Design
	Quickly for Fast Production", CIM Press, 2004.
3	Eri k Tempelman, Hugh Shercliff, Bruno Ninaber van Eyben, "Manufacturing and Design:
	Understanding the Principles of How Things Are Made", Elsevier, 2014.
4	Henry Peck, "Designing for Manufacture", Sir Isaac Pitman & Sons Ltd., 1973.
5	Matousek, "Engineering Design", Blackie & Sons, 1956

COURS	E OUTCOMES:	Bloom's Taxonomy
At the er	nd of the course, learners will be able to	Level
CO1	Discuss the economic process selection principles and general	K2
	design principles for manufacturability in the development and	
	design of products for various engineering applications. Also,	
	apply design consideration principles of casting in the design of	
	cast products.	
CO2	Explain design consideration principles of forming in the design	K2
	of extruded, stamped, and forged products.	
CO3	Explain design consideration principles of machining in the	K2
	design of turned, drilled, milled, planed, shaped, slotted, and	
	ground products.	
CO4	Explain design consideration principles of welding in the design	K2
	of welded products.	
CO5	Explain design consideration principles of assembly in the design	K2
	of assembled products.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	1								1	2	2	1
CO2	3	3	3	1			rn					1	2	2	1
CO3	3	3	3	1	1	3811	441	DIVI	DUU	UR /		1	2	2	1
CO4	3	3	3	1	7		FST	1 21	111	7		1	2	2	1
CO5	3	3	3	1							7	1	2	2	1

# PROFESSIONAL ELECTIVES – THERMAL & ENERGY

		AME511 - POWER I	PLANT	ENGINEERING									
			T a		1.								
Programme &	Ŕ	BE& MECH	Sem.	Category	$\mathbf{L}$	T	P	C					
Branch			7	PE	3	0	0	3					
		> To study coal bas			3	U	U	3					
		•		ne and combined combi	zele i	OWA	r nlai	nte					
Preamble			•	lear engineering ar		-	•						
Treamore		To learn the power			i <b>u</b> po	wei j	Jiani	) <b>.</b>					
		<del>-</del>	To study energy, economic and environmental issues of power plants.										
Unit 1		COAL BASED POWER PLANT  9											
	nnrov	sations, Layout of modern			ritic	al Bo	ilers						
	-	ensers, Steam & Heat rate	_										
		m, Feed water treatment.						der dira distr					
Unit 2	. syste	DIESEL, GAS TURBI					1110	9					
0 2220 2		POWER PLANTS	OF TECHN	OLUGY	022	_							
Otto, Diesel, Dual	& Br	ayton Cycle - Analysis &	Optimiz	ation, Components	of D	iesel	and	Gas Turbine					
		l Cycle Power Plants, Inte	-	· •									
Unit 3		NUCLEAR POWER P	<u> </u>					9					
Basics of Nuclear	Engi	neering, Layout and subs	ystems c	f Nuclear Power I	Plants	s, Wo	rking	g of Nuclear					
	_	er Reactor (BWR), Press					_						
Uranium reactor (	CANI	DU), Breeder, Gas Cooled	and Lie	quid Metal Cooled	Rea	ctors,	Safe	ety measures					
for Nuclear Power	r plant	s.		<b>*</b>				•					
Unit 4		POWER FROM RENE	CWABL	E ENERGY				9					
Hydro Electric Po	ower	Plants – Classification, T	ypical L	ayout and associa	ted	comp	onen	ts including					
Turbines. Principle	e, Cor	struction and working of	Wind, Ti	dal, Solar Photo Vo	ltaic	(SPV	'), So	lar Thermal,					
Geo Thermal, Bio	gas ar	d Fuel Cell power system	s.										
Unit 5		ENERGY, ECONOMIC	CANDI	ENVIRONMENT	AL			9					
		ISSUES OF POWER P	LANT										
Power tariff type	s, Loa	nd distribution parameter	s, load	curve, Comparison	of	site s	select	ion criteria,					
relative merits &	dem	erits, Capital & Operatin	g Cost	of different power	r pla	nts.	Pollu	tion control					
technologies inclu	ding V	Waste Disposal Options for	r Coal a	nd Nuclear Power	Plant	S.							
		Loi	J. 201					Total: 45					
TEXTBOOKS													
1	Nag.	P.K., "Power Plant Engine	eering", '	Γhird Edition, Tata	Mc(	Graw	– Hil	l Publishing					
	Company Ltd., 2008												
2	A Te	ktbook of Power Plant En	gineering	g by R.K. Rajput, 2	016.								
REFERENCES													
1		akil. M.M., "Power Plant 7	Technolo	gy", Tata McGraw	– Hil	l Pub	lishi	ng Company					
	Ltd.,												
2		rey Boyle, "Renewable e			Oxfo	rd Uı	nivers	sity Press in					
	assoc	iation with the Open Univ	ersity, 2	004									

3	Thomas C. Elliott, Kao Chen and Robert C. Swanekamp, "Power Plant Engineering
	Second Edition, Standard Handbook of McGraw – Hill, 1998.
4	Power Plant Engineering by B. Vijaya Ramnath C. Elanchezhian, L. Saravanakumar
	1 November 2019
5	Power Plant Engineering, As per AICTE: Theory and Practice by Dipak Kumar
	Mandal, Somnath Chakrabarti, et al.   1 January 2019

COURSEOUTO	COMES:	Bloom's Taxonomy							
At the end of the	e course, learners will be able to	Level							
CO1	Explain the layout, construction and working of the	K2							
	components inside a thermal power plant.								
CO2	Explain the layout, construction and working of the	K2							
	components inside a Diesel, Gas and Combined cycle								
	power plants.								
CO3	Explain the layout, construction and working of the	K2							
	components inside nuclear power plants.								
CO4	Explain the layout, construction and working of the	K2							
	components inside Renewable energy power plants.								
CO5	Explain the applications of power plants while extending	K2							
	their knowledge to power plant economics and								
	environmental hazards and estimate the costs of electrical								
	energy production.								

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1	1		1	3	])	C	1		1	2	2	1
CO2	3	1	1	1		1	3	scipli	ue I	1		1	2	2	1
CO3	3	1	1	1		1	3			1		1	2	2	1
CO4	3	1	1	1		1	3		Diin	1	7	1	2	2	1
CO5	3	1	1	1		1	3	וויוע	UUU	1 /		1	2	2	1

	AME512 - GAS DYNAMICS AND JET PROPULSION											
Programme &	BE& MECH	Sem.	Category	L	Т	P	C					
Branch		7	PE	3	_	0	3					
	> To study the fundam	entals of c			ents a	nd tl						
Preamble	tables.  To learn the compress  To study the develop  To study the types of  To learn the types of	ssible flow oment of sl f jet engine	behavior in constance waves and it es and their perfo	stant a ts effe rmand	rea c cts.	lucts. rame	ters.					

Unit 1	BASIC CONCEPTS AND ISENTROPIC FLOWS	9			
Energy and mon	nentum equations of compressible fluid flows – Stagnation state	es, Mach waves and Mach			
$cone-Effect\ of$	Mach number on compressibility - Isentropic flow through va	riable ducts – Nozzle and			
Diffusers					
Unit 2	FLOW THROUGH DUCTS	9			
Flows through of	constant area ducts with heat transfer (Rayleigh flow) and	Friction (Fanno flow) -			
variation of flow	properties				
Unit 3	NORMAL AND OBLIQUE SHOCKS	9			
	tions - Variation of flow parameters across the normal and ol	olique shocks – Prandtl –			
Meyer relations					
Unit 4	JET PROPULSION	9			
	ropulsion – Thrust equation – Thrust power and propulsive				
	analysis and use of stagnation state performance of ram jet, tur	rbojet, turbofan and turbo			
prop engines	I IFPPIHHK I				
Unit 5	SPACE PROPULSION	9			
• •	engines - Propellants-feeding systems - Ignition and combu				
	formance study – Staging – Terminal and characteristic veloci	ty – Applications – space			
flights					
		Total: 45			
TEXTBOOKS					
1	And erson, J.D., "Modern Compressible flow", Third Editio				
2	M Yahya, "Fundamentals of Compressible Flow with Aircraft	t and Rocket propulsion",			
	New Age International (P) Limited, 4th Edition, 2012				
REFERENCES					
1	R. D. Zucker and O Biblarz, "Fundamentals of Gas Dynan 2011	nics", 2nd edition, Wiley,			
2	Balachandran, P., "Fundamentals of Compressible Fluid Dy	namics", Prentice-Hall of			
	India, 2007				
3	Radhakrishnan, E., "Gas Dynamics", Printice Hall of India,	2006.			
4	Hill and Peterson, "Mechanics and Thermodynamics of Wesley, 1965.	Propulsion", Addison –			
5	Babu, V., "Fundamentals of Compressible Flow", CRC Pres	s, 1st Edition, 2008			
	101012011				
COURSEOUT	COMES:	Bloom's Taxonomy			
	e course, learners will be able to	Level			
CO1	Apply the fundamentals of compressible flow concepts and	K3			
	the use of gas tables.				
CO2	Analyze the compressible flow behaviour in constant area	K4			
	ducts.				
CO3	Analyze the development of shock waves and their effects.	K4			
	Explain the types of jet engines and their performance parameters. K2				

CO5	Explain the types of rocket engines and their performance	K2
	parameters.	

Vortex and Pulse tube refrigeration systems

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1					1			1	3	1	2
CO2	3	2	1	1					1			1	3	1	2
CO3	3	2	1	1					1			1	3	1	2
CO4	3	2	1	1					1			1	3	1	2
CO5	3	2	1	1					1			1	3	1	2

Al	AME513 - REFRIGERATION AND AIR CONDITIONING								
	INCTITUTE OF TECHNOLOGY								
Programme &	BE& MECH	Sem.	Category	L	T	P	C		
Branch									
		7	PE	3	0	0	3		
	> To introduce the	underly	ing principles of	ope	eratio	ons	in different		
	Refrigeration & Air conditioning systems and components.								
	> To provide knowle	edge or	n design aspects	of	Refr	igera	tion & Air		
Preamble	conditioning systems	S.							
	To study the vapour absorption and air refrigeration systems.								
	> To learn the psychron	metric p	properties and proce	sses					
	To study the air conditioning systems and load estimation								
Unit 1	VAPOUR COMPRESSION REFRIGERATION 9								
	SYSTEM								

Refrigerants Desirable properties – Classification - Nomenclature - Vapour compression cycle: p-h and T-s diagrams - deviations from theoretical cycle – sub cooling and super heating- effects of condenser and evaporator pressure on COP-multi pressure system -low temperature refrigeration - Cascade systems – problems. Equipment's: Type of Compressors, Condensers, Expansion devices, Evaporators.

Unit 2 OTHER REFRIGERATION SYSTEMS 9

Working principles of Vapour absorption systems and adsorption cooling systems – Steam jet refrigeration- Ejector refrigeration systems- Thermoelectric refrigeration- Air refrigeration - Magnetic-

Unit 3 PSYCHROMETRIC PROPERTIES AND 9
PROCESSES

Properties of moist Air-Gibbs Dalton law, Specific humidity, Dew point temperature, Degree of saturation, Relative humidity, Enthalpy, Humid specific heat, Wet bulb temperature Thermodynamic wet bulb temperature, Psychrometric chart; Psychrometric of air-conditioning processes, mixing of air streams.

Unit 4	AIR CONDITIONING SYSTEMS AND LOAD	9
	ESTIMATION	

Air conditioning loads: Outside and inside design conditions; Heat transfer through structure, Solar radiation, Electrical appliances, Infiltration and ventilation, internal heat load; Apparatus selection, effective temperature & chart, calculation of summer & winter air conditioning load; Classifications, Layout of plants; Air distribution system; Filters; Air Conditioning Systems with Controls: Temperature, Pressure and Humidity sensors, Actuators & Safety controls.

TI 14 5	CDY/OCENIC ENGINEEDING	0
Unit 5	CRYOGENIC ENGINEERING	9

Introduction to cryogenics – difference between refrigeration & cryogenics – simple cryogenic cycle – Linde Hampson refrigeration cycle – modified Linde Hampson cryogenic cycle – cascaded systems – boiling point of various gases in ambient air – cryo vessel – cryostat – inversion curve – Joule Thomson effect – positive & negative zone – Liquid Oxygen cryogenics - Liquid Nitrogen cryogenics - Liquid Helium cryogenics.

Total: 45

	10tal: 45
TEXTBOOKS	
1	Arora, C.P., "Refrigeration and Air Conditioning", 3rd edition, McGraw Hill, New
	Delhi, 2010
2	R.S.Khurmi, "Textbook of Refrigeration and Air-Conditioning", S Chand
	Publications, 2019.
3	Mamata Mukhopadhyay, "Fundamentals of cryogenic engineering", PHI Learning,
	2014.
REFERENCES	
1	ASHRAE Handbook, Fundamentals, 2010
2	Jones W.P., "Air conditioning engineering" 5th edition, Elsevier Butterworth-
	Heinemann, 2007
3	Roy J. Dossat, "Principles of Refrigeration", 4th edition, Pearson Education Asia,
	2009.
4	Stoecker W.F and Jones J.W, "Refrigeration and Air Conditioning", McGraw Hill,
	NewDelhi,1986
5	R.K.Rajput, "A Textbook of Refrigeration and Air-Conditioning", 2019.

COURSEOUTO	Bloom's Taxonomy	
At the end of the	e course, learners will be able to	Level
CO1	Explain the Vapor compression Refrigeration systems and	K2
	to solve problems.	
CO2	Discuss the various types of Refrigeration systems.	K2
CO3	Calculate the Psychrometric properties and its use in	K4
	psychrometric processes.	
CO4	Explain the concepts of Air conditioning and to solve	K2
	problems.	
CO5	Explains the concept of cryogenics and its functioning.	K2

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	1	1			1		1			1	2	2	1
CO2	2	1	1	1			1		1			1	2	2	1
CO3	2	1	1	1			1		1			1	2	2	1
CO4	2	1	1	1			1		1			1	2	2	1
CO5	2	1	1	1			1		1			1	2	2	1

	AME514 - MODERN IC ENGINES				
Programme & Branch	BE& MECH Sem. Category L	T	P	С	
	INCTITUTE OF TOWN OLDEY PE 3	0	0	3	
	➤ To study the working of Gasoline fuel injection systems	s and	l SI	combustion.	
	> To study the working of Diesel fuel injection systems a	ınd (	CI co	ombustion.	
	> To Identifying the source and measure it; explain the me	char	nism	of emission	
Preamble	formation and control methods.				
	> To study the Selecting alternative fuel resources a	ınd	thei	r utilization	
	techniques in IC engines.				
	> To study the advanced combustion modes and future pe	owei	r tra	in systems.	
Unit 1	SPARK IGNITION ENGINES			9	
Mixture requirements -	- Fuel injection systems – Mono point, Multipoint & Direct	inje	ctio	1 - Stages of	
combustion - Normal	and Abnormal combustion - Knock - Factors affecting k	nock	ζ –	Combustion	
chambers – Hydrogen	utilization in spark engines – digital twin based spark ignitio	n tec	chnc	ology.	
Unit 2	COMPRESSION IGNITION ENGINES			9	
Diesel Fuel Injection S	ystems - Stages of combustion - Knocking - Factors affecting	g kn	ock	– Direct and	
Indirect injection syste	ms – Combustion chambers – Fuel Spray behaviour – Spray	y stri	ıctu	re and spray	
penetration – Air motio	on - Introduction to Turbo charging – Electronic engine mana	ıgem	nent.		
Unit 3	POLLUTANT FORMATION AND CONTROL			9	
Pollutant – Sources – F	ormation of Carbon Monoxide, Unburnt hydrocarbon, Oxides	of N	Vitro	ogen, Smoke	
and Particulate matter	- Methods of controlling Emissions - Catalytic converters	, Sel	lecti	ve Catalytic	
Reduction and Particul	ate Traps – Methods of measurement – Emission norms and	Driv	ing	cycles.	
Unit 4	ALTERNATE FUELS			9	
Alcohol Fuels, Hydro	gen, Compressed Natural Gas, Liquefied Petroleum Gas	s an	d B	io Diesel -	
Properties, Suitability, Merits and Demerits – Utilisation Methods - Engine Modifications					
Unit 5	RECENT TRENDS IN IC ENGINES			9	
Air assisted Combusti	on, Homogeneous charge compression ignition engines -	Var	iabl	e Geometry	
turbochargers – Common Rail Direct Injection Systems - Hybrid Electric Vehicles – NOx Adsorbers -					
turbochargers – Comm					
Onboard Diagnostics					
<del>-</del>				Total: 45	

1	V. Ganesan, "Internal Combustion Engines", V Edition, Tata McGraw Hill, 2012.				
2	John B. Heywood, "Internal Combustion Engines Fundamentals", McGraw-Hill,				
	1988.				
REFERENCES					
1	B.P . Pundir, "IC Engines Combustion & Emission", Narosa Publishing House, 2014				
2	Duffy Smith, "Auto Fuel Systems", The Good Heart Wilcox Company, Inc., 2003.				
3	EranSher, "Handbook of Air Pollution from Internal Combustion Engines: Pollutant				
	Formation and Control", Academic Press, 1998.				
4	K.K.Ramalingam, "Internal Combustion Engine Fundamentals", SciTech				
	Publications, 2011.				
5	R.B.Mathur and R.P. Sharma, "Internal Combustion Engines", Dhanpat Rai& Sons,				
	2007				

COURSEOUTO	COURSEOUTCOMES:					
At the end of the	e course, learners will be able to	Level				
CO1	Explain the working of Gasoline fuel injection systems and	K2				
	SI combustion.					
CO2	Explain the working of Diesel fuel injection systems and	K2				
	CI combustion.					
CO3	Identify the source and measure it; explain the mechanism	К3				
	of emission formation and control methods.					
CO4	Select alternative fuel resources and its utilization	К3				
	techniques in IC engines.					
CO5	Explain advanced combustion modes and future power	K2				
	train systems					

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	1	2	3		1			3	3	2	2
CO2	3	2	2	1	1	2	3	UIVI	1	UR I		3	3	2	1
CO3	3	1	2	2	2	2	3	1. 21	11			3	2	3	1
CO4	2	1	2	1	2	2	3		1		7	3	2	3	1
CO5	3	1	1	1	2	2	2		1			3	2	3	1

	AME515 - RENEWA	BLE ENE	RGY SYSTEM	S							
Programme & Branch	BE& MECH	Sem.	Category	L	T	P	С				
		7	PE	3	0	0	3				
Preamble		<ul> <li>To Provide knowledge about various renewable energy technologies</li> <li>To enable students to understand solar power and design a PV system.</li> </ul>									

_						
	To provide knowledge about wind energy system.					
	➤ To Provide knowledge about various possible hybrid	• • •				
	> To gain knowledge about application of various	renewable energy				
	technologies	T				
Unit 1	INTRODUCTION	9				
Primary energy s	sources - renewable vs. non-renewable primary energy sources -	renewable energy				
	a - Current usage of renewable energy sources in India - future pot	ential of renewable				
energy in power p	production and development of renewable energy technologies					
Unit 2	SOLAR ENERGY	9				
Solar Radiation a	and its measurements, Solar Thermal Energy Conversion - plate	Solar Collectors -				
Concentrating Co	llectors - Efficiency and performance of collectors. Direct Solar Ele	ectricity Conversion				
from Photovoltaio	c - types of solar cells - applications. Recent Advances in PV App	plications: Building				
Integrated PV, Gr	id Connected PV Systems,					
Unit 3	WIND ENERGY	9				
Wind energy prir	nciples, wind site and its resource assessment, wind assessment,	Factors influencing				
wind, wind turbi	ne components, wind energy conversion systems (WECS), Class	ification of WECS				
devices, wind ele-	ctric generating and control systems, characteristics and application	ıs				
Unit 4	BIO ENERGY	9				
Energy from bior	mass - Principle of biomass conversion technologies/process - cla	ssification, Bio gas				
= -	of biogas plants, selection of site for biogas plant, classificatio	<del>-</del>				
	isadvantages of biogas generation, thermal gasification of biomas					
_	omass and biogas plants and their economics					
Unit 5	OTHER TYPES OF ENERGY	9				
Energy conversion	on from Hydrogen and Fuel cells, Geothermal energy - resource	es, types of wells,				
methods of harne	ssing the energy - potential in India. OTEC - Principles utilizatio	n, setting of OTEC				
plants, thermodyr	namic cycles. Tidal and wave energy: Potential and conversion tecl	nniques, mini hydel				
power plants and						
	Discipline	Total: 45				
TEXTBOOKS						
1	Fundamentals and Applications of Renewable Energy   Indian E	Edition, by Mehmet				
	Kanoglu, Yunus A. Cengel, John M. Cimbala, McGraw Hill; 1st ed	•				
2	Renewable Energy Sources and Emerging Technologies, by Ko					
	India Learning Private Limited, 2 <sup>nd</sup> edition, 2011.	,				
3		2022.				
_	D Yogi Goswami, "Principles of Solar Engineering", CRC Press,	2022.				
REFERENCES	D Yogi Goswami, "Principles of Solar Engineering", CRC Press,					
REFERENCES 1	D Yogi Goswami, "Principles of Solar Engineering", CRC Press, Twidell & Wier, "Renewable Energy Resources", CRC Press (Tay					
REFERENCES  1 2	D Yogi Goswami, "Principles of Solar Engineering", CRC Press,  Twidell & Wier, "Renewable Energy Resources", CRC Press (Tay Tiwari and Ghosal/ Narosa, "Renewable energy resources".	vlor & Francis).				
REFERENCES 1	D Yogi Goswami, "Principles of Solar Engineering", CRC Press,  Twidell & Wier, "Renewable Energy Resources", CRC Press (Tay Tiwari and Ghosal/ Narosa, "Renewable energy resources".  D.P.Kothari, K.C.Singhal, "Renewable energy sources and emergence of the solution of the	vlor & Francis).				
REFERENCES  1 2 3	D Yogi Goswami, "Principles of Solar Engineering", CRC Press, Twidell & Wier, "Renewable Energy Resources", CRC Press (Tay Tiwari and Ghosal/ Narosa, "Renewable energy resources".  D.P.Kothari, K.C.Singhal, "Renewable energy sources and emer P.H.I. Publishers, 2015.	vlor & Francis).				
REFERENCES  1 2	D Yogi Goswami, "Principles of Solar Engineering", CRC Press,  Twidell & Wier, "Renewable Energy Resources", CRC Press (Tay Tiwari and Ghosal/ Narosa, "Renewable energy resources".  D.P.Kothari, K.C.Singhal, "Renewable energy sources and emer P.H.I. Publishers, 2015.  D.S.Chauhan, S.K. Srivastava, 'Non – Conventional Energy Reso	vlor & Francis).				
REFERENCES  1 2 3	D Yogi Goswami, "Principles of Solar Engineering", CRC Press, Twidell & Wier, "Renewable Energy Resources", CRC Press (Tay Tiwari and Ghosal/ Narosa, "Renewable energy resources".  D.P.Kothari, K.C.Singhal, "Renewable energy sources and emer P.H.I. Publishers, 2015.	rlor & Francis).  ging technologies",  urces', New Age				

COURSEOUTO	COMES:	Bloom's Taxonomy
At the end of th	e course, learners will be able to	Level
CO1	Attained knowledge about various renewable energy technologies	K2
CO2	Ability to understand and design a PV system.	K2
CO3	Understand the concept of various wind energy system.	K2
CO4	Gain knowledge about various possible hybrid energy systems	K2
CO5	Attained knowledge about various application of renewable energy technologies	K2
СО-РО Ма	pping JEPPIAAR	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2										2	3	3	3
CO2	3	2										2	3	3	3
CO3	3	2										2	3	3	3
CO4	3	2										2	3	3	3
CO5	3	2										2	3	3	3





AME5	16 - NON-DESTRUCTI	VE TEST	ΓING ANI	D EVALUA	ATIO	N		
Programme &	BE& MECH	Sem.	Categ	gory I	LT	P	С	
Branch								
		8	PF	E 3	3 0	0	3	
<ul> <li>To provide a basic understanding with case studies on different NDT &amp; E techniques.</li> <li>Impart knowledge on inspecting materials with industry specifications and standards.</li> <li>To provide a basic understanding on different NDT &amp; E testing.</li> <li>Understand Eddy current testing</li> <li>To get knowledge about the advanced NDT techniques</li> </ul>								
Unit 1	INTRODUCTION OF	NDT				9		
Fundamentals of charac	eterisation studies, Codes,	Standard	s and Speci	ifications, l	Defec	ts in N	Materials due	
to various processing,	Visual Testing – vision cer	rtificatior	ı, lighting,	material a	ttribu	tes, ei	nvironmenta	
factors, visual percep	tion, direct and indirect	method	ls – mirr	ors, magn	ifiers	, bore	oscopes and	
fibroscopes- light source	ces and special lighting—ca	libration						
Unit 2	SURFACE INSPECTI	N TECH	NIQUES A	AND			9	
	ULTRASONIC TESTI	NG						
Dye penetrant testing	- visible, fluorescent m	ethod, S	election o	f penetran	t me	thod -	- Theory of	
magnetism and Principl	e of Magnetic Particle Test	ting - We	t Magnetic	Particle Te	sting	and I	Ory Magnetic	
Particle Testing. Ultra	asonic transducers, Inspe	ection te	echniques,	Flaw cha	aracte	rizatio	on, Materia	

properties characterization, Immersion testing, Applications.

Unit 3	ACOUSTIC EMISSION TESTING AND	9
	RADIOGRAPHY TESTING	

AE sources, Wave propagation in metals and alloys, AE signal intensity in attenuation media, AE equipment, Signal features, Data collection and analysis, source location, Applications. Introduction to Radiography - radiography sources - Film Radiography - Film handling and storage - Effect of film processing on film characteristics - Radiographic Image Quality and Radiographic Techniques

### Unit 4 **EDDY CURRENT TESTING**

Generation of eddy currents – effect of change of impedance on instrumentation – properties of eddy currents – eddy current sensing elements, probes, type of coil arrangement – absolute, differential, lift off, operation—Through encircling coils, type of arrangements – absolute, differential fill factor, operation - Factors affecting sensing elements and coil impedance - test part and test system- Applicable codes and standards.

### ADVANCED NON-DESTRUCTIVE TESTING Unit 5

Leak testing, Hydro testing, Holography, Thermography, Magnetic Barkhausen Effect, and In-situ metallography. Industrial applications of flaw detection probability, Wave propagation in guided wave modes in isotropic and composite plate structures, Mode conversion, diffraction and scattering of ultrasonic waves in isotropic and anisotropic media, Pulsed eddy, current NDT, Electromagnetic acoustic technique (EMAT). Scanning Acoustic Microscopy (SAM) and Scanning Laser Acoustic Microscopy.

**Total: 45** 

### **TEXTBOOKS**

1	Wong B. Stephen, "Non-Destructive Testing - Theory, Practice and Industrial
	Applications", 2015, 1st edition, Lambert Academic Publishing, USA
REFERENCES	
1	Prasad, J C. G. Krishnadas Nair, "Non-Destructive Test and Evaluation of Materials",
	2017, 2nd edition, McGraw Hill Education (India) Private Limited
2	Raviprakash, "Non-Destructive Testing Techniques", 2010, 1st edition, New Age
	International Private Limited Published.
3	Baldev Raj, M. Thavasimuthu, and Jayakumar T, "Practical Non-Destructive Testing",
	3rd edition, Narosa publications, 2009.
	'

COURSEOUTO	COMES:	Bloom's Taxonomy
At the end of the	e course, learners will be able to	Level
CO1	Infer the knowledge of various NDT techniques.	K2
CO2	Apply the NDT techniques to identify surface defects of engineering components.	K3
CO3	Use the subsurface NDT techniques to identify the defects.	K2
CO4	Examine and quantify closed discontinuities to assess the structural integrity of engineering components.	K3
CO5	Analyse the outputs of the acquired data from NDT techniques	K4

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3
CO2	3	3	3	3	2	3	0/1	3	2	3	1	3	3	2	3
CO3	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3
CO4	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3
CO5	3	3	3	3	2	3	116	3	2	3	1	3	3	2	3
	ESTD. 2011														

	AME517 - TESTING OF MATERIALS									
Programme & BE& MECH Sem. Category L T P C Branch										
		8	PE	3	0	0	3			
Preamble	<ul> <li>To provide a bath</li> <li>To get knowled</li> <li>Impart knowled</li> <li>To get knowled</li> <li>To gain knowled</li> </ul>	ge about the ge onNon I ge about the	e different Mech. Destructive testire Characterization	anical ng on Tecl	Test	ing				
Unit 1	INTRODUCTION TO	) MECHAI	NICAL TESTIN	NG			9			

Overview of materials, Classification of material testing, Purpose of testing, Selection of material, Development of testing, testing organizations and its committee, Testing standards, Result Analysis, Advantages of testing TRADITIONAL MECHANICAL TESTING Unit 2 Introduction to mechanical testing, Hardness test (Vickers, Brinell, Rockwell), Tensile test, Impact test (Izod, Charpy) - Principles, Techniques, Methods, Advantages and Limitations, Applications. Bend test, Shear test, Creep and Fatigue test - Principles, Techniques, Methods, Advantages and Limitations, Applications. 9 Unit 3 NON-DESTRUCTIVE TESTING AND **APPLICATIONS** Visual inspection, Liquid penetrant test, Magnetic particle test, Thermography test - Principles, Techniques, Advantages and Limitations, Applications. Radiographic test, Eddy current test, Ultrasonic test, Acoustic emission- Principles, Techniques, Methods, Advantages and Limitations, Applications **MECHANICAL CHARACTERIZATION** Unit 4 **TECHNIQUES** Macroscopic and Microscopic observations, Optical and Electron microscopy (SEM and TEM) -Principles, Types, Advantages and Limitations, Applications. Diffraction techniques, Spectroscopic Techniques, Electrical and Magnetic Techniques- Principles, Types, Advantages and Limitations, **Applications** Unit 5 ADVANCED TESTING 9 Thermal Testing: Differential scanning calorimetry, Differential thermal analysis. Thermo- mechanical and Dynamic mechanical analysis: Principles, Advantages, Applications. Chemical Testing: X-Ray Fluorescence, Elemental Analysis by Inductively Coupled Plasma-Optical Emission Spectroscopy and Plasma-Mass Spectrometry. Total: 45 **TEXTBOOKS** Baldev Raj, T.Jayakumar, M.Thavasimuthu "Practical Non-Destructive Testing", 1 Narosa Publishing House, 2009. Cullity, B. D., "Elements of X-ray diffraction", 3rd Edition, Addison-Wesley 2 Company Inc., New York, 2000 P. Field Foster, "The Mechanical Testing of Metals and Alloys" 7th Edition, Cousens 3 Press, 2007 REFERENCES Metals Handbook: Mechanical testing, (Volume 8) ASM Handbook Committee, 9th 1 Edition, American Society for Metals, 1978 ASM Metals Handbook, "Non-Destructive Evaluation and Quality Control", 2 American Society of Metals, Metals Park, Ohio, USA 3 Brandon D.G., "Modern Techniques in Metallography", Von Nostrand Inc. NJ, USA, 1986 **COURSEOUTCOMES: Bloom's Taxonomy** Level At the end of the course, learners will be able to

CO1	Identify suitable testing technique to inspect industrial	K1
	component.	
CO2	Ability to use the different technique and know its	K2
	applications and limitations.	
CO3	Obtain the knowledge of Non-destructive testing and its	K2
	applications.	
CO4	To gain knowledge in Mechanical Characterization	K2
	Techniques.	
CO5	Attain Knowledge in Advanced Testing of materials.	K2

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	3	3	3	-	<b>K</b> -	-	3	1	1	1
CO2	3	3	3	3	2	3 51	-3		HNOLO	IGY-	-	3	1	1	1
CO3	3	3	3	3	2	3	3	3	_	-	-	3	1	1	1
CO4	3	3	3	3	2	3	3	3	-	-	-	3	1	1	1
CO5	3	3	3	3	2	3	3	3	-	-	-	3	1	1	1

	AME518 - NANO MATI	ERIALS AN	D APPLICAT	IONS								
				L	Т	P						
Programme &	BE& MECH	Sem.	Sem. Category				C					
Branch												
	Q. O	8	PE	3	0	0 0 3						
	> To provide a ba	sic understa	nding of Nanom	ateria	ls.							
To get knowledge about the Nano sensors												
Preamble > Impart knowledge on Nanotechnology Enabled devises												
To get knowledge about the Diffraction analysis												
	> To gain knowle	To gain knowledge in Surface imaging										
Unit 1	SYNTHESIS AND PREPARATION OF 9											
	NANOMATERIALS											
Synthesis of bulk nar	ostructured materials - So	ol Gel proce	ssing- bulk and	nano	comp	posite	materials -					
Grinding - high energ	y ball milling – injection n	noulding - e	xtrusion - melt q	uencl	ning a	and a	nnealing					
Unit 2	NANOSENSORS						9					
Introduction to sensor	s. Characteristics and term	ninology - st	atic and dynami	c char	acte	ristics	. Micro and					
nano-sensors, Fundar	nentals of sensors, biosen	nsor, micro	fluids, Packagi	ng an	d ch	aract	erization of					
sensors, Sensors for a	erospace and defence. Org	anic and inc	organic nanosens	sors								
Unit 3	NANO TECHNOLOG	GY ENABL	ED DEVICES				9					
Nanomaterials and n	anostructured films, Nano	oscale elect	ronic and ionic	trans	port.	Sens	sor for bio-					
medical applications.	Bioelectronics, Nanopartie	cle biomater	rial hybrid system	ms for	sens	sing a	pplications.					
Gas sensor												
Unit 4	DIFFRACTION ANA	LYSIS					9					

X-ray diffraction, powder diffraction, lattice parameters, structure analyses, strain analyses, phase identification, particle size analyses using - Scherer's formula - X-ray photoelectron spectroscopy (XPS)-Auger electron spectroscopy (AES)

Unit 5	SURFACE IMAGING	9
Scanning Electron Mic	croscope (SEM) - Field Emission Scanning Electron Mic	roscope (FESEM)-
Atomic Force Microsco	opy (AFM ), Scanning Tunneling Microscopy (STM)- Tra	nsmission Electron
Microscopy (TEM)		

	Total: 45							
TEXTBOOKS								
1	W. Gaddand, D. Brenner, S. Lysherski and G. J. Infrate, "Handbook of nanoscience,							
	Engineering and Technology", CRC Press, 2002							
2	G. Cao, "Naostructures and Nanomaterials: Synthesis, properties and applications",							
	Imperical College Press, 2004.							
3	J. George, "Preparation of thin films", Marcel Dekker, InC., New York, 2005.							
4	C. N. R. Rao, A. Muller, A. K. Cheetham, "The chemistry of nanomaterials: Synthesis,							
	properties and applications", Wiley VCH Verlag Gmbh & Co, Weinheim, 2004.							
REFERENCES								
1	A. H. Cottrell, "The Mechanical Properties of Matter", John Wiley, New York-							
	London, 1964.							
2	R. Asthana, A. Kumar and N. Dahotre, "Materials Science in Manufacturing"							
	Butterworth Heinemann, Elsevier 2006							
3	G. E. Dieter, adapted by D Bacon, "Mechanical Metallurgy", SI Metric edition,							
	McGraw Hill, Singapore, 1988							
4	K. A. Padmanabhan, "Mechanical Properties of Nanostructured Materials", Materials							
	Science and Engineering, A 304-306 (2001) 200-205							
5	H. Gleiter, "Nanocrystalline Materials", Progress in Materials Science Vol. 33, 1989							
6	C. Koch, "Nanostructured Materials: Processing, Properties and Applications", 2nd							
	Edition, Ed.: 2007							

COURSEOUT	COMES:	Bloom's Taxonomy
At the end of th	e course, learners will be able to	Level
CO1	Infer the knowledge of various Nanomaterials.	K2
CO2	Obtain the knowledge of nano sensors.	K2
CO3	Use the enabled devices to identify the nano particles.	K2
CO4	Analyze the outputs of the acquired data from Diffraction analyses.	K4
CO5	Analyze the outputs of the acquired data from Surface	K4
	Imaging	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	3	3	3	-	-	-	3	1	1	1
CO2	3	3	3	3	2	3	3	3	-	-	-	3	1	1	1
CO3	3	3	3	3	2	3	3	3	-	-	-	3	1	1	1
CO4	3	3	3	3	2	3	3	3	-	-	-	3	1	1	1
CO5	3	3	3	3	2	3	3	3	-	-	-	3	1	1	1

AME519 - COMPOSITE MATERIALS AND MECHANICS											
Programme & Branch	BE& MECH Sen	. Category	L	Т	P	С					
	INSTITUTE OF 18	PE	3	0	0	3					
Preamble	<ul> <li>Study of different compos</li> <li>Fabrication of FRP and methods</li> <li>Stress analysis of fiber rei plies with different orienta</li> <li>Calculation of stresses in theories.</li> <li>Calculation of residual sthermo-mechanical load u</li> </ul>	other composites inforced Laminates fitions of the fiber. the lamina of the laminates in different tresses in different	by diff  for diff  ninate  t types	erentusing	nt ma t com g diff lami	anufacturing abinations of Gerent failure					
Unit 1	INTRODUCTION TO COM					9					

Definition-Matrix materials-polymers-metals-ceramics - Reinforcements: Particles, whiskers, inorganic fibers, metal filaments-ceramic fibers-fiber fabrication-natural composite wood, Jute Advantages and drawbacks of composites over monolithic materials. Mechanical properties and applications of composites, Particulate-Reinforced composite Materials, Dispersion-Strengthened composite, Fiber-reinforced composites Rule of mixtures-Characteristics of fiber-Reinforced composites, Manufacturing fiber and composites.

### Unit 2 MANUFACTURING OF COMPOSITES 9

Manufacturing of Polymer Matrix Composites (PMCs)-hand lay-up, spray technique, filament winding, Pultrusion, Resin Transfer Moulding (RTM)-,bag moulding, injection moulding, Sandwich Mould Composites (SMC) - Manufacturing of Metal Matrix Composites (MMCs) - Solid state, liquid state, vapour state processing, Manufacturing of Ceramic Matrix Composites (CMCs)—hot pressing reaction bonding process-infiltration technique, direct oxidation-interfaces

### Unit 3 LAMINA CONSTITUTIVE EQUATIONS 9

Lamina Constitutive Equations: Lamina Assumptions–Macroscopic Viewpoint. Generalized Hooke's Law. Reduction to Homogeneous Orthotropic Lamina – Isotropic limit case, Orthotropic Stiffness matrix (Qij), Definition of stress and Moment Resultants. Strain Displacement relations. Basic Assumptions of Laminated anisotropic plates. Laminate Constitutive Equations – Coupling Interactions, Balanced Laminates, Symmetric Laminates, Angle Ply Laminates, CrossPly Laminates. Laminate Structural

Moduli. Evaluation of Lamina Properties from Laminate Tests. Quasi-Isotropic Laminates. Determination of Lamina stresses within Laminates

Unit 4 LAMINA STRENGTH ANALYSIS AND ANALYSIS 9
OF LAMINATE FLAT PLATES

Introduction- Maximum Stress and Strain Criteria. Von-Misses Yield criterion for Isotropic Materials. Generalized Hill's Criterion for Anisotropic materials. Tsai-Hill's Failure Criterion for Composites. Tensor Polynomial (Tsai-Wu) Failure criterion. Prediction of laminate Failure Equilibrium Equations of Motion. Energy Formulations. Static Bending Analysis. Buckling Analysis. Free Vibrations— Natural Frequencies

Unit 5 THERMO STRUCTURAL ANALYSIS 9

Fabrication stresses / Residual stresses in FRP laminated composites-Co-efficient of Thermal Expansion (C.T.E.) - Modification of Hooke's Law. Modification of Laminate Constitutive Equations. Orthotropic Lamina C.T.E's -Stress and Moment Resultants due cooling of the laminates during fabrication-

Calculations for thermo-mechanical stresses in FRP laminates Case studies: Implementation of CLT for evaluating residual stresses in the components made with different isotropic layers such as electronic

packages etc.

	m . 1 . 4
	Total: 45
TEXTBOOKS	
1	Agarwal BD and Broutman LJ, "Analysis and Performance of Fiber Composites",
	John Wiley and Sons, New York,1990.
2	Gibson RF, Principles of Composite Material Mechanics, CRC press,4th
	Edition,2015.
REFERENCES	**
1	Hyer MW and Scott R White, "Stress Analysis of Fiber – Reinforced Composite
	Materials", McGraw-Hill, 1998
2	Issac M Daniel and OriIshai, "Engineering Mechanics of Composite Materials",
	OxfordUniversityPress-2006, First Indian Edition-2007
3	Madhujit Mukhopadhyay, "Mechanics of Composite Materials and Structures",
	University Press (India) Pvt Ltd, Hyderabad, 2004 (Reprinted 2008)
4	Mallick PK, Fiber – Reinforced Composites: Materials, Manufacturing and Design,
	CRC Press, 3rd Edition, 2007

COURSEOUTO	COMES:	Bloom's Taxonomy
At the end of the	e course, learners will be able to	Level
CO1	Infer the knowledge of various NDT techniques.	K2
CO2	Calculate for mechanical strength of the composite material	K4
CO3	Fabricate the FRP and other composites by different manufacturing methods	K4
CO4	Analyze fiber reinforced Laminates for different combinations of plies with different orientations of the fiber.	K4

CO5	Evaluate the stresses in the lamina of the laminate using	K5
	different failure theories	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3
CO2	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3
CO3	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3
CO4	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3
CO5	3	3	3	3	2	3	1	3	2	3	1	3	3	2	3

A	AME520 - MECHANICAL BEHAVIOR OF MATERIALS												
	INSTITUTE OF TECHNOLOGY												
Programme &	BE& MECH	Sem.	Category	L	T	P	C						
Branch													
		8	PE	3	0	0	3						
Preamble	<ul> <li>To learn the concessystem.</li> <li>To study the shear beams subjected to</li> <li>To learn the stresse</li> <li>To study torsional stresses</li> <li>To learn the stresses</li> <li>contact applications</li> </ul>	r centre o unsymme s in flat pla stress of no	f various cross-s trical bending. ates and curved n on-circular section	ection nemb	ns ai ers.	nd de	eflections in						
Unit 1	ELASTICITY	line	3				9						

Stress-Strain relations and general equations of elasticity in Cartesian, Polar and curvilinear coordinates, differential equations of equilibrium – compatibility - boundary conditions - representation of three - dimensional stress of a tension generalized hook's law - St. Venant's principle - planes tress - Airy's stress function. Energy methods

<i>U</i> ,		
Unit 2	SHEAR CENTRE AND UNSYMMETRICAL	9
	BENDING	

Location of shear centre for various thin sections - shear flows. Stresses and Deflections in beams subjected to unsymmetrical loading-kern of a section

Unit 3	STRESSES IN FLAT PLATES AND CURVED	9
	MEMBERS	

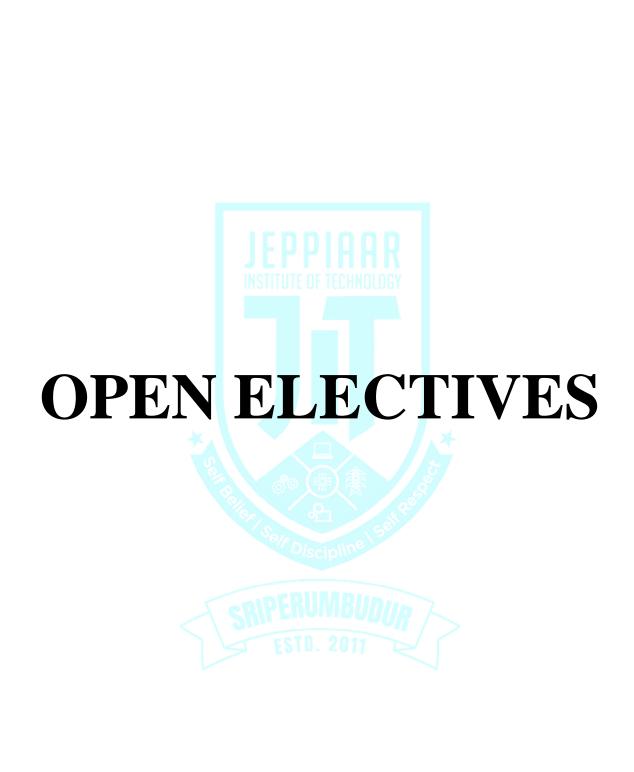
Circumference and radial stresses – deflections - curved beam with restrained ends - closed ring subjected to concentrated load and uniform load - chain links and crane hooks. Solution of rectangular plates – pure bending of plates – deflection – uniformly distributed load – various end conditions

Unit 4	TORSION OF NON-CIRCULAR SECTIONS	9

Torsion of rectangular cross section - St. Venants theory - elastic membrane analogy - Prandtl's stress function - torsional stress in hollow thin walled tubes

Unit 5	STRESSES IN ROTATING MEMBERS AND CONTACT STRESSES	9
Radial and tange	ntial stresses in solid disc and ring of uniform thickness and va	nrying thickness allowable
_	of computing contact stress-deflection of bodies in point and	• •
T C C C C C C C C C C C C C C C C C C C	r	Total: 45
TEXTBOOKS		
1	Arthur P Boresi, Richard J.Schmidt, "Advanced Mechanics	of Materials", Wiley India
	Pvt. Ltd., 2009.	
2	Hibbeler. R.C., "Mechanics of Materials", Prentice-Hall, 20	018.York, 2000.
REFERENCES		
1	1.Robert D.Cook, Warren C.Young, "Advanced Mechanic	es of Materials", Prentice
	Hall,1999.	
2	Srinath. L.S., "Advanced Mechanics of Solids", Tata McGr	aw Hill, 2009
3	Timoshenko and Goodier, "Theory of Elasticity", Tata McC	braw Hill, 2010.
	INSTITUTE OF TECHNOLOGY	
COURSEOUT	COMES:	Bloom's Taxonomy
At the end of the	e course, learners will be able to	Level
CO1	Apply the concepts of theory of elasticity in three-	K3
	dimensional stress system.	
CO2	Determine the shear centre of various cross-sections and	K4
	deflections in beams	
CO3	Appreciate the unsymmetrical bending.	K2
CO4	Evaluate the stresses in flat plates and curved members.	K5
CO5	Calculate torsional stress of non-circular sections.	K4

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1	3	2	1	CETI	1 7/	111	<del>"</del> /		3	1	1	1
CO2	3	1	1	3	2	1	Fari		' * 1 <u>-</u>		-	3	1	1	1
CO3	3	1	1	3	2	1	-	-	-	-	-	3	1	1	1
CO4	3	1	1	3	2	1	-	-	-	-	-	3	1	1	1
CO5	3	1	1	3	2	1	-	-	-	-	-	3	1	1	1



		AME701 - I	DRONE TEC	CHNOLOGIES				
Programmo & Branch		BE & MECH	Sem.	Category	L	Т	P	С
				OE	3	0	0	3
Preamble	A A A A A	To understand the b To learn and unders of drone. To impart the know To know about the To understand the s	tand the fund ledge of a fly various applic	aments of design, ing and operation cations of drone.	of dro	one.	and	programming
Unit 1		ODUCTION TO DI			<i>y</i> ~	<u> </u>		9
on their met	hod of pr	oulary Terminology- lopulsion- Drone teclortunities/application	hnology impa	act on the busine	sses- I	Orone		
Unit 2		NE DESIGN, FABR	<del>                                      </del>					9
		UAV -Overview of the obling a drone- The		-				
		ramming drone- Do stabilization- Flight		_	gram	on c	ompu	ter- Running
Unit 3	DRO	NE FLYING AND C	PERATION					9
controls Flig	ht operati ked mobil	or drone -Flight mode ons —management to e devices and applica	ool –Sensors-Cations.	Onboard storage				
Unit 4		NE COMMERCIAI						9
parcels and	other carg	ed on the application to- Drones in agriculation in the second of the se	ture- Drones					=
Unit 5	FUTU	TRE DRONES AND	SAFETY					9
=		delines to fly safely on of drones- Increasi						warms.
marma o o o			ESTD. 20	11 2				Total: 45
Co Jo	niel Tal instruction nn Wiley	and John Altschuld n: A Strategic Guide t & Sons, Inc, 2021.	to Unmanned	Aerial Vehicle O <sub>l</sub>	peratio	n and	l Imp	lementation",
Ed	ition, 201	and Belinda Kilby, 6.	iviake: Gett	ing started with	ווסוע	es ,	ıvıak	ei iviedia, i <sup>ss</sup>
REFERENCE								
		e Publishing, 2016	Own Drones	: A Beginners' (	Guide	to D	rones	, UAVs, and
2 Za	vrsnik, "I	Prones and Unmanne	d Aerial Syste	ems: Legal and $\overline{S}$	ocial I	nplic	ation	s for Security

COURS	SE OUTCOMES:	Bloom's Taxonomy
At the e	nd of the course, learners will be able to	Level
CO1	Know about a various type of drone technology, drone fabrication and programming.	K2
CO2	Execute the suitable operating procedures for functioning a drone.	K3
CO3	Select appropriate sensors and actuators for Drones.	K3
CO4	Develop a drone mechanism for specific applications.	K4
CO5	Create the programs for various drones.	K6

CC	<b>)-PO</b> ]	Mapp	ing												
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	3	1	3	2						1	2	1	3
CO2	1	2	3	1	3	2		5				1	2	1	3
CO3	1	2	3	1	3	2						1	2	1	3
CO4	1	2	3	1	3	2						1	2	1	3
CO5	1	2	3	1	3	2						1	2	1	3

<u> </u>										
	AME702 - ADDIT	TIVE M	IANUFACTURING							
Programme	Programme BE & MECH Sem. Category L									
& Branch	0,0									
	3/1	Discip	OE	3	0	0	3			
Preamble	> To introduce the co	levelopr	nent, capabilities,	appl	icatio	ns,	of Additive			
	Manufacturing (AM), a	and its b	usiness opportunities.							
	> To be acquainted with	vat poly	merization and mater	ial e	xtrus	ion p	rocesses			
	To be familiar with pover	wder be	d fusion and binder je	tting	proc	esses	S.			
	> To gain knowledge or	applic	ations of direct energ	gy d	eposi	tion,	and material			
	jetting processes.									
	To impart knowledge of	n sheet	lamination and direct	writ	e tec	hnol	ogies.			
Unit 1	INTRODUCTION						9			
Overview - Ne	eed - Development of Additive	Manufa	acturing (AM) Techn	olog	y: Ra	apid	Prototyping -			
Rapid Tooling	- Rapid Manufacturing - Additiv	e Manu	facturing. AM Proces	s Ch	ain -	AST	M/ISO 52900			
Classification -	Benefits - AM File formats: ST	TL, AMI	F – Applications - Bus	sines	s Opj	portu	nities in AM.			
Unit 2	VAT POLYMERIZATION A	ND MA	ATERIAL EXTRUS	ON			9			
Photo polymer	ization: Stereolithography Appa	ratus (S	LA)- Materials -Proc	ess -	top	dowi	n and bottom-			
up approach -	Advantages - Limitations - Ap	plicatio	ons. Digital Light Pro	cess	sing (	(DLF	P) - Process -			

Advantages - Applications. Material Extrusion: Fused Deposition Modeling - Process-Materials - Applications and Limitations.

### Unit 3 POWDER BED FUSION AND BINDER JETTING

9

Powder Bed Fusion: Selective Laser Sintering: Process - Powder Fusion Mechanism - Materials and Application. Selective Laser Melting, Electron Beam Melting: Materials - Process - Advantages and Applications. Binder Jetting: Three-Dimensional Printing - Materials - Process - Benefits - Limitations - Applications.

# Unit 4 MATERIAL JETTING AND DIRECTED ENERGY DEPOSITION

Material Jetting: Multijet Modeling- Materials - Process - Benefits - Applications. Directed Energy Deposition: Laser Engineered Net Shaping - Process - Material Delivery - Materials -Benefits - Applications.

# Unit 5 SHEET LAMINATION AND DIRECT WRITE TECHNOLOGY

Sheet Lamination: Laminated Object Manufacturing - Basic Principle- Mechanism: Gluing or Adhesive Bonding - Thermal Bonding - Materials - Application and Limitation. Ink-Based Direct Writing: Nozzle Dispensing Processes, Inkjet Printing Processes, Aerosol DW - Applications of DW.

**Total: 45** 

### **TEXTBOOKS**

- Ian Gibson, David Rosen, Brent Stucker, Mahyar Khorasani, "Additive manufacturing technologies", Springer Cham, 3rd edition, 2021.
- Andreas Gebhardt and Jan-Steffen Hotter "Additive Manufacturing: 3D Printing for Prototyping and Manufacturing", Hanser publications, 2016.

### **REFERENCES**

- Andreas Gebhardt, "Understanding Additive Manufacturing: Rapid Prototyping, Rapid Manufacturing", Hanser Gardner Publication, 1<sup>st</sup> Edition, 2012.
  - Milan Brandt, "Laser Additive Manufacturing: Materials, Design, Technologies, and Applications", Woodhead Publishing, 1<sup>st</sup> Edition, 2016.
  - Amit Bandyopadhyay and Susmita Bose, "Additive Manufacturing", 2<sup>nd</sup> Edition, CRC Press, 2021.
  - 4 Kamrani A.K. and Nasr E.A, "Rapid Prototyping: Theory and practice", Springer, 2006.
  - Liou, L.W. and Liou, F.W., "Rapid Prototyping and Engineering applications: A toolbox for prototype development", CRC Press, 2019.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Recognize the development of AM technology and how AM	K2
	technology propagated into various businesses and developing	
	opportunities.	
CO2	Acquire knowledge on process vat polymerization and material	K2
	extrusion processes and its applications.	
CO3	Elaborate the process and applications of powder bed fusion and	K2
	binder jetting.	

CO4	Evaluate the advantages, limitations, applications of material	K2
	jetting and directed energy deposition processes.	
CO5	Acquire knowledge on sheet lamination and direct write	K2
	technology.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	2	2							2	2	2	2
CO2	2	2	2	2	2							2	2	2	2
CO3	2	2	2	2	2							2	2	2	2
CO4	2	2	2	2	2							2	2	2	2
CO5	2	2	2	2	2							2	2	2	2

	AME703 - ELECTRIC AND HYBRID VEHICLE TECHNOLOGY												
Programme & Branch	BE & MECH	Sem.	Category	L	Т	P	С						
			OE	3	0	0	3						
Preamble	<ul> <li>To introduce the conce</li> <li>To elaborate on the type</li> <li>To expose on different</li> <li>To learn and utilise different</li> <li>To introduce concept of</li> </ul>	pes and uti types of A fferent type	lisation of hybrid AC and DC drives es of energy stora	and el for ele ge syst	ectric ectric tems.	vehi	cles.						
Unit 1	INTRODUCTION	/ 3					9						

Basics of vehicle performance, vehicle power source characterization, transmission characteristics, History of hybrid and electric vehicles, social and environmental importance of hybrid and electric vehicles, impact of modern drivetrains on energy supplies.

### Unit 2 HYBRID ELECTRIC DRIVE TRAINS

9

Basic concept of hybrid traction, introduction to various hybrid drive-train topologies, power flow control in hybrid drive-train topologies, fuel efficiency analysis. Electric Drivetrains: Basic concept of electric traction, introduction to various electric drive-train topologies, power flow control in electric drive-train topologies, fuel efficiency analysis.

### Unit 3 | CONTROL OF AC & DC DRIVES

9

Introduction to electric components used in hybrid and electric vehicles, Configuration, and control - DC Motor drives, Induction Motor drives, Permanent Magnet Motor drive, and Switch Reluctance Motor drives, drive system efficiency.

### Unit 4 ENERGY STORAGE

9

Introduction to Energy Storage Requirements in Hybrid and Electric Vehicles, Energy storage and its analysis - Battery based, Fuel Cell based, and Super Capacitor based, Hybridization of different energy storage devices.

Unit 5	DRIVE SIZING AND ENERGY MANAGEMENT	9
Unit 5	STRATEGIES	

Sizing the drive system: Matching the electric machine and the internal combustion engine (ICE), Sizing the propulsion motor, sizing the power electronics, selection of appropriate energy storage technology, Energy Management Strategies: Energy management strategies used in hybrid and electric vehicles, classification, and comparison of energy management strategies, Implementation issues.

	Total: 45
TEXTB	OOKS
1	Iqbal Husain, "Electric and Hybrid Vehicles: Design Fundamentals", Routledge publications,
	3 <sup>rd</sup> Edition, 2021
2	James Larminie and John Lowry, "Electric Vehicle Technology Explained", Wiley, 2 <sup>nd</sup> Edition,
	2012.
REFER	ENCES
1	Mehrdad Ehsani, Yimi Gao, Sebastian E. Gay, Ali Emadi, "Modern Electric, Hybrid Electric
	and Fuel Cell Vehicles: Fundamentals, Theory and Design", CRC Press, 3 <sup>rd</sup> Edition 2018.
2	Rand D.A.J, Woods, R & Ronald Dell, "Batteries for Electric vehicles", John Wiley & Sons,
	1998.
3	Jack Erjavec, "Hybrid, Electric and Fuel-Cell Vehicles", Delmar Cengage Learning, 2 <sup>nd</sup>
	Edition, 2012.
4	Christian Paar, "Energy Management in Hybrid Electric Vehicles using Co-Simulation", VDM
	Verlag, 2011.
5	Yangsheng Xu, Jingyu Yan, Huihuan Qian and Tin Lun Lam, "Hybrid Electric Vehicle Design
	and Control: Intelligent Omnidirectional Hybrids", McGraw Hill Eductaion, 1st Edition, 2014.

COURS	E OUTCOMES:	Bloom's Taxonomy
At the en	nd of the course, learners will be able to	Level
CO1	Discuss, categorize and configure hybrid drivetrains requirement	K2
	for a vehicle.	
CO2	Design and apply appropriate hybrid and electric drive trains in a	K5
	vehicle.	
CO3	Design and install suitable AC and DC drives for electric vehicles.	K5
	-unf DIIM Dila-	
CO4	Discuss arrive at a suitable energy storage system for a hybrid /	K2
	electric vehicle.	
CO5	Apply energy management strategies to ensure better economy	K3
	and efficiency.	

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1	1		2						1	2	3
CO2	3	2	1	1	1		2						1	2	3
CO3	3	2	1	1	1		2						1	2	3
CO4	3	2	1	1	1		2						1	2	3
CO5	3	2	1	1	1		2						1	2	3

Programme &	DE 6 POP	Sem.	Category	L	T	P	C
Branch	BE & ECE	-	OE	3	0	0	3
Preamble	The course is to make the student used in automotive vehicles.	s to list co	mmon types	of ser	isor ar	ıd actu	ators
Unit – I	INTRODUCTION TO MEAST SENSORS	UREMEN	TS AND			9	
Sensors: Functions-	Classifications- Main technical 1	equiremen	nt and trends	Uni	ts and	d stand	dards
	s- Classification of errors- Erro	-					
	or- Odds and uncertainty- prin						
= =	ematical model of transducers- Zero						
characteristics of firs	t and second order transducers for	standard te	est				
Unit – II	VARIABLE RESISTANCE A	ND INDU	TANCE			9	
	SENSORS						
potentiometer- Strain	tion- Construction details- Changauges- Resistive thermometers- ble reluctance transducers: - EI pic	Thermisto	rs- Piezoresis				
potentionneter- varia	ofe refuctance transducers Er pre-		\/ I \ I				
Unit III		_				0	
Unit – III Variable air gan tv	VARIABLE AND OTHER SPE	CIAL SE	NSORS	cana	citor 1	9 micron	hone
Variable air gap ty Piezoelectric, Magn		ccial se	NSORS tivity type- nsor- digital	trans		nicrop	
Variable air gap ty Piezoelectric, Magn Sensor. Rain sensor, Unit – IV	variable area type and variable of strictive, Hall Effect, semicor climatic condition sensor, solar, lig	ccial section of the permit of	NSORS tivity type- nsor- digital antiglare sen	trans	sducer	nicrop s-Hum	idity
Variable air gap ty Piezoelectric, Magne Sensor, Rain sensor,  Unit – IV  Electromechanical machines- Three-phaelectrical machines. stepper motor etc.  Unit – V  Different types of actemperature control-	variable area type and variable of strictive, Hall Effect, semiconclimatic condition sensor, solar, ligation actuators - Fluid-mechanical actuators - Single-phase alternation working principles, construction a actuators used in automatic temperations.  AUTOMATIC TEMPERATU ACTUATORS	celal SE  cole permit inductor se  ght sensor,  S  cators- El  ting-curren and location  RE CONT	NSORS  tivity type- nsor- digital antiglare sen ectrical mac nt Machines - on of actuator  TROL	transsor.  Chinese Duty	s- Dir y-type . Sole	microp s-Hum  9 rect-cu rating noid, r	urrent gs for relay,
Variable air gap ty Piezoelectric, Magne Sensor, Rain sensor, Unit – IV Electromechanical machines- Three-pha electrical machines. stepper motor etc. Unit – V  Different types of ac	variable area type and variable of strictive, Hall Effect, semiconclimatic condition sensor, solar, ligation actuators - Fluid-mechanical actuators - Single-phase alternation working principles, construction a actuators used in automatic temperations.  AUTOMATIC TEMPERATU ACTUATORS	celal SE  cole permit inductor se  ght sensor,  S  cators- El  ting-curren and location  RE CONT	NSORS  tivity type- nsor- digital antiglare sen ectrical mac nt Machines - on of actuator  TROL	transsor.  Chinese Duty	s- Dir y-type . Sole	microp s-Hum  9 rect-cu rating noid, r  9 splace ent typ	urrent gs for relay,
Variable air gap ty Piezoelectric, Magne Sensor, Rain sensor,  Unit – IV  Electromechanical machines- Three-phaelectrical machines. stepper motor etc.  Unit – V  Different types of actemperature control-	variable area type and variable of strictive, Hall Effect, semiconclimatic condition sensor, solar, ligation actuators - Fluid-mechanical actuators - Single-phase alternation working principles, construction a actuators used in automatic temperations.  AUTOMATIC TEMPERATU ACTUATORS	celal SE  cole permit inductor se  ght sensor,  S  cators- El  ting-curren and location  RE CONT	NSORS  tivity type- nsor- digital antiglare sen ectrical mac nt Machines - on of actuator  TROL	transsor.  Chinese Duty	s- Dir y-type . Sole	microp s-Hum  9 rect-cu rating noid, r  9 splace ent typ	arrent gs for relay,
Variable air gap ty Piezoelectric, Magne Sensor. Rain sensor, Unit – IV Electromechanical machines- Three-phaelectrical machines. stepper motor etc. Unit – V  Different types of actemperature control- conditioning system.  TEXTBOOK:  1. Doebelin's N	variable area type and variable of strictive, Hall Effect, semiconclimatic condition sensor, solar, ligation actuators - Fluid-mechanical actuators - Single-phase alternation working principles, construction a actuators used in automatic temperations.  AUTOMATIC TEMPERATU ACTUATORS	celal SE  ble permit inductor se that sensor,  s  tators- El ting-curren and location  RE CONT  ture control in for Fixed	NSORS  tivity type- nsor- digital antiglare sen ectrical mach nt Machines - on of actuator  FROL  ol- Fixed and l and variable	transsor.  chinese Duty varia varia e disp	sducer  s- Dir y-type . Sole	microps-Hum  9 rect-cu rating noid, r  9 splace ent typ	arrent gs for relay, ment be air
Variable air gap ty Piezoelectric, Magne Sensor. Rain sensor, Unit – IV  Electromechanical machines- Three-phaelectrical machines. stepper motor etc. Unit – V  Different types of accemperature control- conditioning system.  TEXTBOOK:  1. Doebelin's MacGraw Hill	variable area type and variable to strictive, Hall Effect, semiconclimatic condition sensor, solar, ligation actuators - Fluid-mechanical actuators - Single-phase alternation working principles, construction at AUTOMATIC TEMPERATU ACTUATORS  Semi Automatic - Controller design	celal SE  cole permit inductor se  ght sensor,  S  cators- El  ting-curren and location  RE CONT  ture control in for Fixed  (SIE), Er	nsors  tivity type- nsor- digital antiglare sen  ectrical mac nt Machines - on of actuator  FROL  ol- Fixed and d and variable  nest O. Doeb	transsor.  Chinese Duty variate disp	s- Dir y-type . Sole	microp s-Hum  9 rect-cu rating noid, r  9 splace ent typ  Tot:	ment pe air
Variable air gap ty Piezoelectric, Magne Sensor. Rain sensor, Unit – IV  Electromechanical machines- Three-pha electrical machines. stepper motor etc. Unit – V  Different types of act temperature control- conditioning system.  TEXTBOOK:  1. Doebelin's M McGraw Hi 2. Robert Bran	variable area type and variable to strictive, Hall Effect, semiconclimatic condition sensor, solar, ligation actuators - Fluid-mechanical actuators - Single-phase alternation working principles, construction at AUTOMATIC TEMPERATU ACTUATORS  Settuators used in automatic temperations and Automatic - Controller designation of the Automatic - Controller designation in the Automatic - Controller designation i	celal SE  cole permit inductor se  ght sensor,  S  cators- El  ting-curren and location  RE CONT  ture control in for Fixed  (SIE), Er	nsors  tivity type- nsor- digital antiglare sen  ectrical mac nt Machines - on of actuator  FROL  ol- Fixed and and variable  nest O. Doeb	transsor.  Chinese Dutes vizze variate disposelin	s- Dir y-type . Sole lacem	microp s-Hum  9 rect-cu rating noid, r  9 splace ent typ  Tot:	ment be air

### **REFERENCES:**

- 1. James D Halderman, "Automotive Electrical and Electronics", Prentice Hall, USA, 2013
- 2. Tom Denton, "Automotive Electrical and Electronics Systems," Third Edition, 2004, SAE International.
- 3. Patranabis.D, "Sensors and Transducers", 2nd Edition, Prentice Hall India Ltd,2003
- 4. William Ribbens, "Understanding Automotive Electronics -An Engineering Perspective," 7th Edition, Elsevier Butterworth-Heinemann Publishers, 2012

COU	RSE OUTCOMES:	Bloom's Taxonomy
At the	e end of the course, learners will be able to	Level
CO1	List common types of sensor and actuators used in vehicles	K2
CO2	Design measuring equipment's for the measurement of pressure force, temperature and flow	K4
CO3	Generate new ideas in designing the sensors and actuators for automotive application.	К3
CO4	Understand the operation of the sensors, actuators and electronic control.	K2
CO5	Design temperature control actuators for vehicles.	K4

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	2	- 0	-	(i) <u>-</u>	1/	<u> </u>	7-8°	-	-	1	1	
CO2	3	3	3	2	2	0-0		°11		off =	-	-	1	1	
CO3	3	3	2	2	2	-	e/f Di	1 scipli	ne-	-	-	-	2	2	
CO4	3	3	3	3	2	-	-	1	_	-	-	-	3	2	
CO5	3	2	3	3	2		rn	1		_	-	-	2	2	

AEC702 - APPLIED DESIGN THINKING												
Programme & Branch	BE & ECE	Sem.	Category	L	T	P	С					
	DE W EGE	-	OE	3	0	0	3					
Preamble	<ul> <li>This course air techniques of d</li> <li>Illustrate custon</li> <li>Demonstrate or principles of so</li> <li>Describe system</li> </ul>	esign thinki mer-centric developmen dution conce	ng for innovat product innov t of Minim epts & their ev	tive p ation um valuat	roduc using usable tion.	t, develo simple, Protot	pment. use cases. types, Outline					

Unit – l	L	DESIGN THINKING PRINCIPLES	9
_	_	centered Design - Understanding the Innovation process,	=
* *	•	wing & empathy-building techniques, Mitigate validation	risk with FIR [Forge
Innovatio Unit – l		Case studies ENDUSER-CENTRIC INNOVATION	9
		omer-centric innovation - Problem Validation and Cuem significance and problem incidence - Customer Validat	
		es. Activity: Customer development process - Customer into	•
Unit – l		APPLIED DESIGN THINKING TOOLS	9
Concept	of Minimu	m Usable Prototype [MUP] - MUP challenge brief - Desi	igning & Crafting the
-		Designing and Testing Value Proposition; Design a compell	0 0
Process,	tools and te	chniques of Value Proposition Design	
Unit – l	I <b>V</b>	CONCEPT GENERATION	9
	-	n, Concepts Generation and MUP design- Conceptualize	•
_		learn; build the right prototype; Assess capability, usa	•
		generation; evaluation of technology alternatives and the so	
Unit – '		SYSTEM THINKING	9
System T	Thinking, U	nderstanding Systems, Examples and Understandings, Com	plex Systems.
			Total:45
TEXTE	BOOK:		
1.	Steve Bla Wiley.	nnk, (2013), The four steps to epiphany: Successful strategie	es for products that win
2.		ank, (2013), The four steps to epiphany: Successful strategie	es for products that win
	Wiley.		1
3.	Propositi	on Design: How to Create Products and Services Customer	s Want, Wiley
4.	Donella l	H. Meadows, (2015), "Thinking in Systems -A Primer", Sus	stainability Institute
5.		wn, (2012) "Change by Design: How Design Thinking Tra	ansforms Organization
DEEDE		res Innovation", Harper Business.	
	RENCES:	31111 2113130007	
1.	https://ww	w.ideou.com/pages/design-thinking#process	
2.	_	g.forgeforward.in/valuation-risk-versus-validation-risk-in-pas49f253ca86 24	product-
3.		g.forgefor ward.in/product-innovation-rubric-adf5ebdfd356	4. https
4.	https://blo	g.forgefor ward.in/evaluating-product-innovations-e8178e5	58b86e
5.	https://blo	g.forgeforward.in/user-guide-for-product-innovation-rubric	:-857181b253dd
6.	https://blo	g.forgeforward.in/startup-failure-is-like-true-lie-7812cdfe9l	b85
COLLE	TE OUT		
	SE OUTCO	DMES:	Bloom's Taxonomy

CO1	Define & test various hypotheses to mitigate the inherent risks in	K2
	product innovations	
CO2	Design the solution concept based on the proposed value by exploring	K4
	alternate solutions to achieve value-price fit.	
CO3	Develop skills in empathizing, critical thinking, analyzing, storytelling	K4
	& pitching	
CO4	Develop skills in storytelling & pitching	К3
CO5	Apply system thinking in a real-world scenario	K3

POs/ COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	3	2	-	-	J.	1	-	-	-	-	1	1	
CO2	3	3	3	2	2	J. L.		1			-	-	1	1	
CO3	3	3	2	2	2	IIDII	IULL	r Itul	INULU	11 _	-	-	2	2	
CO4	3	3	3	3	2	-	-	1	-	-	-	-	3	2	
CO5	3	2	3	3	2	-	=	1	-	-	-	-	2	2	

Signpost words, Cohesive Devices – Paragraph writing - Technical Writing vs. General Writing.  Unit – II  Project Report – Definition, Structure, Types of Reports, Purpose – Intended Audience – Plagiarism Report Writing in STEM fields – Experiment – Statistical Analysis.  Unit – III  Structure of the Project Report: (Part 1) Framing a Title – Content – Acknowledgement – Fund Details -Abstract – Introduction – Aim of the Study – Background - Writing the research question Need of the Study/Project Significance, Relevance – Determining the feasibility – Theoretical Writing Paragraph writing - Technical Writing vs. General Writing.  9		AEC/03	- PROJECT K	EPORT WRITI	NG			
Preamble  This course aims to provide essentials of project writing, Perceive difference between general writing and technical writing.  Assimilate the fundamental features of report writing, Learn the struct of a technical and project report.  Unit - I  Writing Skills - Essential Grammar and Vocabulary - Passive Voice, Reported Speech, Conce Signpost words, Cohesive Devices - Paragraph writing - Technical Writing vs. General Writing.  Unit - II  Project Report - Definition, Structure, Types of Reports, Purpose - Intended Audience - Plagiarism Report Writing in STEM fields - Experiment - Statistical Analysis.  Unit - III  9  Structure of the Project Report: (Part 1) Framing a Title - Content - Acknowledgement - Fund Details - Abstract - Introduction - Aim of the Study - Background - Writing the research question Need of the Study/Project Significance, Relevance - Determining the feasibility - Theoretic Framework.		RE & ECE	Sem.	Category	L	T	P	С
difference between general writing and technical writing.  Assimilate the fundamental features of report writing, Learn the struct of a technical and project report.  Unit – I  Writing Skills – Essential Grammar and Vocabulary – Passive Voice, Reported Speech, Concounting Skills – Essential Grammar and Vocabulary – Passive Voice, Reported Speech, Concounting Skills – Essential Grammar and Vocabulary – Passive Voice, Reported Speech, Concounting II  Project Report – Definition, Structure, Types of Reports, Purpose – Intended Audience – Plagiarism Report Writing in STEM fields – Experiment – Statistical Analysis.  Unit – III  Structure of the Project Report: (Part 1) Framing a Title – Content – Acknowledgement – Fund Details -Abstract – Introduction – Aim of the Study – Background - Writing the research question Need of the Study/Project Significance, Relevance – Determining the feasibility – Theoretic Framework.	Branch	DE & ECE		OE	3	0	0	3
difference between general writing and technical writing.  Assimilate the fundamental features of report writing, Learn the struct of a technical and project report.  Unit – I  Writing Skills – Essential Grammar and Vocabulary – Passive Voice, Reported Speech, Concounting Skills – Essential Grammar and Vocabulary – Passive Voice, Reported Speech, Concounting Skills – Essential Grammar and Vocabulary – Passive Voice, Reported Speech, Concounting II  Project Report – Definition, Structure, Types of Reports, Purpose – Intended Audience – Plagiarism Report Writing in STEM fields – Experiment – Statistical Analysis.  Unit – III  Structure of the Project Report: (Part 1) Framing a Title – Content – Acknowledgement – Fund Details -Abstract – Introduction – Aim of the Study – Background - Writing the research question Need of the Study/Project Significance, Relevance – Determining the feasibility – Theoretic Framework.				<b>鎌</b> // 💆				
Vriting Skills – Essential Grammar and Vocabulary – Passive Voice, Reported Speech, Concomposition words, Cohesive Devices – Paragraph writing - Technical Writing vs. General Writing.  Unit – II  Project Report – Definition, Structure, Types of Reports, Purpose – Intended Audience – Plagiarism Report Writing in STEM fields – Experiment – Statistical Analysis.  Unit – III  Structure of the Project Report: (Part 1) Framing a Title – Content – Acknowledgement – Fund Details - Abstract – Introduction – Aim of the Study – Background - Writing the research question Vield of the Study/Project Significance, Relevance – Determining the feasibility – Theoretic Framework.	Preamble	difference Assimilar	ce between gene ate the fundamer	ral writing and tental features of re	echnical	l writir	ng.	
Signpost words, Cohesive Devices – Paragraph writing - Technical Writing vs. General Writing.  Unit – II  Project Report – Definition, Structure, Types of Reports, Purpose – Intended Audience – Plagiarism Report Writing in STEM fields – Experiment – Statistical Analysis.  Unit – III  Structure of the Project Report: (Part 1) Framing a Title – Content – Acknowledgement – Fund Details - Abstract – Introduction – Aim of the Study – Background - Writing the research question Need of the Study/Project Significance, Relevance – Determining the feasibility – Theoretic Framework.	Unit – I		inicar and projec	тороги.				9
Project Report – Definition, Structure, Types of Reports, Purpose – Intended Audience – Plagiarism Report Writing in STEM fields – Experiment – Statistical Analysis.  Unit – III  Structure of the Project Report: (Part 1) Framing a Title – Content – Acknowledgement – Fund Details -Abstract – Introduction – Aim of the Study – Background - Writing the research question View of the Study/Project Significance, Relevance – Determining the feasibility – Theoretic Framework.	•						•	
Report Writing in STEM fields – Experiment – Statistical Analysis.  Unit – III  Structure of the Project Report: (Part 1) Framing a Title – Content – Acknowledgement – Fund Details - Abstract – Introduction – Aim of the Study – Background - Writing the research question Veed of the Study/Project Significance, Relevance – Determining the feasibility – Theoretic Framework.		est ve Bevices T	ESTU. 21	g recimiear vi	iting ve	. Gene	101 111	
Unit – III  Structure of the Project Report: (Part 1) Framing a Title – Content – Acknowledgement – Fund Details -Abstract – Introduction – Aim of the Study – Background - Writing the research question Need of the Study/Project Significance, Relevance – Determining the feasibility – Theoretic Framework.					ended A	Audien	ice – Pla	agiarism -
Structure of the Project Report: (Part 1) Framing a Title – Content – Acknowledgement – Fund Details -Abstract – Introduction – Aim of the Study – Background - Writing the research question Need of the Study/Project Significance, Relevance – Determining the feasibility – Theoretic Framework.		EWI Helds – Expe	eriment – Statist	icai Aliaiysis.				9
Details -Abstract – Introduction – Aim of the Study – Background - Writing the research question Need of the Study/Project Significance, Relevance – Determining the feasibility – Theoretic Framework.								
Need of the Study/Project Significance, Relevance – Determining the feasibility – Theoreti Framework.		-				_		
Framework.			-	-	_			_
	Need of the Study/	Project Significa	ınce, Relevance	e – Determining	the fe	easibili	ity – T	heoretica <sup>*</sup>
Unit – IV								
	Unit – IV							9
Structure of the Project Report: (Part 2) – Literature Review, Research Design, Methods of D		•				_		
Collection - Tools and Procedures - Data Analysis - Interpretation - Findings -Limitation	Recommendations –		-	1		υ		

Recommendations – Conclusion – Bibliography.

Unit – V	9

Proof reading a report – Avoiding Typographical Errors – Bibliography in required Format – Font – Spacing – Checking Tables and Illustrations – Presenting a Report Orally – Techniques.

Total:45

### **REFERENCES:**

- 1. Gerson and Gerson Technical Communication: Process and Product, 7th Edition, Prentice Hall(2012)
- 2. Virendra K. Pamecha Guide to Project Reports, Project Appraisals and Project Finance(2012)
- Daniel Riordan Technical Report Writing Today (1998) Darla-Jean Weatherford Technical Writing for Engineering Professionals (2016) Penwell Publishers.

	E OUTCOMES: nd of the course, learners will be able to	Bloom's Taxonomy Level
CO1	Write effective project reports.	K2
CO2	Use statistical tools with confidence	K2
CO3	Explain the purpose and intension of the proposed project coherently and with clarity.	K2
CO4	Create writing texts to suit achieve the intended purpose.	K2
CO5	Master the art of writing winning proposals and projects.	K2

POs/	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	DO0	DO10	PO11	PO12	PSO1	PSO2	PSO3
COs	FOI	FO2	103	FO4	FO3	100	ro/	FU8	FU9	FOIU	POII	FO12	F301	F302	1303
CO1	2	1	1	1	1	3	2	2	3	3	3	3	-	-	
CO2	2	2	2	1	1	1 %	2	1	2	3	2	3	-	-	
CO3	2	2	2	2	2	3	2	Ci2	2	3	2	3	-	-	
CO4	3	3	3	3	3	3	3	3	3	3	3	3	-	-	
CO5	3	2	3	3	3	3	3	3	3	3	3	3	-	-	

		ACS	5701 - SYSTI	EMS EN	GINEERING				
Programme & Branch	&	B.E	&CSE	Sem.	Category	L	T	P	C
21 411011					PE	3	0	0	3
D 11		To introdu	ce system eng	gineering	concepts to design	the n	nanufa	cturin	g systei
Preamble		for optimu	m utilization	of source	for effective funct	ioning	g.		
Unit 1		INTROD	UCTION					9	1
Definitions of Sys	stems E	Engineering	g, Systems Er	ngineering	g Knowledge, Life	cycle	es, Life	e-cycle	phase
logical steps of sy	stems e	engineering	g, Frame work	ks for sys	tems engineering.				
Unit 2		SYSTEM	S ENGINEE	RING PI	ROCESSES			9	)
	Quality	function	deployment,	System	esign, Functional synthesis, Appro			gener	ation (
Unit 3			IS OF ALTE		I IT I I I V			9	
models: present	value a		_	•	Oynamics models works over time, R				
breakdown structu	uic.								
Unit 4 Reliability, Availamodels, Queuing models.	ability, networ	Maintaina k optimiza	tion, Time se	pportabil eries and	ES–II ity models; Stocha Regression models				Marko rge scal
Unit 4 Reliability, Availamodels, Queuingmodels. Unit 5 Decision assessm	ability, networ	Maintaina rk optimiza  DECISIO res, Five ty	bility, and Su tion, Time se N ASSESSM ppes of decisi	ries and ENT on assess	ity models; Stocha Regression models sment efforts, Util	, Eval	luation eory, C	cs and of lar	Marko
Unit 4 Reliability, Availamodels, Queuing models. Unit 5 Decision assessm making and Voting	ability, networ	Maintaina ck optimiza  DECISIO pes, Five ty roaches, Se	bility, and Su tion, Time se N ASSESSM ppes of decisi	ries and ENT on assess	ity models; Stocha Regression models	, Eval	luation eory, C	cs and of lar	Marko
Unit 4 Reliability, Availamodels, Queuingmodels. Unit 5 Decision assessm	ability, networ	Maintaina ck optimiza  DECISIO pes, Five ty roaches, Se	bility, and Su tion, Time se N ASSESSM ppes of decisi	ries and ENT on assess	ity models; Stocha Regression models sment efforts, Util	, Eval	luation eory, C	s and of lar	Marko
Unit 4 Reliability, Availamodels, Queuing models. Unit 5 Decision assessm making and Voting	ability, networ	Maintaina ck optimiza  DECISIO pes, Five ty roaches, Se	bility, and Su tion, Time se N ASSESSM ppes of decisi	ries and ENT on assess	ity models; Stocha Regression models sment efforts, Util	, Eval	luation eory, C	s and of lar	Marko rge scal decisio System
Unit 4 Reliability, Availa models, Queuing models.  Unit 5 Decision assessm making and Voting Engineering Managements	ability, networ	Maintaina rk optimiza DECISIO pes, Five ty roaches, Sont.	bility, and Su tion, Time se NASSESSM vpes of decisi ocial welfare	ENT on assess	ity models; Stocha Regression models sment efforts, Util	ity the	luation leory, (	s and of land	Marko rge scal decisio System
Unit 4 Reliability, Availamodels, Queuing models.  Unit 5 Decision assessmaking and Voting Engineering Mana  TEXTBOOKS  1	ability, network typing approagement agement wiley	Maintaina tk optimizate DECISIO to pes, Five ty troaches, Sont.  w P. Sage, and Sons,	bility, and Su tion, Time se NASSESSM vpes of decisi ocial welfare	ENT on assess	ity models; Stocha Regression models sment efforts, Utili Systems Enginee	ity the	luation leory, (	s and of land	Marko rge scal decisio System
Unit 4 Reliability, Availamodels, Queuing models.  Unit 5 Decision assessm making and Voting Engineering Mana	ability, network typing approagement agement wiley  OMES	Maintaina k optimiza  DECISIO  Des, Five ty  roaches, Sont.  w P. Sage,  and Sons,	bility, and Sution, Time set NASSESSM ppes of decisional welfare James E. Arm Inc,2000.	ENT on assess function	ity models; Stocha Regression models sment efforts, Utili Systems Enginee	, Eval	luation leory, ( method as Engi	s and of land	Marko rge scal decisio System Fotal: 4
Unit 4 Reliability, Availamodels, Queuing models.  Unit 5 Decision assessm making and Votin Engineering Mana  TEXTBOOKS  1 COURSEOUTC	ability, network agement typing appropriate agement wiley  OMES course	Maintaina k optimiza  DECISIO  Des, Five ty  roaches, Sont.  w P. Sage, and Sons,	bility, and Sution, Time set NASSESSM pes of decisiocial welfare James E. Arm Inc,2000.	ENT on assess function astrong Jr.	ity models; Stocha Regression models sment efforts, Utili Systems Enginee	ystem  Blo Lev	luation leory, ( method as Engi	s and of land	Marko rge scal decisio System Fotal: 4
Unit 4 Reliability, Availamodels, Queuing models.  Unit 5 Decision assessm making and Votin Engineering Mana  TEXTBOOKS  1  COURSEOUTCO At the end of the CO1	ability, network agent typing appropriate agement.  Andrew Wiley  OMES  course princip	Maintaina k optimiza  DECISIO bes, Five ty roaches, So  at.  W P. Sage, and Sons,  e, learners tudent must bles to mak	N ASSESSM Types of decision welfare  James E. Arm Inc,2000.  will be able to the decision for	ENT on assess function astrong Jr. to apply sy r optimize	sment efforts, Utility Systems Engineer Stems engineering attion.	ystem  Blo Lev	luation leory, ( method as Engi	Group  In a series  I a series	Marko rge scal decisio System Fotal: 4
Unit 4 Reliability, Availamodels, Queuing models.  Unit 5 Decision assessm making and Votin Engineering Mana  TEXTBOOKS  1  COURSEOUTCO At the end of the	Andrework  Andrework  OMES  course  The S  princip  Hence  discipl	Maintaina k optimiza  DECISIO  Des, Five ty  roaches, Sont.  W P. Sage, and Sons,  te, learners tudent must bles to mak an unde	NASSESSM Types of decision ocial welfare  James E. Arm Inc,2000.  will be able to the decision for retanding of the able to us	to apply sy r optimize the sys se the co	sment efforts, Utility Systems Engineering ation.  tems engineering pre principles and	ystem  Blo Lev	luation leory, ( method as Engi	Group  In a series  I a series	Marko rge scal decisio System Fotal: 4
Unit 4 Reliability, Availamodels, Queuing models.  Unit 5 Decision assessmaking and Voting Engineering Management of the COURSEOUTCO At the end of the CO1  CO2	ability, network agement typing approagement wiley  OMES course The Siprincip Hence discipling proces	Maintaina k optimiza  DECISIO bes, Five ty roaches, So  nt.  W P. Sage, and Sons,  e, learners tudent must bles to mak an unde line and bleses for des	N ASSESSM ppes of decision welfare  James E. Arm Inc,2000.  will be able to the decision for retanding of the able to us igning effecti	to apply syroptimize the system	stems engineering ation.  tems engineering ore principles and n.	ystem  Blo Lev	luation leory, ( method as Engi	Group Inneering K2 K2	Markonge scandecision  decision System  Fotal: 4
Unit 4 Reliability, Availamodels, Queuing models.  Unit 5 Decision assessmaking and Votin Engineering Mana  TEXTBOOKS  1  COURSEOUTCO At the end of the CO1	ability, network approach and reverse agement type agement wiley  OMES course The Signification of the signification of the significant and si	Maintaina rk optimiza rk optimiza re optim	NASSESSM pes of decision ocial welfare  James E. Arm Inc,2000.  will be able to the decision for retanding of the able to us igning effection out method.	to apply syroptimize the system od to in	sment efforts, Utility Systems Engineering ation.  tems engineering pre principles and	ystem  Blo Lev	luation leory, ( method as Engi	Group Is for  Faxon  K2	Marko rge sca decisio System Fotal: 4

CO5	Management the system based on decision results.	K2

POs/ COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	2	1	1	-	-	-	3	2	2	2	2	2	2
CO2	2	3	2	1	1	-	-	=	3	2	3	2	2	2	2
CO3	2	3	2	2	2	-	-	-	-	-	-	2	2	3	2
CO4	2	-	_	2	3	-	-	-	-	-	-	-	2	2	-
CO5	2	2	_	3	3	-	1	2	3	2	1	3	2	3	-

	ACS702- GREE	N CO	MPUTING	G				
	JEFF		ПΠ					
Programme &	B.E & CSE	Sem.	Cate	gory	L	T	P	С
Branch								
			O	E	3	0	0	3
	To learn the funda	mental	s of Green	Computir	ıg.			
Preamble	To analyze the Green	en con	nputing Gr	id Framev	work	ζ.		
Preamble	To understand the	issues	related wit	th Green o	com	plian	ce.	
	To study and deve	lop var	ious case s	tudies.				
Unit 1	FUNDAMENTALS			14				9
Green IT Fundamentals	: Business, IT, and the Envi	ronmer	nt – Green	computing	g: ca	ırbon	foot	print, scoop
on power - Green IT	Strategies: Drivers, Dime	nsions,	and Goa	ls – Envi	ron	ment	ally	Responsible
Business: Policies, Prac	etices, and Metrics.							
Unit 2	GREEN ASSETS AND N	MODE	LING					9
Green Assets: Buildings	s, Data Centers, Networks,	and De	vices – Gr	een Busin	ess	Proc	ess M	Ianagement:
Modeling, Optimization	on, and Collaboration –	Green	Enterpris	se Archit	ectu	re -	- En	vironmental
Intelligence – Green Su	pply Chains - Green Inform	nation	Systems: D	esign and	l De	velo	pmen	t Models
Unit 3	GRID FRAMEWORK	WB	UNIID I	7				9
Virtualization of IT syst	tems – Role of electric utilities	es, Tel	ecommutii	ng, teleco	nfer	encin	ig and	d teleporting
- Materials recycling -	Best ways for Green PC – G	Green I	Data center	– Green	Grio	l frar	newo	ork.
Unit 4	GREEN COMPLIANCE	E						9
Socio-cultural aspects of	of Green IT – Green Enterp	rise Tr	ansformati	on Roadr	nap	– Gı	een (	Compliance:
Protocols, Standards, an	nd Audits – Emergent Carbo	on Issu	es: Techno	logies and	d Fu	ture.	•	
Unit 5	CASE STUDIES							9
Unit 5	01102 01 02 120							
	esponsible Business Strateg	gies (El	RBS) – Cas	se Study S	Scen	arios	for '	-

Total: 45

### **TEXTBOOKS**

and Telecom Sector.

1	Bhuvan Unhelkar, "Green IT Strategies and Applications-Using Environmental
	Intelligence", CRC Press, June 2014
2	Woody Leonhard, Katherine Murray, "Green Home computing for dummies", August
	2012.
REFERENCES	
1	Alin Gales, Michael Schaefer, Mike Ebbers, "Green Data Center: steps for the
	Journey", Shroff/IBM rebook, 2011.
2	John Lamb, "The Greening of IT", Pearson Education, 2009.
3	Jason Harris, "Green Computing and Green IT- Best Practices on regulations &
	industry", Lulu.com, 2008
4	.Carl speshocky, "Empowering Green Initiatives with IT", John Wiley & Sons, 2010.
	5. Wu Chun Feng (editor), "Green computing: Large Scale energy efficiency", CRC
	Press
	IFPHHHK

COURSEOUT At the end of t	TCOMES: the course, learners will be able to	Bloom's Taxonomy Level
CO1	Acquire knowledge to adopt green computing practices to	K2
	minimize negative impacts on the environment	
CO2	Enhance the skill in energy saving practices in their use of	K2
	hardware.	
CO3	Evaluate technology tools that can reduce paper waste and	K2
	carbon footprint by the stakeholders.	
CO4	Understand the ways to minimize equipment disposal	K2
	requirements.	
CO5	Discuss briefly about the use cases in various applications.	K2

POs/ COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1		2				3111		2		2			2	2	
CO2		2		2	2	2	£211	. ZU	17	A			3	2	
CO3				2		2					7		3	2	3
CO4	3	2			2			2	2	2	2		3	2	3
CO5		2	3	2			1					1		2	

Self Discipline

	ACS703 - FINTI	ECH RE	GULATION				
Programme &	B.E & CSE	Sem.	Category	L	T	P	$\mathbf{C}$
Branch							
			OE	3	0	0	3
Preamble	➤ To learn about Laws	and Regi	ılation	•			

i .		To acquire the knowledge of Regulations of Finted	ch firm and their role in
		Market	
Unit 1		INTRODUCTION	9
The Role of the	Regul	ators, Equal Treatment and Competition, Need for a re-	egulatory assessment of
Fintech, India I	Regulat	ions, The Risks to Consider, Regtech and SupTech,	The rise of TechFins,
Regulatory sand	boxes,	compliance and whistle blowing	
Unit 2		INNOVATION AND REGULATION	9
= -		and the law, Regulation and Innovation in Banking and	<del>-</del>
		role in Market-Based Chains, Current Regulatory Approa	
_	et Mana	agement, Insurance, Pensions and Healthcare Schemes, l	Patentability of FinTech
inventions.			
Unit 3		CROWDFUNDING AND DIGITAL ASSETS	9
	_	g, The Jobs Act, Regulation crowd funding, Regulation A	=
=		erings, Digital Assets – Three uses of Digital Assets,	
•		set Forks, Initial Coin Offerings, Regulatory Framework	t for Digital and Crypto
Assets, Central I	Bank D		0
Unit 4		MARKETPLACE LENDING AND MOBILE	9
Online I andine	Dusins	PAYMENTS	Daht Callastian Faval
_		ss Models, Payday Loans, Consumer Protection Laws,	<del>-</del>
= =	-	, Contract Formation and the E-Sign Act, Military Lendi Devices, Payment Cards and the Law, Truth in Lending	=
		und Transfer Act and Regulation E, Fair Credit Repor	-
		ey Transmitter Laws.	tilig Act, Federal Dalik
Unit 5	ite ivion	ANTI-MONEY LAUNDERING AND	9
		CIBERSECURITI	
Reporting requir	ements	under the Bank Secrecy Act Patriot Act Panalties for vi	olating the BSA Virtual
		under the Bank Secrecy Act, Patriot Act, Panalties for vi	•
currencies and	the Ba	under the Bank Secrecy Act, Patriot Act, Panalties for views. Secrecy Act, Cybersecurity Frameworks, Cyber	•
currencies and	the Ba	under the Bank Secrecy Act, Patriot Act, Panalties for vi	•
currencies and	the Ba	under the Bank Secrecy Act, Patriot Act, Panalties for views. Secrecy Act, Cybersecurity Frameworks, Cyber	security Act of 2015,
currencies and Contractual and	the Ba	under the Bank Secrecy Act, Patriot Act, Panalties for views. Secrecy Act, Cybersecurity Frameworks, Cyber	resecurity Act of 2015,  Total: 45
currencies and Contractual and	the Ba Self Re	under the Bank Secrecy Act, Patriot Act, Panalties for views Act, Cybersecurity Frameworks, Cybersegulatory obligations  Madir, FinTech – Law and Regulation, Edward Elgar P	Total: 45 ublishing Limited, 2019
currencies and Contractual and REFERENCES	self Res	under the Bank Secrecy Act, Patriot Act, Panalties for views and Secrecy Act, Cybersecurity Frameworks, Cybersegulatory obligations	Total: 45 ublishing Limited, 2019
currencies and Contractual and REFERENCES	Self Resident Se	under the Bank Secrecy Act, Patriot Act, Panalties for view of the Secrecy Act, Cybersecurity Frameworks, Cybersegulatory obligations  Madir, FinTech – Law and Regulation, Edward Elgar Paio Lemma, Fintech Regulation: Exploring New Chaets Union, Palgrave Macmillan, 2020	Total: 45  ublishing Limited, 2019 Illenges of the Capital
currencies and Contractual and  REFERENCES  1 2	Jelena Valer Marke	under the Bank Secrecy Act, Patriot Act, Panalties for viewed Act, Cybersecurity Frameworks, Cybersegulatory obligations  Madir, FinTech – Law and Regulation, Edward Elgar Paio Lemma, Fintech Regulation: Exploring New Chaets Union, Palgrave Macmillan, 2020  Brummer, Fintech Law in a Nutshell, West Academic Parks	Total: 45  White the control of the
currencies and Contractual and  REFERENCES  1 2	Jelena Valer Marko Chris Berna	under the Bank Secrecy Act, Patriot Act, Panalties for viewed Research Act, Cybersecurity Frameworks, Cybersegulatory obligations  Madir, FinTech – Law and Regulation, Edward Elgar Prio Lemma, Fintech Regulation: Exploring New Charts Union, Palgrave Macmillan, 2020  Brummer, Fintech Law in a Nutshell, West Academic Prior Nicoletti, The Future of Fintech, Integrating Final	Total: 45  ublishing Limited, 2019 Illenges of the Capital ublishing, 2020
currencies and Contractual and  REFERENCES  1 2 3 4	Jelena Valer Marko Chris Berna Finan	under the Bank Secrecy Act, Patriot Act, Panalties for viewed Research Act, Cybersecurity Frameworks, Cybersegulatory obligations  Madir, FinTech – Law and Regulation, Edward Elgar Patrio Lemma, Fintech Regulation: Exploring New Chartes Union, Palgrave Macmillan, 2020  Brummer, Fintech Law in a Nutshell, West Academic Pardo Nicoletti, The Future of Fintech, Integrating Finalcial Services, Springer Nature, 2017	Total: 45  White the Capital and Technology in the Capital and Tec
currencies and Contractual and  REFERENCES  1 2	Jelena Valer Marke Chris Berna Finan Kevin	under the Bank Secrecy Act, Patriot Act, Panalties for viewed Research Act, Cybersecurity Frameworks, Cybersegulatory obligations  Madir, FinTech – Law and Regulation, Edward Elgar Prio Lemma, Fintech Regulation: Exploring New Charts Union, Palgrave Macmillan, 2020  Brummer, Fintech Law in a Nutshell, West Academic Prior Nicoletti, The Future of Fintech, Integrating Final	Total: 45  White the Capital and Technology in the Capital and Tec
currencies and Contractual and  REFERENCES  1 2 3 4	Jelena Valer Marko Chris Berna Finan Kevin	under the Bank Secrecy Act, Patriot Act, Panalties for view and Secrecy Act, Cybersecurity Frameworks, Cybersegulatory obligations  Madir, FinTech – Law and Regulation, Edward Elgar Prio Lemma, Fintech Regulation: Exploring New Chartes Union, Palgrave Macmillan, 2020  Brummer, Fintech Law in a Nutshell, West Academic Prodo Nicoletti, The Future of Fintech, Integrating Finalcial Services, Springer Nature, 2017  C. Taylor, FinTech Law: A Guide to Technology Law in	Total: 45  White the control of the Capital and Technology in the capital and the capit
currencies and Contractual and  REFERENCES  1 2 3 4	Jelena Valer Marko Chris Berna Finan Kevin	under the Bank Secrecy Act, Patriot Act, Panalties for view of the Secrecy Act, Cybersecurity Frameworks, Cybersegulatory obligations  a Madir, FinTech – Law and Regulation, Edward Elgar Prior Lemma, Fintech Regulation: Exploring New Chartes Union, Palgrave Macmillan, 2020  Brummer, Fintech Law in a Nutshell, West Academic Prodo Nicoletti, The Future of Fintech, Integrating Financial Services, Springer Nature, 2017  a C. Taylor, FinTech Law: A Guide to Technology Law in try, BNA Books, 2014	Total: 45  White the control of the Capital and Technology in the capital and the capit
currencies and Contractual and REFERENCES  1 2 3 4 5 COURSEOUT	Jelena Valer Marko Chris Berna Finan Kevin Indus Lee R	under the Bank Secrecy Act, Patriot Act, Panalties for view and Secrecy Act, Cybersecurity Frameworks, Cybersegulatory obligations  a Madir, FinTech – Law and Regulation, Edward Elgar Prior Lemma, Fintech Regulation: Exploring New Charts Union, Palgrave Macmillan, 2020  Brummer, Fintech Law in a Nutshell, West Academic Prodo Nicoletti, The Future of Fintech, Integrating Final Calcal Services, Springer Nature, 2017  a C. Taylor, FinTech Law: A Guide to Technology Law in try, BNA Books, 2014  einers, FinTech Law and Policy, 2018  S:	Total: 45  White the control of the Capital and Technology in the capital and the capit

CO1	Understand the role that financial regulation plays in key	K2
	FinTech developments such as mobile payments,	
	crowdfunding, crypto assets, private digital currencies, and	
	decentralized finance.	
CO2	Know the role that law and technology play in facilitating	K2
	international transactions such as syndicated lending and	
	international bond issues.	
CO3	Be able to critically engage with the major theoretical legal	K2
	debates surrounding international financing, financial	
	markets and financial technology.	
CO4	Be able to deal with policy arguments on international	K2
	financing, financial markets and financial technology law	
CO5	Demonstrate ability to apply critical and contextual	K2
	approaches to the developing legal issues emanating from	
	international financing, regulation of financial markets and	
	financial technology.	

POs/ COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1		2						2		2			2	2	
CO2		2		2	2	2					. *		3	2	
CO3				2		2							3	2	3
CO4	3	2			2			2	2	2	9 2		3	2	3
CO5		2	3	2	10		1		<b>T</b>	3		1		2	

	AIT701 - NETWOR	KING	ESSENTIALS				
Programme & Branch	B.Tech & IT	Sem.	Category	L	Т	P	С
	2Ull Flie		OE	3	0	0	3
Preamble	<ul> <li>Understand the division</li> <li>Be familiar with the networks</li> <li>Be exposed to the reconstruction</li> <li>Learn the flow control</li> <li>Learn the Classify the</li> </ul>	e complete c	oonents required to unctionality at each ongestion control al	bui laye gori	ild d er thms	iffere	
Unit1	FUNDAMENTALS & L	INK L	AYER				9
_	Requirements – Layering a ; Link layer Services – Fran						- Network
Unit 2	MEDIA ACCESS & INT	ΓERNE	TWORKING				9
	Ethernet (802.3) – Wirele working (IP, CIDR, ARP,			etoot	th –	Swit	ching and
Unit 3	ROUTING						9

•	SPF, metrics) – Switch basics – Global Internet (Areas, B	GP, IPv6), Multicast –
Unit 4	cast routing (DVMRP, PIM), Unicast Routing Algorithms  TRANSPORT LAYER	9
Overview of Tran	sport layer – UDP – Reliable byte stream (TCP) – Connectinission – TCP Congestion control – Congestion avoidance (	on management – Flow
Unit 5	APPLICATION LAYER	9
	ations -Electronic Mail (SMTP, POP3, IMAP, MIME) – HTT	
		Total: 45
TEXTBOOKS		
1	Larry L. Peterson, Bruce S. Davie, "Computer Networks: A Edition, Morgan Kaufmann Publishers, 2011.	•
2	Behrouz A. Forouzan, Data Communications and Networ 2013.	king, Fifth Edition TMH,
REFERENCES	JEFFINNN	
1	James F. Kurose, Keith W. Ross, "Computer Networking Featuring the Internet", Fifth Edition, Pearson Education, 2	
2	Nader. F. Mir, "Computer and Communication Network Publishers, 2010	s", Pearson Prentice Hall
3	Ying-Dar Lin, Ren-Hung Hwang, Fred Baker, "Computer N Approach", McGraw Hill Publisher, 2011	Networks: An Open Source
4	Behrouz A. Forouzan, "Data communication and Network McGraw – Hill, 2011.	ing", Fourth Edition, Tata
COURSEOUTCO	MES:	
At the end of the	course, learners will be able to	Bloom's Taxonomy Level
CO1	Identify the components required to build different types of networks	K2
CO2	Choose the required functionality at each layer for given application	К3
CO3	Identify solution for each functionality a t each layer	K1
CO4	Trace the flow of information from one node to another node in the network.	K2
CO5	Design protocols for various functions in the network and understand the working of various application layer protocols	K2

CO/	PO 1	PO2	PO 3	PO4	РО	PO	PO7	PO8	PO9	РО	РО	РО	PSO 1	PSO 2	PSO 3
PO	101	102	103	104	5	6	107	100	10)	10	11	12	1501	1502	1503
CO1	3	3	3	1	3	3	3	2	2	1	-	1			
CO2	3	3	2	-	ı	-	1	-	-	-	-				
CO3	3	3	2	-	1	ı	1	1	-	1	-	1			
CO4	3	3	2	-	ı	ı	1	1	-	1	ı	ı			
CO5	3	3	2	-	1	-	2	2	-	1	-	1			

Programme & Branc	h B.Tech & IT	Sem.	Category	L	T	P	С
			OE	3	0	0	3
	Classify the var	rious soft cor	nnuting frame w	orks			
	➤ Be familiar w		1 0		ks. fu	ızzv	logic and
Preamble	fuzzy systems		6		,	J	
	Learn mathema	tical backgr	ound for optimiz	ed gen	etic 1	progr	amming
	➤ Be exposed to r			_			
Unit 1	INTRODUCTION TO						9
Soft Computing Const	ituents-From Conventiona	al AI To Co	mputational Inte	ligeno	ce- A	rtific	ial Neural
1 0	, Characteristics- Evolution		-	_			
Technologies - Applica	ations. Fuzzy Logic: Introd	duction - Cr	isp Sets- Fuzzy S	Sets - 0	Crisp	Rela	tions And
Fuzzy Relations: Carte	esian Product Of Relation	- Classical	Relation, Fuzzy	Relati	ons,	Tole	rance And
	s. Genetic Algorithm-In			ackgro	ound	- ]	raditional
Optimization And Sear	rch Techniques – Genetic		epts.				
Unit 2	NEURAL NETWOR	KS	LUGY				9
	on - Linear Separability		-			_	
Perceptron Networks	- Adaptive Linear Neuro	n, Multiple	Adaptive Line	ar Ne	uron	, BP	N, RBF -
Associative Memory	Network: Auto- Associa	tive Memor	ry Network, He	tero-A	ssoc	iative	e Memory
	tworks, Iterative Auto As				super	vised	l Learning
Networks: Kohonen Se	olf_Organizing Feature Ma	ma I VIO			-		U
		ips, LVQ – (	CP Networks, Al	RT Ne	twor	k.	
Unit 3  Membership Function	FUZZY LOGIC as: Features, Fuzzification	on, Methods	s Of Membersl	nip V	alue	Ass	9 ignments-
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru	FUZZY LOGIC	on, Methods Arithmetics Of Fuzzine Tables, Fuzy Rules, F	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition	nip V sures: als - Fu	alue Fuzz uzzy rmat	Ass zy Ai Rule ion (	9 ignments- ithmetic - Base And Of Rules-
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru	FUZZY LOGIC  as: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures ng : Truth Values And les, Aggregation Of Fuzz	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Foon Making	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition	nip V sures: als - Fu	alue Fuzz uzzy rmat	Ass zy Ai Rule ion (	9 ignments- ithmetic - Base And Of Rules-
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4	FUZZY LOGIC  as: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures ng : Truth Values And les, Aggregation Of Fuzz pert System- Fuzzy Decisi	on, Methods Arithmetics Of Fuzzine Tables, Fuzy Rules, Foon Making	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning-	nip V sures: als - Fu s, Fo Fuzzy	alue Fuzz uzzy rmat	Ass zy Ai Rule ion (erence	9 ignments- ithmetic - Base And Of Rules- e Systems
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4  Genetic Algorithm- C	FUZZY LOGIC  as: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures ng : Truth Values And les, Aggregation Of Fuzz pert System- Fuzzy Decisi GENETIC ALGORI	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Foon Making THM	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation	nip V sures: als - Fu s, Fo Fuzzy	alue Fuzz uzzy rmat	Ass zy Ai Rule ion (erence	9 ignments- ithmetic - Base And Of Rules- e Systems
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4  Genetic Algorithm- C	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures and les, Aggregation Of Fuzzy pert System- Fuzzy Decision of	on, Methods of Arithmetic of Fuzzine Tables, Fuzy Rules, Fucon Making FHM THM Teme - Fitn Togramming	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In O	nip V sures: als - Fo s, Fo Fuzzy -Cros	alue Fuzz uzzy rmat	Ass zy Ai Rule ion (erence	9 ignments- ithmetic - Base And Of Rules- e Systems
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4  Genetic Algorithm- C Classification Of Gnet	FUZZY LOGIC  as: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures ng : Truth Values And les, Aggregation Of Fuzz pert System- Fuzzy Decisi GENETIC ALGORI  perators - Encoding Sch ic Algorithms- Genetic Pro-	on, Methods of Arithmetic of Fuzzine Tables, Fuzy Rules, Fucon Making FHM THM Teme - Fitn Togramming	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In O	nip V sures: als - Fo s, Fo Fuzzy -Cros	alue Fuzz uzzy rmat	Ass zy Ai Rule ion (erence	9 ignments- ithmetic - Base And Of Rules- e Systems  9 futation –
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4  Genetic Algorithm- C Classification Of Gnet	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures and les, Aggregation Of Fuzzy pert System- Fuzzy Decision GENETIC ALGORITATIONS  HYBRID SOFT CON APPLICATIONS	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Foon Making FHM Theme – Fith Ogramming MPUTING	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In C	nip V sures: als - Fu s, Fo Fuzzy -Cros GA.	alue Fuzz uzzy rmat Infe	Ass zy Ai Rule ion (erence	9 ignments- rithmetic - Base And Of Rules- e Systems  9 futation –
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4  Genetic Algorithm- C Classification Of Gnet Unit 5	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures and les, Aggregation Of Fuzzy pert System- Fuzzy Decision GENETIC ALGORITY operators — Encoding School and School APPLICATIONS  Systems - Genetic Neuro	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Fuzy Rules, Fuzy Rules On Making THM Deme — Fith Degramming MPUTING	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In O TECHNIQUES tems - Genetic I	nip V sures: als - Fu s, Fo Fuzzy  -Cros GA . &	alue Fuzzy rmat    Infe	Ass zy Ai Rule ion (erence	9 ignments- ithmetic - Base And Of Rules- e Systems  9 futation -  9
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4  Genetic Algorithm- C Classification Of Gnet Unit 5  Neuro-Fuzzy Hybrid S Genetic Hybrid Syste	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures and les, Aggregation Of Fuzzy pert System- Fuzzy Decision GENETIC ALGORITORS  Systems - Genetic Propertion of Fuzzy Decision of Fuzz	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Fuzy Rules, Fuzy Rules THM The Fith Ogramming MPUTING Hybrid Syst	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In O FECHNIQUES tems - Genetic I - Applications:	nip V sures: als - Fi s, Fo Fuzzy  -Cros GA. & Guzzy  A Fi	alue Fuzzy rmat Infe	Ass zy Ai Rule ion (erence r - M	9 ignments- rithmetic - Base And Of Rules- e Systems  9 futation –  9 and Fuzzy proach Of
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4  Genetic Algorithm- C Classification Of Gnet Unit 5  Neuro-Fuzzy Hybrid S Genetic Hybrid Syste Multispectral Images	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures and les, Aggregation Of Fuzzy pert System- Fuzzy Decision GENETIC ALGORITY operators — Encoding School and School APPLICATIONS  Systems - Genetic Neuro	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Fuzy Rules, Fuzy Rules THM THM THM THM THM THOUSE APPUTING THYPOTING THY	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In O TECHNIQUES tems - Genetic I - Applications: eling Salesman	nip V sures: als - Fi s, Fo Fuzzy  -Cros GA. & Guzzy  A Fi	alue Fuzzy rmat Infe	Ass zy Ai Rule ion (erence r - M	9 ignments- rithmetic - Base And Of Rules- e Systems  9 futation –  9 and Fuzzy proach Of
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4  Genetic Algorithm- C Classification Of Gnet Unit 5  Neuro-Fuzzy Hybrid S Genetic Hybrid Syste Multispectral Images	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures ing : Truth Values And les, Aggregation Of Fuzzy pert System- Fuzzy Decision GENETIC ALGORITORS - Encoding School Calgorithms - Genetic Propertion APPLICATIONS  Systems - Genetic Neuro in Samplified Fuzzy With SAR, Optimization	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Fuzy Rules, Fuzy Rules THM THM THM THM THM THOUSE APPUTING THYPOTING THY	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In O TECHNIQUES tems - Genetic I - Applications: eling Salesman	nip V sures: als - Fi s, Fo Fuzzy  -Cros GA. & Guzzy  A Fi	alue Fuzzy rmat Infe	Ass zy Ai Rule ion (erence r - M	9 ignments- rithmetic - Base And Of Rules- e Systems  9 futation –  9 and Fuzzy proach Of
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4  Genetic Algorithm- C Classification Of Gnet Unit 5  Neuro-Fuzzy Hybrid S Genetic Hybrid Syste Multispectral Images	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures ing : Truth Values And les, Aggregation Of Fuzzy pert System- Fuzzy Decision GENETIC ALGORITORS - Encoding School Calgorithms - Genetic Propertion APPLICATIONS  Systems - Genetic Neuro in Samplified Fuzzy With SAR, Optimization	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Fuzy Rules, Fuzy Rules THM THM THM THM THM THOUSE APPUTING THYPOTING THY	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In O TECHNIQUES tems - Genetic I - Applications: eling Salesman	nip V sures: als - Fi s, Fo Fuzzy  -Cros GA. & Guzzy  A Fi	alue Fuzzy rmat Infe	Ass zy Ai Rule ion (erence r - M	9 ignments- rithmetic - Base And Of Rules- e Systems  9 futation –  9 and Fuzzy proach Of
Unit 3  Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4  Genetic Algorithm- C Classification Of Gnet Unit 5  Neuro-Fuzzy Hybrid S Genetic Hybrid Syste Multispectral Images	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures ing : Truth Values And les, Aggregation Of Fuzzy pert System- Fuzzy Decision GENETIC ALGORITORS - Encoding School Calgorithms - Genetic Propertion APPLICATIONS  Systems - Genetic Neuro in Samplified Fuzzy With SAR, Optimization	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Fuzy Rules, Fuzy Rules THM THM THM THM THM THOUSE APPUTING THYPOTING THY	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In O TECHNIQUES tems - Genetic I - Applications: eling Salesman	nip V sures: als - Fi s, Fo Fuzzy  -Cros GA. & Guzzy  A Fi	alue Fuzzy rmat Infe	Ass zy Ai Rule ion (erence r - M	9 ignments- ithmetic - Base And Of Rules- e Systems  9 futation –  9 and Fuzzy proach Of g Genetic
Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4 Genetic Algorithm- C Classification Of Gnet Unit 5  Neuro-Fuzzy Hybrid S Genetic Hybrid Syste Multispectral Images Algorithm Approach, S  TEXTBOOKS  1 S.N	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures ing : Truth Values And les, Aggregation Of Fuzzy pert System- Fuzzy Decision GENETIC ALGORITORS - Encoding School Calgorithms - Genetic Propertion APPLICATIONS  Systems - Genetic Neuro in Samplified Fuzzy With SAR, Optimization	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Fuzy Rules, Fuzy Rules THM THM THM THM THY	And Fuzzy Meass -Fuzzy Integrated Proposition uzzy Proposition uzzy Reasoning-ess Evaluation — Advances In Core Techniques  tems - Genetic I — Applications: eling Salesman Controllers.	nip V sures: als - Fi s, Fo Fuzzy  -Cros GA . & Guzzy  A Fu Probl	alue Fuzzy rmat Infe	Ass zy Ai Rule ion (erence r - N rid A App Usin	9 ignments- rithmetic - Base And Of Rules- e Systems  9 futation –  9 and Fuzzy broach Of g Genetic  Total: 4
Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4 Genetic Algorithm- C Classification Of Gnet Unit 5  Neuro-Fuzzy Hybrid S Genetic Hybrid Syste Multispectral Images Algorithm Approach, S  TEXTBOOKS  1 S.N. Ltd.	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures and : Truth Values And les, Aggregation Of Fuzzy pert System- Fuzzy Decision GENETIC ALGORITY (Perators — Encoding School Calgorithms- Genetic Process - Genetic Neurolems - Simplified Fuzzy With SAR, Optimization Soft Computing Based Hydronic Soft Computing Based Hydronic Silvanandam and S.N.Dordonic Silvanandam a	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Fron Making THM The Fith Ogramming MPUTING ARTMAP The Of Trave Brid Fuzzy Control Trave The Of Trave	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In O FECHNIQUES tems - Genetic I - Applications: eling Salesman Controllers.	nip V sures: als - Fi s, Fo Fuzzy  -Cros GA . & Fuzzy  A Fi Probl	alue Fuzzy rmate Infe	Ass zy Ai Rule ion (erence r - M  rid A App Usin	9 ignments- rithmetic - Base And Of Rules- e Systems  9 Intation -  9 and Fuzzy broach Of g Genetic  Total: 4
Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4  Genetic Algorithm- C Classification Of Gnet Unit 5  Neuro-Fuzzy Hybrid S Genetic Hybrid Syste Multispectral Images Algorithm Approach, S  TEXTBOOKS  1 S.N Ltd 2 J.S	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures ing : Truth Values And les, Aggregation Of Fuzzy pert System- Fuzzy Decision GENETIC ALGORITY (Programmer) GENETIC ALGORITY (Programmer) Fuzzy Decision Algorithms - Genetic Programmer - Encoding School Computing Soft Computing Systems - Genetic Neuro Coms - Simplified Fuzzy With SAR, Optimization Soft Computing Based Hympoly (I. Sivanandam and S.N.Doll, 2011	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Fron Making THM The Fith Ogramming MPUTING ARTMAP The Of Trave Brid Fuzzy Control Trave The Of Trave	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In O FECHNIQUES tems - Genetic I - Applications: eling Salesman Controllers.	nip V sures: als - Fi s, Fo Fuzzy  -Cros GA . & Fuzzy  A Fi Probl	alue Fuzzy rmate Infe	Ass zy Ai Rule ion (erence r - M  rid A App Usin	9 ignments- rithmetic - Base And Of Rules- e Systems  9 Intation -  9 and Fuzzy broach Of g Genetic  Total: 4
Membership Function Defuzzification: Lamb Extension Principle - F Approximate Reasoni Decomposition Of Ru Overview Of Fuzzy Ex Unit 4 Genetic Algorithm- C Classification Of Gnet Unit 5  Neuro-Fuzzy Hybrid S Genetic Hybrid Syste Multispectral Images Algorithm Approach, S  TEXTBOOKS  1 S.N. Ltd 2 J.S  REFERENCES	s: Features, Fuzzification da Cuts - Methods - Fuzzy uzzy Measures - Measures ing : Truth Values And les, Aggregation Of Fuzzy pert System- Fuzzy Decision GENETIC ALGORITY (Programmer) GENETIC ALGORITY (Programmer) Fuzzy Decision Algorithms - Genetic Programmer - Encoding School Computing Soft Computing Systems - Genetic Neuro Coms - Simplified Fuzzy With SAR, Optimization Soft Computing Based Hympoly (I. Sivanandam and S.N.Doll, 2011	on, Methods Arithmetic Of Fuzzine Tables, Fuzy Rules, Fuzy Rules, Fuzy Rules THM The Fith Ogramming APUTING ARTMAP The Of Trave Brid Fuzzy Control Trave The Of Trave	s Of Membersl And Fuzzy Mea ss -Fuzzy Integra zzy Proposition uzzy Reasoning- ess Evaluation – Advances In O FECHNIQUES  tems - Genetic I - Applications: eling Salesman Controllers.	nip V sures: als - Fi s, Fo Fuzzy  -Cros GA . & Fuzzy  A Fi Probl	alue Fuzzy rmati Infe	Ass zy Ai Rule ion (erence r - M  rid A App Usin Wile	9 ignments- rithmetic - Base And Of Rules- e Systems  9 Mutation -  9 And Fuzzy proach Of g Genetic  Total: 4 ey India Po

2	George J. Klir, Ute St. Clair, Bo Yuan, "Fuzzy Set Theory: Foundations and
	Applications" Prentice Hall, 1997.
3	David E. Goldberg, "Genetic Algorithm in Search Optimization and Machine
	Learning" Pearson Education India, 2013.
4	James A. Freeman, David M. Skapura, "Neural Networks Algorithms, Applications,
	and Programming Techniques, Pearson Education India, 1991.

## **COURSEOUTCOMES:**

At the end of the	course, learners will be able to	Bloom's Taxonomy Level
CO1	Apply various soft computing concepts for practical applications	K2
CO2	Choose and design suitable neural network for real time problems	K2
CO3	Use fuzzy rules and reasoning to develop decision making and expert system	K2
CO4	Explain the importance of optimization techniques and genetic programming	K2
CO5	Review the various hybrid soft computing techniques and apply in real time problems	K2

## **CO-PO Mapping**

CO/	PO 1	PO2	PO3	PO4	РО	РО	PO7	PO8	PO9	Ю	PO	РО	PSO 1	PSO 2	PSO 3
PO	ro i	ro z	103	FO4	5	6	ro /	108	FO9	10	11	12	F30 1	F3O 2	1303
CO1	3	1	2	2	*	2	-	-	-	-	2	2	1	2	2
CO2	3	2	3	2		2		<u></u>	<u></u>	- /	2	2	3	2	2
CO3	3	2	3	2	3-6	2	-	\-:-\		- /	2	2	2	1	2
CO4	3	3	3	2	3	2	(4) (6) (6)		多		2	2	2	3	1
CO5	2	3	3	3	3	2	-	$\sim$			2	2	1	2	2

Programme & Branch	B.Tech & IT Sem.	Category	L	Т	P	C
<b>Drunen</b>	ESTU. 201	OE	3	0	0	3
Preamble	<ul> <li>To understand the basics of K</li> <li>To discuss methodologies and Development.</li> <li>To design and develop ontologies and Development.</li> <li>To apply reasoning with onto To understand learning and respectively.</li> </ul>	d modeling for Ageries. logies and rules.	_		n and	

Introduction – Abductive reasoning – Probabilistic reasoning: Enumerative Probabilities – Subjective Bayesian view – Belief Functions – Baconian Probability – Fuzzy Probability – Uncertainty methods - Evidence-based reasoning – Intelligent Agent – Mixed-Initiative Reasoning-Knowledge Engineering.

Unit 2		METHODOLOGY AND MODELING		9
Conventional D	esign an	d Development – Development tools and Reusable Ont	ologie	s – Agent Design
_	_	Learning Technology - Problem Solving through Ar	•	•
Inquiry-driven A	Analysis	and Synthesis - Evidence-based Assessment - Belie	evabili	ty Assessment –
Drill-Down Ana	alysis, A	ssumption-based Reasoning, and What-If Scenarios.		
Unit 3		ONTOLOGIES – DESIGN AND DEVELOPMEN	T	9
Concepts and I	Instance	s - Generalization Hierarchies - Object Features -	- Defi	ining Features –
Representation -	– Transi	tivity – Inheritance – Concepts as Feature Values – Or	ntology	Matching.
Design and Dev	elopme	nt Methodologies – Steps in Ontology Development –	Domai	in Understanding
and Concept Eli	icitation	<ul> <li>Modelling-based Ontology Specification.</li> </ul>		
Unit 4		REASONING WITH ONTOLOGIES AND RULE	ES	9
Production Syst	em Arch	itecture – Complex Ontology-based Concepts – Reduce	tion an	d Synthesis rules
and the Inferen	ce Engi	ne – Evidence-based hypothesis analysis – Rule and	Onto	logy Matching –
Partially Learne	d Know	ledge – Reasoning with Partially Learned Knowledge.		
Unit 5		LEARNING AND RULE LEARNING		9
Machine Learni	ng – Co	ncepts – Generalization and Specialization Rules – Typ	pes – F	Formal definition of
		ng, Learning and Problem Solving – Rule learning and		
– Rule Generati	on and A	Analysis – Hypothesis Learning		
				Total: 45
TEXTBOOKS				
1	C1			1 77 1 1
	(theo	rghe Tecuci Dorin Marcu, Mihai Boicu, David	A. S	chiim. Knowledge
1		rghe Tecuci, Dorin Marcu, Mihai Boicu, David neering Building Cognitive Assistants for Evidence-bas		
1	Engir	neering Building Cognitive Assistants for Evidence-base	ed Rea	soning, Cambridge
1	Engir Unive	neering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / U	ed Rea	soning, Cambridge
1	Engir Unive 3 – C	neering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit $1-$ Chapter $1/$ Uhapter $5, 6/$ Unit $4-7$ , Unit $5$	ed Rea	soning, Cambridge
2	Engir Unive 3 – C Chap	neering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9)	ed Rea Jnit 2 -	asoning, Cambridge - Chapter 3,4 / Unit
2	Engir Unive 3 – C Chap Jiawe	neering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit $1-$ Chapter $1/$ Uhapter $5, 6/$ Unit $4-7$ , Unit $5$	ed Rea Jnit 2 -	asoning, Cambridge - Chapter 3,4 / Unit
2  REFERENCES	Engir Unive 3 – C Chap Jiawe Third	neering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9) Ei Han and MichelineKamber, "Data Mining Con	ed Rea Jnit 2 -	asoning, Cambridge - Chapter 3,4 / Unit
	Engir Unive 3 – C Chap Jiawe Third	neering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9) ei Han and MichelineKamber, "Data Mining Con Edition, Elsevier, 2012.	ed Rea Jnit 2 -	soning, Cambridge - Chapter 3,4 / Unit and Techniques",
REFERENCES	Engir Unive 3 – C Chap Jiawe Third	neering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9) Ei Han and MichelineKamber, "Data Mining Con	ed Rea Jnit 2 -	soning, Cambridge - Chapter 3,4 / Unit and Techniques",
REFERENCES	Engir Unive 3 - C Chap Jiawe Third S Rona Morg	heering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5  ter 8, 9)  ii Han and MichelineKamber, "Data Mining Content Edition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Representations."	ed Rea Jnit 2 -	soning, Cambridge - Chapter 3,4 / Unit and Techniques", ion and Reasoning,
REFERENCES 1	Engir Unive 3 - C Chap Jiawe Third S Rona Morg	heering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9)  ei Han and MichelineKamber, "Data Mining Con Edition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.	ed Rea Jnit 2 -	soning, Cambridge - Chapter 3,4 / Unit and Techniques", ion and Reasoning,
REFERENCES 1	Engir Unive 3 – C Chap Jiawe Third S Rona Morg	heering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9)  ei Han and MichelineKamber, "Data Mining Con Edition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.	ed Rea Jnit 2 - ncepts esentat	soning, Cambridge - Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018.
REFERENCES  1  2	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K	heering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9) Ei Han and MichelineKamber, "Data Mining Con Edition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004. Eumar, Knowledge Engineering, I K International Publicational Action of Company (Data communication and Networkitation) and Networkitation (Publication)	ed Rea Jnit 2 - ncepts esentat isher H	soning, Cambridge - Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018.
REFERENCES  1  2	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K	deering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5  ter 8, 9)  ii Han and MichelineKamber, "Data Mining Conedition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.  Tumar, Knowledge Engineering, I K International Publicational Action of Company (Policy Press, 2011).  Touz A. Forouzan, "Data communication and Networking aw – Hill, 2011.  Tiebowitz, Knowledge Management Learning from Knowledge Management L	ed Rea Jnit 2 - ncepts esentat isher H	soning, Cambridge - Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018.
REFERENCES  1  2  3	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K	heering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9) Ei Han and MichelineKamber, "Data Mining Con Edition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004. Eumar, Knowledge Engineering, I K International Publicational Action of Company (Data communication and Networkitation) and Networkitation (Publication)	ed Rea Jnit 2 - ncepts esentat isher H	soning, Cambridge - Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018.
REFERENCES  1  2  3	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K	deering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5  ter 8, 9)  ii Han and MichelineKamber, "Data Mining Conedition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.  Tumar, Knowledge Engineering, I K International Publicational Action of Company (Policy Press, 2011).  Touz A. Forouzan, "Data communication and Networking aw – Hill, 2011.  Tiebowitz, Knowledge Management Learning from Knowledge Management L	ed Rea Jnit 2 - ncepts esentat isher H	soning, Cambridge - Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018.
REFERENCES  1  2  3	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K Behro McGr Jay L Editio	deering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5  ter 8, 9)  ii Han and MichelineKamber, "Data Mining Conedition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.  Tumar, Knowledge Engineering, I K International Publicational Action of Company (Policy Press, 2011).  Touz A. Forouzan, "Data communication and Networking aw – Hill, 2011.  Tiebowitz, Knowledge Management Learning from Knowledge Management L	ed Rea Jnit 2 - ncepts esentat isher H	soning, Cambridge - Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018.
REFERENCES  1  2  3  4  COURSEOUTO	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K Behro McG Jay L Editio	deering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5  ter 8, 9)  ii Han and MichelineKamber, "Data Mining Conedition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.  Tumar, Knowledge Engineering, I K International Publicational Action of Company (Policy Press, 2011).  Touz A. Forouzan, "Data communication and Networking aw – Hill, 2011.  Tiebowitz, Knowledge Management Learning from Knowledge Management L	ed Rea Jnit 2 - ncepts esentat isher H	soning, Cambridge - Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018.
REFERENCES  1  2  3  4  COURSEOUTO	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K Behro McG Jay L Editio	deering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9)  ei Han and MichelineKamber, "Data Mining Con Edition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.  Jumar, Knowledge Engineering, I K International Publicational Action (Polyalar Communication) and Networki (Polya	ed Rea Jnit 2 - ncepts esentat isher H	asoning, Cambridge - Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018. Fourth Edition, Tata ge Engineering, 1st  m's Taxonomy
REFERENCES  1  2  3  4  COURSEOUTO At the end of the	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K Behro McG Jay L Editio	deering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9)  ei Han and MichelineKamber, "Data Mining Con Edition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.  Jumar, Knowledge Engineering, I K International Publicational Action (Polyalar Communication) and Networki (Polya	ed Rea Jnit 2 - ncepts esentat isher H owled	soning, Cambridge Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018. Fourth Edition, Tata ge Engineering, 1st  m's Taxonomy
REFERENCES  1  2  3  4  COURSEOUTO	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K Behro McG Jay L Editio	deering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9)  ei Han and MichelineKamber, "Data Mining Con Edition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.  Jumar, Knowledge Engineering, I K International Publicational Action (Polyalar Communication) and Networki (Polya	ed Rea Jnit 2 - ncepts esentat isher H owled	asoning, Cambridge - Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018. Fourth Edition, Tata ge Engineering, 1st  m's Taxonomy
REFERENCES  1  2  3  4  COURSEOUTO At the end of the country of th	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K Behro McGr Jay L Edition	deering Building Cognitive Assistants for Evidence-basersity Press, First Edition, 2016. (Unit 1 – Chapter 1 / Uhapter 5, 6 / Unit 4 - 7, Unit 5 ter 8, 9)  ei Han and MichelineKamber, "Data Mining Con Edition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.  Jumar, Knowledge Engineering, I K International Publicational Action (Polyalar Communication) and Networki (Polya	ed Rea Jnit 2 - ncepts esentat isher H owled	soning, Cambridge Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018. Courth Edition, Tata ge Engineering, 1st  "'s Taxonomy  K2
REFERENCES  1  2  3  4  COURSEOUTO At the end of the	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K Behro McG Jay L Edition	d J. Brachman, Hector J. Levesque: Knowledge Represant Kaufmann, 2004.  June A. Forouzan, "Data communication and Networking aw – Hill, 2011.  July A. Forouzan, "Data communication and Networking aw – Hill, 2011.  July A. Forouzan, "Data communication and Networking which will be able to erstand the basics of Knowledge Engineering.  June A. Forouzan, "Rowledge Management Learning from Knowledge Engineering.	ed Rea Jnit 2 - ncepts esentat isher H owled	soning, Cambridge Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018. Fourth Edition, Tata ge Engineering, 1st  m's Taxonomy
REFERENCES  1  2  3  4  COURSEOUTO At the end of the CO1  CO2	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K Behro McGr Jay L Edition	neering Building Cognitive Assistants for Evidence-base Press, First Edition, 2016. (Unit 1 – Chapter 1 / Unit 4 - 7, Unit 5 per 8, 9)  Pei Han and Micheline Kamber, "Data Mining Consedition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.  J	ed Rea Jnit 2 - ncepts esentat isher H owled	soning, Cambridge Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018. Courth Edition, Tata ge Engineering, 1st  "'s Taxonomy  K2
REFERENCES  1  2  3  4  COURSEOUTO At the end of the country of th	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K Behro McGr Jay L Edition	d J. Brachman, Hector J. Levesque: Knowledge Represant Kaufmann, 2004.  June A. Forouzan, "Data communication and Networking aw – Hill, 2011.  July A. Forouzan, "Data communication and Networking aw – Hill, 2011.  July A. Forouzan, "Data communication and Networking which will be able to erstand the basics of Knowledge Engineering.  June A. Forouzan, "Rowledge Management Learning from Knowledge Engineering.	ed Rea Jnit 2 - ncepts esentat isher H owled	soning, Cambridge Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018. Courth Edition, Tata ge Engineering, 1st  "'s Taxonomy  K2
REFERENCES  1  2  3  4  COURSEOUTO At the end of the CO1  CO2	Engir Unive 3 – C Chap Jiawe Third S Rona Morg Ela K Behro McGr Jay L Edition COMES: he cours	neering Building Cognitive Assistants for Evidence-base Press, First Edition, 2016. (Unit 1 – Chapter 1 / Unit 4 - 7, Unit 5 per 8, 9)  Pei Han and Micheline Kamber, "Data Mining Consedition, Elsevier, 2012.  Id J. Brachman, Hector J. Levesque: Knowledge Represan Kaufmann, 2004.  J	ed Rea Jnit 2 - ncepts esentat isher H owled	asoning, Cambridge Chapter 3,4 / Unit and Techniques", ion and Reasoning, House, 2018. Fourth Edition, Tata ge Engineering, 1st  M's Taxonomy  K2  K3

CO5	Understand learning and rule learning.	K2
-----	--	----

CO/ PO	PO1	PO2	РО3	PO4	PO 5	PO 6	PO7	PO8	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	3	1	1	1	1	1	-	-	1	2	1	2	1	1	1
CO2	3	2	3	2	2	-	-	-	2	1	2	1	3	3	1
CO3	2	2	3	2	2	-	-	=	3	2	2	2	3	2	3
CO4	2	2	3	1	1	-	-	-	2	2	2	2	2	1	1
CO5	2	2	2	1	1	-	-	-	2	1	1	1	2	1	1

	ACB701 -	BUSIN	ESS R	ESEAR	СН МЕ	THOD	S			
Programme & Branch	B.TECH &		PP	Sem.		egory	L	T	P	C
Prerequisites		INST	TUTE OF	TECHNO	.OGY C	E	3	0	0	3
-	'									
	➤ To make t	he stude	ents of	f tourisi	n unde	rstand t	he prii	nciples	of sc	ientific
Preamble	methodolog	y in busi	ness ei	nquiry, c	levelop a	analytica	al skills	of busin	ness re	esearch
	and to prep	are scient	tific bu	isiness r	eports.					
UNIT I	INTRODUCTION	1								9
Business Researc	h – Definition and	l Signifi	cance	– the r	esearch	process	- Typ	oes of I	Resear	ch –
	ausal Research – T	_				-	• •			
series Research -	- Research question	ns / Prob	olems	<ul><li>Resea</li></ul>	rch obje	ectives -	- Rese	arch hy	pothes	ses –
characteristics – R	esearch in an evolu	tionary p	erspec	tive – th	e role o	f theory	in rese	arch.		
UNIT II	RESEARCH DES	SIGN AN	ID ME	CASURI	EMENT	9				9
Research design -	Definition – type	s of rese	arch de	esign –	explorat	ory and	causal	researc	h des	ign –
	xperimental design			_	-	•				_
internal and exter	nal validity – Varia	bles in R	esearc	h – Mea	suremen	it and so	aling -	- Differe	ent sca	ıles –
Construction of in	strument - Validity	and Reli	iability	of instr	ument.					
UNIT III	DATA COLLECT	ΓΙΟΝ								9
		AniD	FRI	MRII		<del>)</del>			~	
	Primary Vs Secon									
	periments – Const									•
	Sample size – deter	minants	optima	al sampl	e size –	samplir	ng tech	nıques -	- Sam	pling
methods	DATEA DDEDADA	TION	NID A	NI A T X70	TC.					Τ_
UNIT IV	DATA PREPARA	TION A	ND A	NALYS	515					9
Data Preparation -	- editing - Coding	–Data en	try – V	alidity	of data -	- Qualita	ative V	s Quant	itative	data
•	ications of Bivari									•
	ysis, Cluster analys						Multid	limensio	nal sc	aling
<ul> <li>Conjoint Analys</li> </ul>	sis – Application of					•				
UNIT V	REPORT DESIRESEARCH	GN, W	RITI	NG AI	ND ET	THICS	IN ]	BUSINI	ESS	9

Research report – Types – Contents of report – need for executive summary – chapterization – contents of chapter – report writing – the role of audience – readability – comprehension –tone – final proof – report format – title of the report – ethics in research – Ethics in research Subjectivity and Objectivity in research.

#### **Total:45 Periods**

### **TEXTBOOK:**

1. Donald R. Cooper, Pamela S. Schindler and J K Sharma, Business Research methods,11th Edition, Tata Mc Graw Hill, New Delhi, 2012.

## **REFERENCES:**

- Alan Bryman and Emma Bell, Business Research methods, 3rd Edition, Oxford University Press, New Delhi, 2011.
- 2. Uma Sekaran and Roger Bougie, Research methods for Business, 5th Edition, Wiley India, New Delhi, 2012.
- William G Zikmund, Barry J Babin, Jon C.Carr, AtanuAdhikari, Mitch Griffin, Business Research methods, A South Asian Perspective, 8th Edition, Cengage Learning, New Delhi, 2012.
- Panneerselvam. R, Research Methodology, 2nd Edition, PHI Learning, 2014.

	RSE OUTCOMES: successful completion of the course the student will be able to	Bloom's Taxonomy Level
CO1	Understand and appreciate the scientific inquiry	K2
CO2	Undertake a systematic outlook towards business situations for the purpose of objective decision making.	K3
CO3	Ability to conduct a scientific inquiry to solve organizational problems	K3
CO4	Analyze data and find solutions to the problems.	K3
CO5	Prepare research reports	K4

CO/	PO 1	PO2	РО3	PO4	PO	РО	PO 7	PO8	PO9	РО	РО	РО	PSO 1	PSO 2	PSO 3
PO					5	6		19CI	1111	10	11	12			
CO1	2	3	2	2	2	2	2					2	3		
CO2	2	2	2	2	3	2	2					2	3		
CO3	2	3	2	2	2	2	2		IKIII	MILL	7	2	3		
CO4	2	3	2	2	3	8	2			$\mathcal{L}(f)$		2	3		
CO5		3	2	2	2		2	3	011			2	3		

Programme & Branch	B.TECH & CSBS	Sem.	Category	L	T	P	C
Prerequisites			OE	3	0	0	3
Preamble	<ul> <li>To understand the basic</li> <li>To build test cases and</li> <li>To focus on automation</li> <li>To automate the testing</li> <li>To get an insight about</li> </ul>	execute then testing usin using TestN	n g selenium IG	•	C		

Why do we test Software?, Black-Box Testing and White-Box Testing, Software Testing Life Cycle, V-model of Software Testing, Program Correctness and Verification, Reliability versus Safety, Failures, Errors and Faults (Defects), Software Testing Principles, Program Inspections, Stages of Testing: Unit Testing, Integration Testing, System Testing-Performance Testing-The Goal of Test Planning, High Level Expectations, Intergroup Responsibilities, Test Phases, Test Strategy, Resource Requirements, Tester Assignments, Test Schedule, Test Cases, Bug Reporting, Metrics and Statistics.

## UNIT II TEST DESIGN AND EXECUTION

9

Test Objective Identification, Test Design Factors, Requirement identification, Testable Requirements, Modeling a Test Design Process, Modeling Test Results, Boundary Value Testing, Equivalence Class Testing, Path Testing, Data Flow Testing, Test Design Preparedness Metrics, Test Case Design Effectiveness, Model-Driven Test Design, Test Procedures, Test Case Organization and Tracking, Bug Reporting, Bug Life Cycle.

## UNIT III SELENIUM

9

me browsers, Identifying Web Elements using id, name, linkname, class, xpath, tagname- Handling Input box/buttons, list/selection/drop down boxes, radio buttons, check boxes- Extracting links and other Web-Elements-Extracting Data from WebTable-Capturing screenshots-Handling pop-ups, frames, and windows- Exceptions in Selenium - Data driving from csv and excel using Java APIs-Debugging Tests-Page Object Model

## UNIT IV TESTNG

9

Introduction to TestNg-Advantages over Junit-Annotations in TestNg-Understand and Read TestNg Reports-Testng and its configuration-Grouping the testcases, Exclusion of groups, Partial Groups - TestSuite.xml/Suite creation-Types of parameterization-Parameter from TestNg.xml (pass value at Suite and Test level) - Assertion, Verification

## UNIT V CUCUMBER

9

Introduction to Behavior Driven Development(BDD)-BDD framework using Cucumber-Preparing selenium and cucumber environment -creating a feature files using Gherkins and Gherkin syntax-writing features and scenario, Given – When -Then structure -Writing glue code -Cucumber and Java step definitions-writing step definition/ implementing scenarios steps-Cucumber data driven testing

#### **Total:45 Periods**

#### **TEXTBOOK:**

- 1. Yogesh Singh, "Software Testing", Cambridge University Press, 2012
- 2. Unmesh Gundecha, Satya Avasarala, "Selenium WebDriver 3 Practical Guide" Second Edition 2018

#### **REFERENCES:**

- 1. Glenford J. Myers, Corey Sandler, Tom Badgett, The Art of Software Testing, 3rd Edition, 2012, John Wiley & Sons, Inc.
- Ron Patton, Software testing, 2nd Edition, 2006, Sams Publishing
- Paul C. Jorgensen, Software Testing: A Craftsman's Approach, Fourth Edition, 2014, Taylor & Francis Group.
- 4 Carl Cocchiaro, Selenium Framework Design in Data-Driven Testing, 2018, Packt Publishing

#### COURSE OUTCOMES:

Upon successful completion of the course the student will be able to

Bloom's Taxonomy Level

CO1	Understand the basic concepts of software testing and test planning.	K2
	Understand	
CO2	Design effective test cases that can uncover critical defects in the	K3
	application.	
CO3	Automate the software testing using Selenium Apply	К3
CO4	Automate the software testing using TestNG Apply	К3
CO5	Automate the software testing using Cucumber	K3

CO/	PO 1	PO2	PO3	PO4	PO	РО	PO 7	PO8	PO9	PO	PO	PO	PSO 1	PSO 2	PSO 3
PO					5	6				10	11	12			
CO1	1	3	2	2	2									2	
CO2	3	2	2	1	1				00	£				3	
CO3	2	3	3	3	3			U		R			2	3	
CO4	2	1	2	3	2	, d							1	2	
CO5	2	2	1	2	1		STITUT	EOFT	ECHNO	LOGY			2	2	

	ACB/03	- SUCIAL	NEIWO	RK ANALYS	19			
Programme & Branch	B.TECH &	CSBS	Sem.	Category	L	T	P	C
Prerequisites			-	OE	3	0	0	3
Duograhlo	To understa				-	plicatio	ns.	
Preamble	<ul><li>To learn kno</li><li>To understa</li></ul>				•	commu	nities.	
	> To learn vis	ualization of	social net	works.				
UNIT I	INTRODUCTION	S						9

Introduction to Semantic Web: Limitations of current Web - Development of Semantic Web - Emergence of the Social Web - Social Network analysis: Development of Social Network Analysis - Key concepts and measures in network analysis - Electronic sources for network analysis: Electronic discussion networks, Blogs and online communities - Web-based networks - Applications of Social Network Analysis.

UNIT II	MODELLING, AGGREGATING	AND	KNOWLEDGE	9
	REPRESENTATION			

Ontology and their role in the Semantic Web: Ontology-based knowledge Representation - Ontology languages for the Semantic Web: Resource Description Framework - Web Ontology Language - Modelling and aggregating social network data: State-of-the-art in network data representation - Ontological representation of social individuals - Ontological representation of social relationships - Aggregating and reasoning with social network data - Advanced representations

UNIT III	EXTRACTION AND MINING COMMUNITIES IN WEB SOCIAL	9
	NETWORKS	

Extracting evolution of Web Community from a Series of Web Archive - Detecting communities in social networks - Definition of community - Evaluating communities - Methods for community detection and

mining - Applications of community mining algorithms - Tools for detecting communities social network infrastructures and communities - Decentralized online social networks - Multi-Relational characterization of dynamic social network communities.

## UNIT IV PREDICTING HUMAN BEHAVIOUR AND PRIVACY ISSUES

Understanding and predicting human behaviour for social communities - User data management - Inference and Distribution - Enabling new human experiences - Reality mining - Context - Awareness - Privacy in online social networks - Trust in online environment - Trust models based on subjective logic - Trust network analysis - Trust transitivity analysis - Combining trust and reputation - Trust derivation based on trust comparisons - Attack spectrum and countermeasures.

## UNIT V VISUALIZATION AND APPLICATIONS OF SOCIAL NETWORKS 9

Graph theory - Centrality - Clustering - Node-Edge Diagrams - Matrix representation - Visualizing online social networks, Visualizing social networks with matrix-based representations - Matrix and Node-Link Diagrams - Hybrid representations - Applications - Cover networks - Community welfare - Collaboration networks - Co-Citation networks.

**Total:45 Periods** 

#### TEXTBOOK:

- 1. Peter Mika, "Social Networks and the Semantic Web", First Edition, Springer 2007.
- 2. Borko Furht, "Handbook of Social Network Technologies and Applications", 1st Edition, Springer, 2010.

### **REFERENCES:**

- 1. Guandong Xu, Yanchun Zhang and Lin Li, "Web Mining and Social Networking Techniques and applications", First Edition, Springer, 2011.
- 2. Dion Goh and Schubert Foo, "Social information Retrieval Systems: Emerging Technologies and Applications for Searching the Web Effectively", IGI Global Snippet, 2008.
- Max Chevalier, Christine Julien and Chantal Soulé-Dupuy, "Collaborative and Social Information Retrieval and Access: Techniques for Improved user Modelling", IGI Global Snippet, 2009.
- 4. John G. Breslin, Alexander Passant and Stefan Decker, "The Social Semantic Web", Springer, 2009

COU	RSE OUTCOMES:	Bloom's Taxonomy
Upon	successful completion of the course the student will be able to	Level
CO1	Develop semantic web related applications.	K4
CO2	Represent knowledge using ontology.	K3
CO3	Predict human behaviour in social web and related communities.	K4
CO4	Visualize social networks.	K3

CO/ PO	PO 1	PO2	РО3	PO4	PO 5	PO 6	PO7	PO8	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	1	3	2	2	2									2	
CO2	3	2	2	1	1									3	
CO3	2	3	3	3	3								2	3	
CO4	2	1	2	3	2								1	2	
CO5	1	3	2	2	2									2	

AAI701 - DRINKING WATER SUPPLY AND TREATMENT													
Programme &Branch	B.TECH & AIDS	Sem.	Category	L	Т	P	C						
Prerequisites			OE	3	0	0	3						
	To equip the students wit	h the principles	and design of	water	treatme	ent unit	ts and						
Preamble	distribution system.												
		PPINE	П				T						
UNIT I	SOURCES OF WATER	SOURCES OF WATER 1997 1997 1997 1997 1997 1997 1997 199											
Public water sur	pply system – Planning, Ol	bjectives, Desig	n period, Popu	lation	forecast	ting; W	'ater						
demand - Source	es of water and their character	ristics, Surface a	and Groundwate	r – Im	pounding	g Reser	voir						
<ul> <li>Development</li> </ul>	and selection of source – So	ource Water qua	ality – Characte	erizatio	n – Sig	nificano	ce –						
Drinking Water of	quality standards.												
UNIT II	CONVEYANCE FROM	THE SOURCE					9						
Water supply – i	ntake structures – Functions;	Pipes and condu	uits for water –	Pipe m	aterials	– Hydra	aulics						
of flow in pipes	– Transmission main design -	– Laying, jointin	g and testing of	pipes	– appurt	tenance	s –						
Types and capac	ity of pumps – Selection of p	umps and pipe r	naterials.										
J1 T													
TINITE III	WATER TREATMENT						0						

## UNIT III WATER TREATMENT

9

Objectives – Unit operations and processes – Principles, functions, and design of water treatment plant units, aerators of flash mixers, Coagulation and flocculation – sand filters - Disinfection – Construction, Operation and Maintenance aspects

## UNIT IV ADVANCED WATER TREATMENT

9

Water softening – Desalination- R.O. Plant – demineralization – Adsorption - Ion exchange– Membrane Systems - Iron and Manganese removal - Defluoridation - Construction and Operation and Maintenance aspects.

## UNIT V WATER DISTRIBUTION AND SUPPLY

9

Requirements of water distribution – Components – Selection of pipe material – Service reservoirs – Functions – Network design – Economics - Computer applications – Appurtenances – Leak detection - Principles of design of water supply in buildings – House service connection – Fixtures and fittings, systems of plumbing and types of plumbing.

**Total:45Periods** 

#### **TEXTBOOK:**

- 1. Garg. S.K., "Water Supply Engineering", Khanna Publishers, Delhi, September 2008.
- Punmia B.C, Arun K.Jain, Ashok K.Jain, "Water supply Engineering" Lakshmi publication private limited, New Delhi, 2016

J.	Rangwala "Water Supply and Sanitary Engineering", February 2022 4. Birdie.G.S., "Water Supply and Sanitary Engineering", Dhanpat Rai and sons, 2018
DEFEI	DENCES.

- Fair. G.M., Geyer.J.C., "Water Supply and Wastewater Disposal", John Wiley and Sons, 1954.
- Babbit.H.E, and Donald.J.J, "Water Supply Engineering", McGraw Hill book Co, 1984. 2.
- Steel. E.W.et al., "Water Supply Engineering", Mc Graw Hill International book Co, 1984.
- Duggal. K.N., "Elements of public Health Engineering", S.Chand and Company Ltd, New Delhi, 1998.

COURSEOUTCOMES: Upon successful completion of the course the stude	ent will be able to  Taxonomy  Level
An understanding of water quality criteria and relation to public health	standards, and their  K2
CO2 The ability to design the water conveyance sy	stem 247 K3
CO3 The knowledge in various unit operations and treatment	processes in water  K3
CO4 An ability to understand the various systems f treatment	or advanced water K3
CO5 An insight into the structure of drinking water	distribution system K4

CO/ PO	PO 1	PO2	РО3	PO4	PO 5	PO 6	PO7	PO8	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	2	3	2	2	2	2	2		Dir	D/1.		2	3		
CO2	2	2	2	2	3	2	2	IVII	MA	UU;		2	3		
CO3	2	3	2	2	2	2	2	- D (			1	2	3		
CO4	2	3	2	2	3	9	2	10. 4	UII	4	1	2	3		
CO5		3	2	2	2		2	3			7	2	3		

AAI702 - GEOGRAPHICAL INFORMATION SYSTEM												
Programme &Branch	B.TECH& AIDS	Sem.	Category	L	T	P	C					
Prerequisites			OE	3	0	0	3					
Preamble  To impart the knowledge on basic components, data preparation and implementation of Geographical Information System. To build test cases and execute them												
UNIT I	FUNDAMENTALS OF GIS						9					

Introduction to GIS - Basic spatial concepts - Coordinate Systems - GIS and Information Systems - Definitions - History of GIS - Components of a GIS - Hardware, Software, Data, People, Methods - Proprietary and open source Software - Types of data - Spatial, Attribute data- types of attributes - scales/ levels of measurements.

## UNIT II SPATIAL DATA MODELS

9

Database Structures – Relational, Object Oriented – Entities – ER diagram - data models - conceptual, logical and physical models - spatial data models – Raster Data Structures – Raster Data Compression - Vector Data Structures - Raster vs Vector Models- TIN and GRID data models.

# UNIT III DATA INPUT AND TOPOLOGY

9

Scanner - Raster Data Input – Raster Data File Formats – Georeferencing – Vector Data Input – Digitizer – Datum Projection and reprojection -Coordinate Transformation – Topology - Adjacency, connectivity and containment – Topological Consistency – Non topological file formats - Attribute Data linking – Linking External Databases – GPS Data Integration

## UNIT IV DATA QUALITY AND STANDARDS

9

Data quality - Basic aspects - completeness, logical consistency, positional accuracy, temporal accuracy, thematic accuracy and lineage — Metadata — GIS Standards —Interoperability - OGC - Spatial Data Infrastructur

## UNIT V DATA MANAGEMENT AND OUTPUT

9

Import/Export – Data Management functions- Raster to Vector and Vector to Raster Conversion - Data Output - Map Compilation – Chart/Graphs – Multimedia – Enterprise Vs. Desktop GISdistributed GIS.

**Total:45Periods** 

## TEXTBOOK:

- 1. Kang Tsung Chang, Introduction to Geographic Information Systems, McGraw Hill Publishing, 2nd Edition, 2011.
- Ian Heywood, Sarah Cornelius, Steve Carver, Srinivasa Raju, "An Introduction Geographical Information Systems, Pearson Education, 2nd Edition, 2007.

#### **REFERENCES:**

Lo. C. P., Albert K.W. Yeung, Concepts and Techniques of Geographic Information Systems, Prentice-Hall India Publishers, 2006

	RSEOUTCOMES:  mpletion of the course, the student is expected to	Bloom's Taxonomy Level
CO1	Have basic idea about the fundamentals of GIS.	K2
CO2	Understand the types of data models	К3
CO3	Get knowledge about data input and topology	К3
CO4	Gain knowledge on data quality and standards	K3
CO5	Understand data management functions and data output	К3

CO/ PO	PO1	PO2	РО3	PO4	PO 5	PO 6	PO 7	PO8	PO 9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	1	3	2	2	2									2	
CO2	3	2	2	1	1									3	
CO3	2	3	3	3	3								2	3	
CO4	2	1	2	3	2								1	2	
CO5	2	2	1	2	1								2	2	

	<b>AAI703 - IT IN A</b> (	GRICULTUI	RAL SYSTEM						
Programme &Branch	B.TECH& AIDS	Sem.	Category	L	Т	P	C		
Prerequisites			OE	3	0	0	3		
Preamble	<ul> <li>To introduce the stud computers play a majo</li> <li>To also expose the environmental control prediction models</li> </ul>	or role. students to	T application	ons in	precisi	on far	ming,		
UNIT I	PRECISION FARMING						9		
	ture and agricultural managemetware, Yield mapping systems,			Remote	sensing,	GPS,	GIS		
UNIT II	ENVIRONMENT CONTRO	OL SYSTEM	IS				9		
	rstems, management of crop groundine measurement of plant grounding horticulture.								
UNIT III	AGRICULTURAL SYSTEMS MANAGEMENT								
Agricultural syst	ems - managerial overview, R	eliability of	agricultural sys	stems,	Simulation	on of	crop		
~	operations, Optimizing the use		Linear program	nming,	Project s	chedul	ing,		
Artificial intellige	ence and decision support syste	ms.							

#### WEATHER PREDICTION MODELS UNIT IV

Importance of climate variability and seasonal forecasting, Understanding and predicting world's climate system, Global climatic models and their potential for seasonal climate forecasting, General systems approach to applying seasonal climate forecasts.

#### E-GOVERNANCE IN AGRICULTURAL SYSTEMS UNIT V

Expert systems, decision support systems, Agricultural and biological databases, e-commerce, business systems & applications, Technology enhanced learning systems and solutions, eLearning, Rural development and information society

#### **Total:45 Periods**

## **TEXTBOOK:**

- National Research Council, "Precision Agriculture in the 21st Century", National Academies Press, Canada, 1997.
- H. Krug, Liebig, H.P. "International Symposium on Models for Plant Growth, Environmental Control and Farm Management in Protected Cultivation", 1989.

### **REFERENCES:**

- Peart, R.M., and Shoup, W. D., "Agricultural Systems Management", Marcel Dekker, New York, 2004.
- 2. Hammer, G.L., Nicholls, N., and Mitchell, C., "Applications of Seasonal Climate", Springer, Germany, 2000.

	RSEOUTCOMES: successful completion of the course the student will be able to	Bloom's Taxonomy Level
CO1	The students shall be able to understand the applications of IT in remote sensing applications such as Drones etc	K1
CO2	The students will be able to get a clear understanding of how a greenhouse can be automated and its advantages.	K2
CO3	The students will be able to apply IT principles and concepts for management of field operations	K4
CO4	The students will get an understanding about weather models, their inputs and applications.	K1
CO5	The students will get an understanding of how IT can be used for e-governance in agriculture	K4

CO/ PO	PO1	PO2	РО3	PO4	PO 5	PO 6	PO7	PO8	PO 9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	1	3	2	2	2								1	1	1
CO2	3	2	2	1	1						/ A	7	1	1	1
CO3	2	3	3	3	3						75		2	2	2
CO4	2	1	2	3	2	P	(A)		人數		ેવ્		2	2	2
CO5	2	2	1	2	1	0/2				0	9		3	3	3



AMB701-CORPORATE GOVERNANCE											
	1.50				-	_					
Programme & Branch	MBA	Sem.	Category	L	T	P	C				
			OEC	3	0	0	3				
Preamble  To understand the concepts, need for and importance of Governance.  To understand the relationship between Business, government to provide the learners with different organization structures.  To provide the learners to integrate with business and society.  To formulate and execute the plans at various levels of managements.											
Unit 1	CORPORATE GOVER	RNANC	E				9				

Corporate governance: The concept, need and importance of corporate governance, The role and purpose of the corporation, separation of ownership and control, benefits of good corporate governance, OECD (Organization for economic co-operation and development) on corporate governance, Theoretical basis for corporate governance, environmental Concerns and Corporations, environmental preservation-role of stakeholders, sustainable development, industrial pollution, role of corporate in environmental management, waste management, pollution control and environmental audit.

### Unit 2 BUSINESS, GOVERNMENT AND SOCIETY

9

An introduction to Business, Government, and Society: The Connect between Business, Government, and Society, Importance of BGS relationship in management, models of BGS relationships-Market capitalism model, dominance model, countervailing forcer's model and stakeholder model.

#### Unit 3 BUSINESS STRUCTURES

9

**Business structures:** Meaning and nature of business structures, types, nature, advantages, limitations and applicability of - single ownership, partnerships, private limited companies, public limited companies, co-operative societies.

## Unit 4 BUSINESS ETHICS AND CSR

9

**Business Ethics and Corporate Social Responsibility:** Meaning of business ethics, need and purpose, importance, approaches to business ethics, roots of unethical behavior, ethical decision making some unethical issues, benefits from managing ethics at workplace. Nature of CSR, arguments for and against CSR, models of CSR, best practices of CSR-Indian examples.

### Unit 5 BOARD OF DIRECTORS

9

Role of Board of Directors in Corporate Governance, Corporate board of Management, structure and composition of the board, Types of board and directors, Size of the board, Powers of the board of directors, responsibilities, functions of the board, code of conduct for board members, training for the board of directors, effectiveness of the board members, effectiveness and powers of the board.

	Total: 45
TEEDENIGE DOOK	

REFERENCE I	BOOK
1	Corporate Governance: Principles, policies and Practices by Fernando A.c. Pub:
	Pearson, 2014.
2	Business and Government by Francis Cherunilam, Pub: Himalayan Publishing House.
3	Corporate Governance, Ethics & Social Responsibility by Balachandran C.H, Pub:
	PHI Pvt Ltd, 2015.

4	Business Ethics and Corporate Governance: Ghosh B.N., TM	ИН, 2015		
COURSE OUT	COMES:	Bloom's Taxonomy		
At	the end of the course, learners will be able to	Level		
CO1	Understand to connect between the corporate, ethics and	K1		
	society.			
CO2	Decide about the appropriateness of various business structures.	K2		
CO3	Understand the need for and importance of corporate	К3		
	governance with reference to Environment protection			
CO4	Make the students to understand the essence of business and	K4		
	how business could be mutually beneficial to the			
	businessman and the society.			
CO5	Decide on the role and functions of Board of Directors in	K5		
	an Organization.			
	INCTITUTE OF TECHNOLOGY			

CO/ PO	PO 1	PO2	РО3	PO4	PO 5	PO 6	PO 7	PO8	PO9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	3	2	1		1			1	1	2	1	1	2	2	2
CO2	3	2	1	1	1	1		1	2	2	1	1	1	2	2
CO3	3	2	1	1	1	1	2	1	2	2	1	1	2	1	2
CO4	3	2	1	1	1		2	1	2	2	1	1	2	2	2
CO5	3	2	1	1	10	1	2	1	2	2	1	1	2	1	1



	AMB702- DIG	ITAL MA	RKETING							
Programme & Branch	MBA	Sem.	Category	L	T	P	С			
	•		OE	3	0	0	3			
Preamble	<ul> <li>To understand the conce</li> <li>To understand the Online</li> <li>To analyse the Social me</li> <li>To evaluate the concepts</li> <li>To formulate mobile ma</li> </ul>	e Advertisedia and en	ing and SEO. mail Marketing. marketing.	egie	s.					
Unit 1	OVERVIEW OF DIGITA	L MARK	ETING				9			
Digital marketing	overview and meaning- bene	efits – pla	atform & strategies	s- co	ompa	ring	digital with			
traditional marketi	ng- latest digital marketing tro	ends- case	studies of digital 1	narl	cetin	g trei	nds. Content			
Marketing, Handli	ng Traffic.									
Unit 2	ONLINE ADVERTISING AND SEO									

Internet and Search Engine Basics, online Advertising, Importance of online Advertising, Types of online Marketing and advertising Methods. Importance of Search Engines, How the search engine works, Understanding the SERP, Using Search Operators, Search Engine Algorithms.

## Unit 3 SOCIAL MEDIA AND EMAIL MARKETING

9

What is Social Media, SMM Vs. SMO, Benefits of using SMM, Social Media Strategy, and Impact of Social Media on SEO. Marketing strategy, Benefits, Promotional tools for- Facebook, YouTube, Twitter, Google, Linkedn. Email Marketing- Email Marketing concept, Importance, Popular Email Marketing Softwares, Email Marketing Goals and strategies, Types of Email marketing campaigns, Creating an Email Campaign, What is Newsletter, Design a Newsletter. Micro Blogging.

#### Unit 4 E COMMERCE

9

Ecommerce Business Planning, eCommerce Website, Product Placements, Product Grouping, Promoting eCommerce Website, Remarketing Products: Re-Marketing Flow, Email, Facebook Re-Marketing. Understanding Coupon System, Appointing Affiliates for Products, Cross/Up/Down Selling, Introduction to payment gateway- Application and Documentation.

### Unit 5 MOBILE MARKETING AND REMARKETING

9

Overview of the B2B and B2C Mobile Marketing, Mobile Sites, Apps (Applications) and Widgets and their relevant to marketing, opportunities and pitfalls of Mobile Marketing, user interfaces and architectures. Trends in Mobile social media, Mobile Commerce, Mobile Payments and Billing, integration of mobile marketing into marketing plan.

Total: 45

REFERE	NCE BOOK
1	Digital Marketing: Strategy, Implementation & Practice, Dave Chaffey & Fiona Ellis-
	Chadwick, 2019
2	Convert!: Designing Websites For Traffic and Conversions, Ben Hunt, 2020
3	The Social Media Bible: Tactics, Tools, & Strategies for Business Success, Lon Safko, 2018
4	Digital Marketing: Strategies for Online Success , Godfrey Parkin, 2015

5	Understanding Digital Marketing: Marketing Strategies for Engagin	g the Digital Generation,
	Damian Ryan, 2018	
COURSE	COUTCOMES:	Bloom's Taxonomy
	At the end of the course, learners will be able to	Level
CO1	Understand how and why to use digital marketing for multiple goals within a larger marketing and/or media strategy.	K1
CO2	Understand the major digital marketing channels - online advertising: Digital display, video, mobile, search engine, email and social media.	K2
CO3	Learn to develop, evaluate, and execute a comprehensive digital marketing strategy and plan.	K3
CO4	Explore the concepts of Remarketing strategies	K4
CO5	Develop various payment and billing gateways in digital marketing.	K5
CO-1	PO Mapping	

CO/ PO	PO 1	PO2	РО3	PO4	PO 5	PO 6	PO 7	PO8	PO 9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	3	2	1		1			1	2	2	1	1	2	2	1
CO2	3	2	1	1	1	1	1	1	2	2	1	1	1	2	2
CO3	3	2	1	1	714	1	2	1	2	2	1	1	2	2	2
CO4	3	2	1	1	\10		1	1	1	2	1	1	2	2	2
CO5	3	2	1	1	10	1	2	1:::=	2	2	1	1	2	2	1



	AMB703- R	URAL MAF	RKETING									
Programme &	& MBA	Sem.	Sem. Category			P	С					
			OE	3	0	0	3					
	> To understand the concepts of Rural Marketing											
	To understand the types of Agricultural products for marketing.											
Preamble												
	To evaluate the Rural Marketing Regulations.											
	➤ To formulate the strate											
Unit 1												
Concept- Natu	re- Scope- Significance of Ru	ıral Marketin	g- Factors contr	ibutir	g to	Grov	vth of rura					
	ponents and classification of F											
marketing.		<u> </u>	<u> </u>									
Unit 2 AGRICULTURAL MARKETING 9												
Concept-Nature	e and Types of Agriculture	produce- co	ncept and types	of A	Agric	ultura	al Markets					
	nnels -Methods of Sales - Marko											
Unit 3 Rural Consume	Unit 3 ISSUES IN RURAL MARKETING 9											
growing FMCO	oncept and classification of consumer dural	bles- The role	e of Advertising.									
Unit 4	RURAL MARKETING						9					
control -Inspec 1955 –Consum	ket- APMC Act 1963- Model tion of AGMARK - Indian Stander Protection Act 1986. The Na	ders and Grad ational Cound	de Specifications- cil for State Mark	Food	l Prod	ducts	order (FPC					
	orporation (STC), Public Distri			CINIC			9					
Unit 5	in Agriculture Costs and Prices					rotive	-					
	<u> </u>		Food Exports		-		Authorit					
(APEDA)	(Ar LD), Agriculture and	Trocessed	Toou Exports	DC	ciop	mem	Authorit					
(TH EDIT)	- Shiri		<del>UUR /</del>				Total: 4					
REFERENCE	BOOK	STD. 2011										
	Badi R.V. Badi N.V.Rural Marketing Himalaya Publishing House – 2010											
2 Ru	Rural Marketing- Gopalaswamy Vikas Publishing House, 2020.											
	Kashyp Pradeep, Rant Siddhartha The Rural Marketing, Biztantra, 2015.											
4 Mis	Mishra and Puri Development Issues of Indian Economy Himalaya Publishing House, 2018											
	rcomes.				Bloo	m's T	axonomy					
		•111 1	.1. 4.			-	. 1					
	t the end of the course, learne		ole to			Le <sup>x</sup>						
CO1 Un		Marketing					1					

CO3	Analyse the nature of marketing rural products	К3
CO4	Identify the problems and issues in Rural Marketing	K4
CO5	Formulate the marketing strategies to satisfy the rural consumers.	K5

CO/	CO/ PO PO1 PO2 PO3	DO 2	PO4	PO 5	РО	PO7	PO8	PO9	РО	РО	РО	PSO 1	PSO 2	PSO 3	
PO		J2   PU3	FO4		6				10	11	12				
CO1	3	2	1		1		1	1	2	2	1	1	1	2	2
CO2	3	2	1	1	1	1		1	1	2	1	1	2	2	1
CO3	3	2	1	1	1	1	2	1	2	1	1	1	2	2	2
CO4	3	2	1	1	1		2	1	2	2	1	1	2	2	1
CO5	3	2	1	1		1	2	1	2	2	2	1	1	2	2

